

CS:4350 Logic in Computer Science

Transition Systems

Cesare Tinelli

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Credits

These slides are largely based on slides originally developed by **Andrei Voronkov** at the University of Manchester. Adapted by permission.

Outline

Transition Systems

- State-Changing Systems

- Transition Systems

- Labelled Transition Systems

- Symbolic Representation of Transition Systems

State-changing systems

Our main interest from now on is modeling *state-changing systems*

We assume a discrete notion of time, with each time corresponding to a *step* taken by the system

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At each step, the system is in a particular state	
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Reasoning about state-changing systems

1. Build a **formal model** of this state-changing system describing
 - the behavior of the system, or
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Example, Vending machine

A state-changing system: **vending machine** dispensing drinks

- The machine has several components, including:
 - **storage space** for storing and preparing drinks,
 - a **dispenser** for the purchased drink, and
 - a **coin slot** to pay for the drink
- When the machine is operating, it goes through several **states**, depending on the behavior of the current **customer**
- Each action by the customer or the machine itself may change its state
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State transition: action that may change the machine's state

Modeling state-changing systems

To build a **formal model** of a particular state-changing system, we specify its behavior in terms of

1. its **state variables**
2. the possible **values** for the state variables
3. the state **transitions** and how they **change** the values of the state variables

A state can be identified with

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Transition systems

A *transition system* is a tuple $\mathbb{S} = (S, In, T, \mathcal{X}, dom, L)$, where

1. S is a finite non-empty set, the set of *states* of \mathbb{S}
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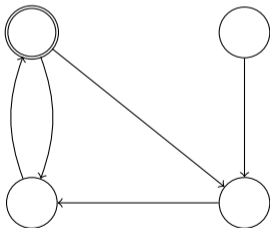
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there is an edge from state s to state s' iff $(s, s') \in T$

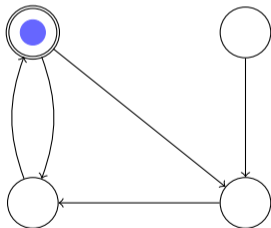


We denote the initial states with double circles

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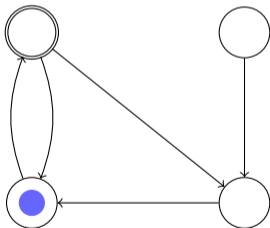


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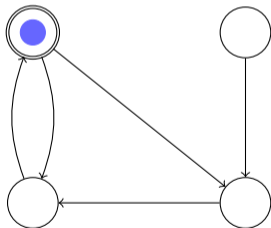


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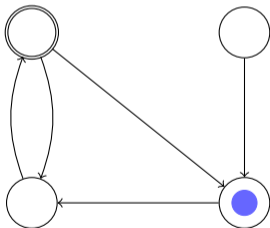


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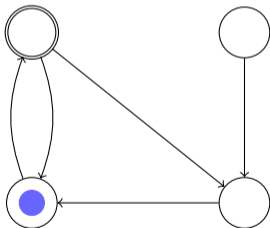


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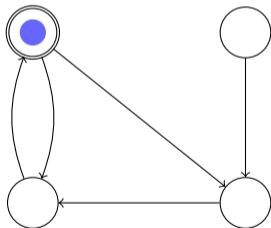


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4. \mathcal{X} is a finite set of *state variables*
5. dom is a mapping from \mathcal{X} such that
for every $x \in \mathcal{X}$, $dom(x)$ is a non-empty set of values, the *domain of x*
6. L is a function mapping states of S to interpretations, the *labelling function* of \mathbb{S} (more on this later)

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4. \mathcal{X} is a set of labels
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We will only study *finite-state* transition systems

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Systems in PLFD

$$\mathbb{S} = (S, In, T, \mathcal{X}, dom, L)$$

Note this part of the definition transition system:

4. \mathcal{X} is a finite set of *state variables*
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\mathcal{X} and dom define an **instance of PLFD!**

Labeling function

$$\mathbb{S} = (S, In, T, \mathcal{X}, dom, L)$$

Let \mathbb{I} be the set of all interpretations for the instance of PLFD given by \mathcal{X} and dom

1. for every $x \in \mathcal{X}$ and $s \in S$, we have $L(s)(x) \in dom(x)$
2. for every formula A over \mathcal{X} and every state $s \in S$, either $L(s) \models A$ or $L(s) \not\models A$

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States as interpretations

If $L(s)(x) = v$, we say that x *has value* v *in state* s , and write $s(x) = v$

If $L(s) \models A$, we say that s *satisfies* A or A *is true in* s , and write $s \models A$

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- Nodes **labeled** by states

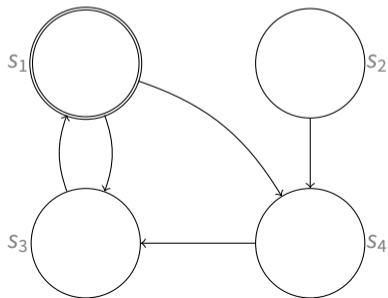
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Example: $\mathcal{X} = \{x, y\}$, $dom(x) = dom(y) = \{0, 1\}$



$$\begin{aligned} S &= \{s_1, s_2, s_3, s_4\} \\ In &= \{s_1\} \\ T &= \{(s_1, s_3), (s_1, s_4), (s_3, s_1), \\ &\quad (s_4, s_2), (s_4, s_3)\} \\ L &= \{s_1 \mapsto \{x \mapsto 1, y \mapsto 0\}, \\ &\quad s_2 \mapsto \{x \mapsto 1, y \mapsto 1\}, \\ &\quad s_3 \mapsto \{x \mapsto 0, y \mapsto 0\}, \\ &\quad s_4 \mapsto \{x \mapsto 0, y \mapsto 1\}\} \end{aligned}$$

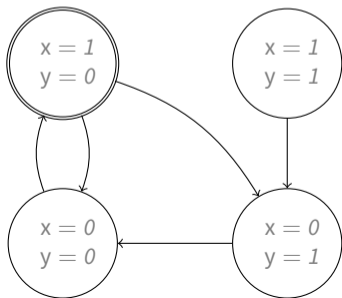
State Transition Graph with interpretations as states

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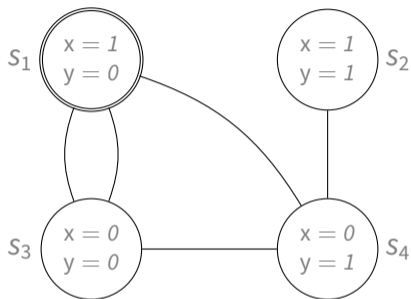
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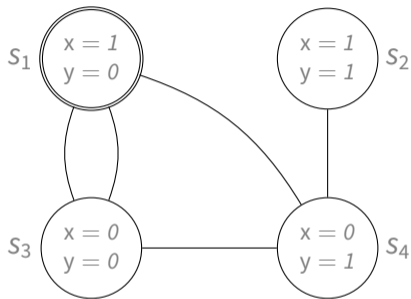
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States as Interpretations



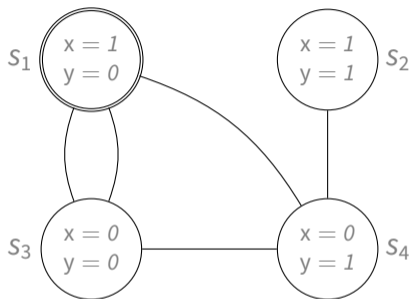
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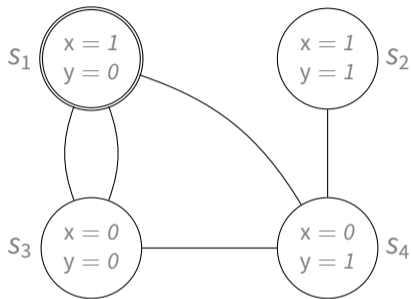
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Transitions

We will usually represent a transition relation as a **union of transitions**

Transition t : any set of state pairs

A transition t is

- *applicable* to a state s if there is a state s' such that $(s, s') \in t$
- *deterministic* if for every state s there is at most one state s' such that $(s, s') \in t$

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Vending machine

1. The vending machine contains a drink storage, a coin slot, and a drink dispenser.
2. The drink storage stores drinks of two kinds: soda and coffee. We are only interested in whether a particular kind of drink is currently being stored or not (but not its amount).
3. The coin slot can accommodate up to three coins.
4. The drink dispenser can hold at most one drink. Any drink in it must be removed before the next one can be dispensed.
5. A can of soda costs two coins. A cup of coffee costs one coin.
6. There are two kinds of customers: students and professors. Students drink only soda, professors drink only coffee.
7. From time to time the drink storage can be restocked.

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7. From time to time the drink storage can be restocked.

Formalization: Variables and Domains

variable	domain	explanation
st_coffee	{ 0, 1 }	drink storage contains coffee
st_soda	{ 0, 1 }	drink storage contains soda
disp	{ <i>none, soda, coffee</i> }	content of drink dispenser
coins	{ 0, 1, 2, 3 }	number of coins in the slot
customer	{ <i>none, student, prof</i> }	customer

Transitions for the Vending Machine

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Symbolic Representation of Sets of States

Let $\mathbb{S} = (S, In, T, \mathcal{X}, dom, L)$ be a (finite-state) labelled transition system

Every PLFD formula F over the variables in \mathcal{X} defines a set states:

$$\{s \in S \mid s \models F\}$$

Symbolic Representation of Sets of States

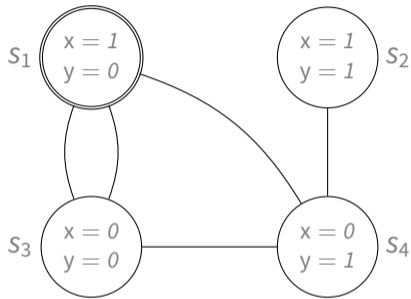
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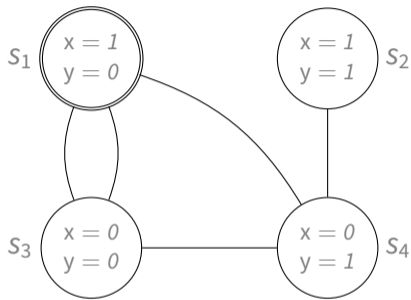
We say that F (*symbolically*) *represents* this set of states

Symbolic Representation of Sets of States



- $x \leftrightarrow y$
- $x \wedge y$
- $\neg x$

Symbolic Representation of Sets of States

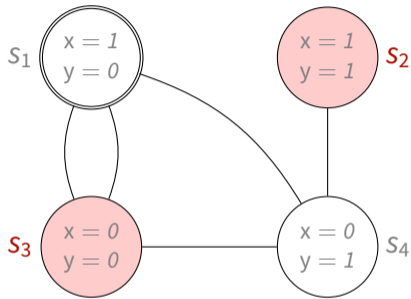


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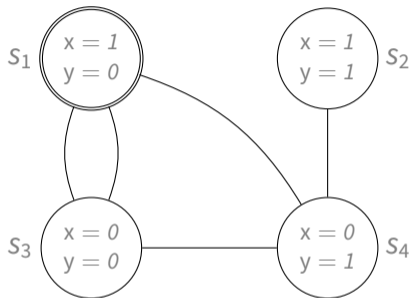
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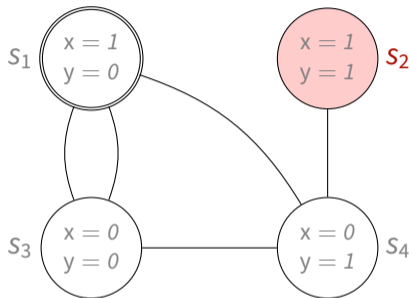
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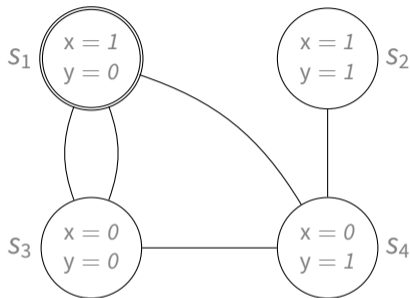
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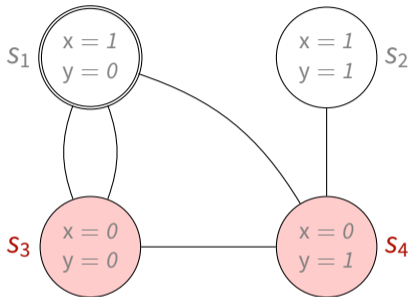
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Example

Let us represent the set of states in which the machine is ready to dispense a drink

In every such state, it must be the case that

- a drink is available
- the drink dispenser is empty, and
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This can be expressed by:

$$\begin{aligned} & (\text{st_coffee} \vee \text{st_soda}) \wedge \\ & \text{disp} = \text{none} \wedge \\ & ((\text{coins} = 1 \wedge \text{st_coffee}) \vee \text{coins} = 2 \vee \text{coins} = 3) \end{aligned}$$

Symbolic Representation of Transitions

$$\mathbb{S} = (S, In, T, \mathcal{X}, dom, L)$$

A *transition* t in \mathbb{S} is a binary relation on s , i.e., a set of **state pairs**:

$$t = \{ (s, s') \mid s, s' \in S \}$$

It takes the system from some *current state* or *pre-state* s
to some *next state* or *post-state* s'

Can we represent transitions symbolically using PLFD formulas?

Not immediately.

PLFD formulas over \mathcal{X} can only express properties of a single state

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How can we represent transitions using formulas?

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$$\text{For all } x \in \mathcal{X}, \quad (s, s')(x) \stackrel{\text{def}}{=} s(x)$$

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The transition *Restock*:

$$\text{customer} = \text{none} \wedge \text{st_coffee}' \wedge \text{st_soda}'$$

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Note: This formula describes a **strange transition** after which, for example

- coins may appear in and disappear from the slot
- drinks may appear in and disappear from the dispenser
- ...

Frame problem

We must express explicitly, possibly for a large number of state variables, that
the values of certain variables do not change after a transition

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The frame formula

$$\mathbb{S} = (S, In, T, \mathcal{X}, dom, L)$$

Notation:

When $dom(x) = dom(y)$,

$$x \neq v \stackrel{\text{def}}{=} \neg(x = v)$$

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$only(x_1, \dots, x_n)$ can be used in symbolic transitions to state that x_1, \dots, x_n are the only variables whose values may change in the transition

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Preconditions and postconditions

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Typical symbolic representation of a transition t in \mathbb{S} :

A PLFD formula $F_1 \wedge F_2$ where

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precondition: a necessary condition for a state of \mathbb{S} of to be a pre-state of t

postcondition: a condition relating t 's post-states to their corresponding pre-state

Transitions for the Vending Machine

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Transitions: Symbolic Representation

Restock

Customer_arrives

Customer_leaves

Coin_insert

Transitions: Symbolic Representation

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Restock $\stackrel{\text{def}}{=}$ $\begin{matrix} \textit{precondition} & \textit{postcondition} \\ \textit{customer} = \textit{none} \wedge \textit{st_coffee}' \wedge \textit{st_soda}' \\ & \wedge \textit{only}(\textit{st_coffee}, \textit{st_soda}) \end{matrix}$

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<i>Customer_arrives</i>	$\stackrel{\text{def}}{=}$	$\text{customer} = \text{none}$	$\wedge \text{customer}' \neq \text{none}$ $\wedge \text{only}(\text{customer})$

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<i>Coin_insert</i>	$\stackrel{\text{def}}{=}$	$customer \neq none$	$(coins = 0 \rightarrow coins' = 1)$
	\wedge	$coins \neq 3$	$\wedge (coins = 1 \rightarrow coins' = 2)$ $\wedge (coins = 2 \rightarrow coins' = 3)$ $\wedge only(coins)$

Transitions

Dispense_soda
Dispense_coffee
Take_drink

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Take_drink $\stackrel{\text{def}}{=}$ $\text{customer} \neq \text{none} \wedge \text{disp} \neq \text{none} \wedge$
 $\text{disp}' = \text{none} \wedge \text{only}(\text{disp})$

Temporal properties of transition systems

1. There is **no state** in which professors and students are both customers.
2. Students **always** get soda.
3. The machine cannot dispense drinks **forever** without recharging.
4. **Eventually**, the machine runs out of soda.
5. If coffee has just been dispensed, the machine must have had coins right **before**.
6. If the machine is **never** restocked it will **never** dispense drinks.
7. The machine **never** dispenses drinks at a discount or for free.
8. ...

Temporal properties of transition systems

1. There is **no state** in which professors and students are both customers.
2. Students **always** get soda.
3. The machine cannot dispense drinks forever without recharging.
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These properties, which talk about the systems behavior over time, cannot be expressed in PLFD. We need a more expressive logic!