

# Traces arising from regular inclusions

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# Outline

- 1 Introduction
- 2 Invariant states
- 3 The groupoid framework: balanced measures
- 4 The graph framework: graph traces

# Tracial states

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Note that  $n^*n, nn^* \in B$  for any  $n \in N(B)$  if  $B$  contains an approximate identity for  $A$ .

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For which states  $\phi \in S(B)$  is the extension  $\phi \circ \mathbb{E}$  a *tracial state* on  $A$ ? If  $S'$  is the set of such states, is the map  $S' \rightarrow T(A)$  given by  $\phi \mapsto \phi \circ \mathbb{E}$  a surjection?

# Invariant states

## Definition

If  $\phi \in S(B)$  and  $n \in N(B)$ , then  $\phi$  is called *n-invariant* if  $\phi(nbn^*) = \phi(n^*nb)$  for all  $b \in B$ . If  $N_0 \subset N(B)$ , then  $\phi$  is  *$N_0$ -invariant* if it is *n-invariant* for all  $n \in N_0$ . If  $\phi$  is  *$N(B)$ -invariant* we will call  $\phi$  *fully invariant*

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If  $\tau \in T(A)$  is a tracial state, then  $\phi = \tau|_B$  is a fully invariant state on  $B$ .

Under fairly mild assumptions the converse of the above example is also true.

# Normalization of conditional expectations

## Definition

Let  $E : A \rightarrow B$  be a conditional expectation. We say that  $\mathbb{E}$  is *normalized* by  $n \in N(B)$  if  $\mathbb{E}(nan^*) = n\mathbb{E}(a)n^*$  for all  $a \in A$ . (Similar for  $N_0 \subset N(B)$ .)

In the cases that we care about, the relevant conditional expectations will be normalized by a set of normalizers that generate  $A$ .



## Invariant states, part II

### Theorem (C., Nagy '15)

*Suppose that  $B \subset A$  is a regular inclusion and  $\mathbb{E} : A \rightarrow B$  is a conditional expectation which is normalized by  $N_0 \subset N(B)$ . Then for any  $N_0$ -invariant state  $\phi \in S(B)$ , the composition  $\phi \circ \mathbb{E}$  is a tracial state when restricted to  $C^*(B \cup N_0) \subset A$ .*

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### Corollary

*Suppose that  $\mathbb{E} : A \rightarrow B$  is normalized by  $N_0 \subset N(B)$  and  $\phi$  is a  $N_0$ -invariant state on  $B$ , where  $N_0$  generates  $A$  as a  $C^*$ -algebra. Then  $\phi \circ \mathbb{E}$  is a tracial state on  $A$ .*

# Proof

## Proof

We show that if  $\mathbb{E}$  is normalized by  $n$  and  $\phi \in S(B)$  is an  $n$ -invariant state, then  $\phi \circ \mathbb{E}(na) = \phi \circ \mathbb{E}(an)$  for all  $a \in A$ , because we can then use the fact that the centralizer of a state always forms a  $C^*$ -algebra.

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$$\phi(\mathbb{E}((nn^*)^j na)) = \phi(\mathbb{E}(an(n^*n)^j))$$

for any positive integer  $j$ , because we have the approximations

$$na = \lim_{k \rightarrow \infty} (nn^*)^{1/k} na \quad an = \lim_{k \rightarrow \infty} an(n^*n)^{1/k}$$

and we can find suitable polynomials with zero constant term approximating the  $k$ -th root function.

## Proof, ctd.

$$\phi(\mathbb{E}(an(n^*n)^j)) = \phi(\mathbb{E}(an(n^*n)^{j-1})n^*n) \quad (1)$$

$$= \phi(n\mathbb{E}(an(n^*n)^{j-1})n^*) \quad (2)$$

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Here (1) follows because  $\mathbb{E}$  is a conditional expectation, (2) from the  $n$ -invariance of  $\phi$ , (3) from the fact that  $n$  normalizes  $\mathbb{E}$ , and (4) follows from conditional expectation and commutativity of  $B$ . □

## Parametrizing the trace space

The previous result shows that if we have a conditional expectation which is normalized by  $N(B)$ , then there is a surjective map

$$\text{res} : T(A) \ni \tau \mapsto \tau|_B \in S_{\text{inv}}(B)$$

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### Question

When is the restriction map injective? That is, for which inclusions  $B \subset A$  is it always the case that any tracial state  $\tau \in T(A)$  is fully determined by its restriction to  $B$ ?

# The extension property

## Definition

A non-degenerate inclusion  $B \subset A$  is said to have the *extension property* if every pure state  $\phi \in P(B)$  has a *unique* extension to a state on  $A$  (which must then be pure).

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If an inclusion has the extension property one automatically obtains a conditional expectation  $\mathbb{E} : A \rightarrow B$ , so these inclusions fall within our framework.

## Proposition (C., Nagy '15)

*If  $B \subset A$  is a non-degenerate inclusion with the extension property, then the restriction map carrying  $T(A)$  to  $S_{\text{inv}}(B)$  is injective.*

## Proof of proposition

### Proof.

By a result of Archbold [1], if  $B \subset A$  has the extension property, the kernel of the associated conditional expectation  $\mathbb{E} : A \rightarrow B$  is spanned by the commutators  $\{ab - ba : a \in A, b \in B\}$ .



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### Remark

We do not claim that the tracial state space is non-empty in this case (there are examples of inclusions with the extension property where  $T(A) = \emptyset$ ).

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### Remark

We do not claim that the tracial state space is non-empty in this case (there are examples of inclusions with the extension property where  $T(A) = \emptyset$ ). Also, there are cases of inclusions without the extension property for which  $\tau \mapsto \tau|_B$  is still injective (for example,  $\mathbb{C} \subset C_r^*(\mathbb{F}_2)$ ).

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- (iii) an involutive inversion operation  $\alpha \mapsto \alpha^{-1}$  such that  
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Sometimes elements of  $G$  are called *morphisms* or *arrows*, as an alternate definition of a groupoid is as a small category with inverses.



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For any element  $\alpha$  of  $G$ , the compositions  $s(\alpha) := \alpha^{-1}\alpha$  and  $r(\alpha) = \alpha\alpha^{-1}$  are units referred to as the *source* and *range* of  $\alpha$ . The set of all units is denoted by  $G^{(0)} \subset G$ .

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Étale groupoids turn out to be the appropriate generalization of discrete groups/discrete dynamical systems to the groupoid context.

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where  $\pi_u$  is the representation on  $\ell^2(s^{-1}(u))$  given by  $\pi_u(f)\delta_\gamma = f * \delta_\gamma$  for  $\gamma \in s^{-1}(u)$ . The abelian  $C^*$ -algebra  $C_0(G^{(0)})$  is contained in  $C_r^*(G)$  as the completion of  $C_c(G^{(0)}) \subset C_c(G)$ . There is a conditional expectation  $\mathbb{E}_{\text{red}} : C_r^*(G) \mapsto C_0(G^{(0)})$  extending restriction  $C_c(G) \rightarrow C_c(G^{(0)})$ .

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## Definition

Let  $\mu$  be a Radon probability measure on  $G^{(0)}$  and let  $B \subset G$  be an open bisection. Then  $\mu$  is called *B-balanced* if for every compact subset  $K \subset G^{(0)}$  we have  $\mu(BKB^{-1}) = \mu(s(B) \cap K)$ . We call  $\mu$  *totally balanced* if it is *B-balanced* for every open bisection  $B$ .



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If  $\mu$  is a totally balanced measure then the corresponding state  $\phi_\mu$  on  $C_0(G^{(0)})$  will be *n*-invariant for every elementary normalizer  $n$ .

## Balanced measures and tracial states

Let  $G$  be étale. If  $\tau$  is a tracial state on  $C_r^*(G)$ , then the restriction  $\tau|_{C_0(G^{(0)})}$  is a state on  $C_0(G^{(0)})$ , and the corresponding measure  $\mu_\tau$  on  $G^{(0)}$  is balanced.

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### Proposition (C., Nagy)

*Let  $G$  be an étale groupoid, let  $\mu$  be a probability Radon measure on  $G^{(0)}$ , and let  $\phi_\mu$  be the corresponding state on  $C_0(G^{(0)})$ . The following conditions are equivalent:*

- (i)  $\mu$  is totally balanced;
- (ii)  $\phi_\mu$  is elementary invariant;
- (iii)  $\phi_\mu$  is fully invariant;
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## Balanced measures and tracial states

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(In particular this shows that  $\tau \mapsto \mu_\tau$  is a surjection onto the collection of totally balanced probability measures.)

# Parametrizing the trace space

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When is the map  $\tau \mapsto \mu_\tau$  injective (and hence a bijection)?

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## Proposition

Let  $G$  be a principal étale groupoid. Then the map from  $T(C_r^*(G))$  onto the collection of totally balanced probability measures is a bijection. Equivalently, the map  $\mu \mapsto \phi_\mu \circ \mathbb{E}_{\text{red}}$  is a surjection.

# Proof

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By a result of Kumjian, if  $G$  is principal then the inclusion  $C_0(G^{(0)}) \subset C_r^*(G)$  has the extension property. Thus the theorem from the previous section about general regular inclusions ensures that the map from  $T(C_r^*(G))$  onto  $S_{\text{inv}}(C_0(G^{(0)}))$  is in fact a bijection. □



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## Question

What are necessary and sufficient conditions for  $\tau \mapsto \mu_\tau$  to be injective? What information needs to be added to  $\mu_\tau$  in order to describe the trace space bijectively?

# Graph $C^*$ -algebras

If  $E = (E^0, E^1, r, s)$  is a directed graph, then there is a universal  $C^*$ -algebra  $C^*(E)$  generated by a family  $\{s_e, p_v\}_{e \in E^1, v \in E^0}$  such that

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For a directed path  $\alpha = e_1 \dots e_n$ , we denote the associated partial isometry  $s_{e_1} \dots s_{e_n}$  by  $s_\alpha$ . Elements of the form  $s_\alpha s_\beta^*$ , for  $\alpha, \beta \in E^*$  (finite path space), span the graph  $C^*$ -algebra.



# The abelian core

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It is shown in [4] that there is a conditional expectation  $\mathbb{E}$  from  $C^*(E)$  onto  $\mathcal{M}(E)$ . It is easy to verify that  $\mathcal{M}(E) \subset C^*(E)$  is regular (all the generators of  $C^*(E)$  are normalizers of  $\mathcal{M}(E)$ ). The abelian core is a MASA, in fact  $\mathcal{M}(E) = \mathcal{D}(E)'$ , where  $\mathcal{D}(E) = \overline{\text{span}}\{s_\alpha s_\alpha^* : \alpha \in E^*\}$ .

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If  $\tau$  is a tracial state on  $C^*(E)$  then  $g_\tau(v) = \tau(p_v)$  defines a normalized graph trace on  $E$ .

Tomforde in [5] showed that the map  $\tau \mapsto g_\tau$  is surjective onto the normalized graph traces, using states on  $K$ -theory.

# The tracial state space

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Let  $E$  be the graph with one edge  $e$  and one vertex  $v$ . Then  $C^*(E) \cong C(\mathbb{T})$ , which has infinitely many tracial states. However, there is only one graph trace,  $g(v) = 1$ .

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## Question

What additional structure needs to be added to parametrize all the tracial states? When is the map  $\tau \mapsto g_\tau$  injective?

# The tracial state space, ctd.

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# Cyclically tagged graph traces

## Definition

The *cyclic support* of a graph trace  $g$  is the set  $\text{supp}^c g$  of vertices  $v$  with  $g(v) > 0$  that lie on cycles without entry. A *cyclically tagged graph trace* is a pair  $(g, \mu)$ , where  $g$  is a normalized graph trace and  $\mu : \text{supp}^c g \rightarrow \text{Prob}(\mathbb{T})$ . It is *consistent* if whenever  $v$  and  $w$  are on the same cycle, then  $\mu(v) = \mu(w)$ . The space of consistent cyclically tagged graph traces is denoted by  $T_1^{\text{CCT}}(E)$ .

## Example

If  $\tau$  is a tracial state on  $C^*(E)$ , we obtain the graph trace  $g_\tau$  as before, and the cyclic tagging  $\mu = \mu_{\tau} \text{au}$  is defined for  $v \in \text{supp}^c g$

$$\int_{\mathbb{T}} z^k d\mu_v = \frac{\tau(s_\lambda^k)}{\tau(p_v)} \quad s(\lambda) = r(\lambda) = v \quad |\lambda| \text{ minimal.}$$

# Invariant states and cyclically tagged graph traces

## Theorem (C., Nagy)

If  $(g, \mu) \in T_1^{\text{CCT}}(E)$ , there is a state  $\phi_{(g, \mu)}$  on  $\mathcal{M}(E)$  which satisfies  $\phi_{(g, \mu)}(s_\alpha s_\alpha^*) = g(s(\alpha))$  and

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## Idea of proof

Divide the Gelfand spectrum  $\Omega$  of  $\mathcal{M}(E)$  into two parts, and then define the state on  $\mathcal{M}(E)$  by choosing a measure on  $\Omega$  that is suitably invariant. (One part will carry the graph trace and the other will carry the tagging.) □

# Parametrizing $T(C^*(E))$

## Theorem (C., Nagy )

(1) for any  $E$ , the map

$$T_1^{\text{CCT}}(E_{\text{tight}}) \ni (g, \mu) \mapsto \tau_{(g, \mu)} \circ \rho_{\text{tight}} \in T(C^*(E))$$

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(2) if  $E$  is tight, then  $\tau \mapsto (g_\tau, \mu_\tau)$  is an isomorphism from  $T(C^*(E))$  onto  $T_1^{\text{CCT}}(E)$ .

# When is $\tau \mapsto g_\tau$ injective

Tomforde noted that if  $E$  satisfies condition (K), then the map  $\tau \mapsto g_\tau$  is injective. However this is not necessary.

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### Definition

Two (finite) paths  $\lambda$  and  $\mu$  are *incomparable* if neither one contains the other as initial prefix. A vertex  $v$  is *essentially left infinite* if there is an infinite set  $\{\lambda_k\}$  of finite paths that are pairwise incomparable and such that  $s(\lambda_k) = v$  for all  $k$ .

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For a directed graph  $E$  the following are equivalent:

- (i) the map  $\tau \mapsto g_\tau$  is injective;
- (ii) the source of each cycle in  $E$  is essentially left infinite.

# When is $\tau \mapsto g_\tau$ injective, ctd.

## Proof.

(ii)  $\Rightarrow$  (i): If a vertex  $v$  is essentially left infinite, then any bounded graph trace  $g$  must vanish on  $v$ . Thus if the source of each cycle is essentially left infinite, there are no measures to consider (after passing to the tightening) and the map  $\tau \mapsto g_\tau$  is injective.

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(i)  $\Rightarrow$  (ii): If  $v$  is the source of a cycle and  $v$  is *not* essentially left infinite, then we can define a (non-normalized but bounded) graph trace  $g$  on  $E$  by  $g(w) = |\{\text{paths } v \rightarrow w\}|$ . Thus there is a normalized graph trace  $g$  on  $E$  which does not vanish at  $v$ , and if we take any non-Lebesgue probability measure for  $\mu_v$ , the tagging  $(g, \mu_v)$  is consistent.



## Directions for future work

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- (1) Results on invariant states seem to generalize readily to non-abelian context (suggested by R. Exel).
- (2) Find necessary and sufficient conditions for the balanced measures to parametrize all of  $T(C_r^*(G))$  (should have something to do with non-existence of compact invariant sets or something related, especially for ample groupoids).

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Thank you!