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(P1)

(7.2)

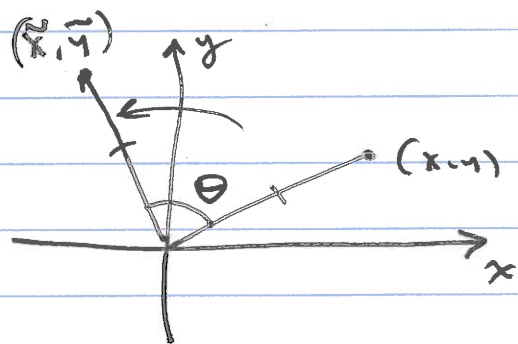
SPECTRAL THM of 7.1

 \Rightarrow PRINCIPAL AXIS THEOREM

Let A be an $n \times n$ symmetric matrix.
 Then there is an orthogonal change of variables
 $\vec{x} = P\vec{y}$ that transforms the quadratic form
 $\vec{x}^T A \vec{x}$ into $\vec{y}^T D \vec{y}$ (D is diagonal) with
 no cross-product terms.

(A)

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x' \\ y' \end{bmatrix}$$



$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

is an orthogonal matrix

Rotation Matrix

Exc #10 p.407

$$Q(x_1, x_2) = 9x_1^2 - 8x_1x_2 + 3x_2^2$$

$x = Py \rightarrow$ q. form with no cross-terms
 \rightarrow i.e. diagonalize (orthogonally)

$$A = \begin{bmatrix} 9 & -4 \\ -4 & 3 \end{bmatrix}$$

$$\begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 9 & -4 \\ -4 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 9x_1^2 - 8x_1x_2 + 3x_2^2$$

Orthogonally diagonalize A.

$$\begin{aligned} \cdot \begin{vmatrix} 9-\lambda & -4 \\ -4 & 3-\lambda \end{vmatrix} &= (9-\lambda)(3-\lambda) - 16 \\ &= 27 - 12\lambda + \lambda^2 - 16 \\ &= \lambda^2 - 12\lambda + 11 \end{aligned}$$

$$\text{Det } A = \begin{vmatrix} 9 & -4 \\ -4 & 3 \end{vmatrix} = 11 = \lambda_1 \lambda_2$$

$$\text{Trace } A = 9 + 3 = 12 = \lambda_1 + \lambda_2$$

$$\begin{matrix} \nearrow & \nearrow \\ a_{11} & + & a_{22} \end{matrix}$$

trace

$$\lambda_1 + \lambda_2$$

det = $\lambda_1 \lambda_2$

$$= (\lambda - 11)(\lambda - 1)$$

$$\lambda = 1 \quad A - I = \begin{bmatrix} 8 & -4 \\ -4 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -\frac{1}{2} \\ 0 & 0 \end{bmatrix}$$

$$x_1 - \frac{1}{2}x_2 = 0$$

$$\begin{bmatrix} 1 \\ 2 \end{bmatrix} \text{ basis for eigenspace } \lambda = 1$$

$$\lambda = 11$$

$$A - 11I = \begin{bmatrix} -2 & -4 \\ -4 & -8 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix}$$

$$x_1 + 2x_2 = 0$$

$$\begin{bmatrix} -2 \\ 1 \end{bmatrix} \text{ basis for eigenspace } \lambda = 11.$$

$$P = \begin{bmatrix} \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{bmatrix}$$

$$D = \begin{bmatrix} 1 & 0 \\ 0 & 11 \end{bmatrix}$$

$$Py = x$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

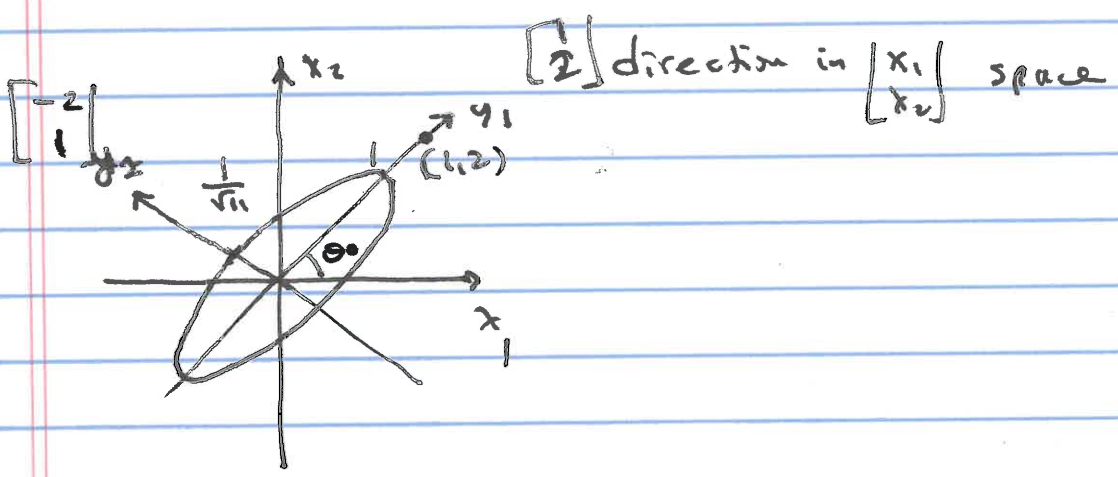
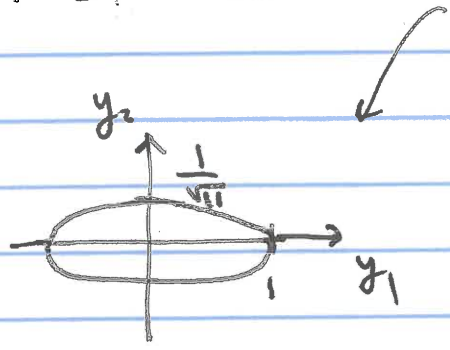
Rotation matrix
 $\cos \theta_0 = \frac{1}{\sqrt{5}}$
 $\sin \theta_0 = \frac{2}{\sqrt{5}}$

$$9x_1^2 - 8x_1x_2 + 3x_2^2 = y_1^2 + 11y_2^2$$

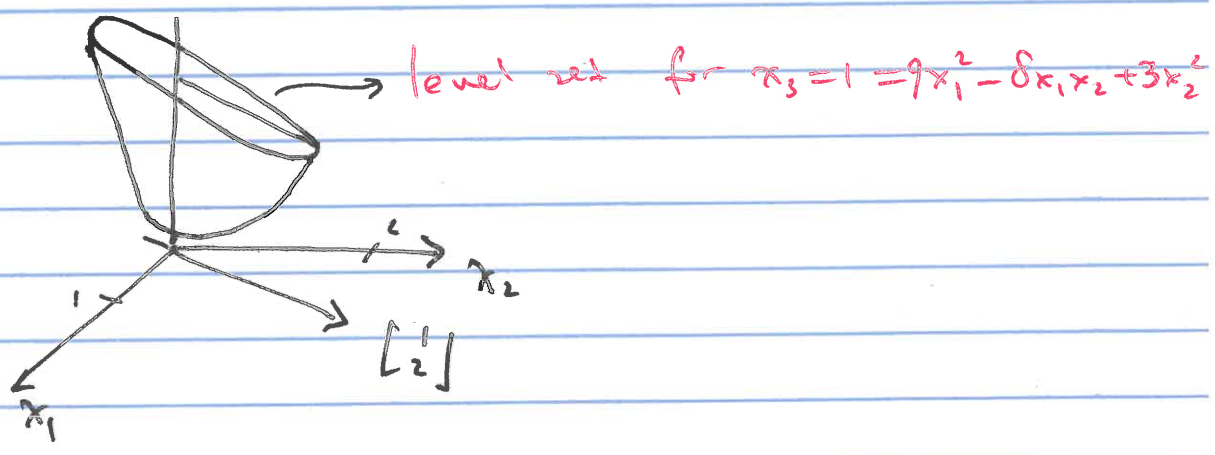
We also do more:

Graph:

(b) $9x_1^2 - 8x_1x_2 + 3x_2^2 = 1 = y_1^2 + 11y_2^2$



(c) $x_3 = 9x_1^2 - 8x_1x_2 + 3x_2^2$ plot 3-D graph



CLASSIFYING QUADRATIC FORMS

A quadratic form is positive-definite if $Q(x) > 0$ if $x \neq 0$

A quadratic form is negative definite if $Q(x) < 0$ for all $x \neq 0$

A quadratic form is called indefinite if $Q(x) < 0 < Q(x')$ for some x, x' .

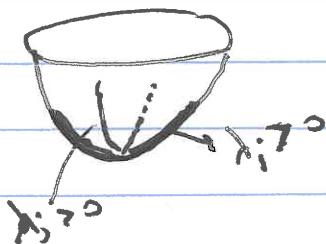
Then Given $Q = x^T A x$, A symmetric

Q is + definite \Leftrightarrow All eigenvalues of A are +

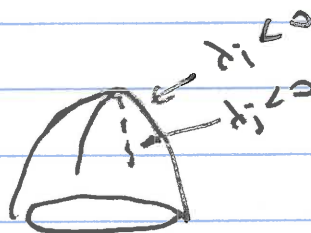
Q is - " \Leftrightarrow " " " " -

Q is indefinite \Leftrightarrow A has at least one (+) eigenvalue & at least one (-) eigenvalue

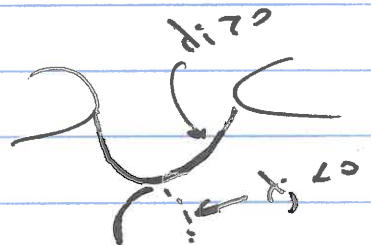
$x \in \mathbb{R}^n$ $x_{min} = x^T A x$. *Graphs:*



+ definite



- definite



indefinite

Ex

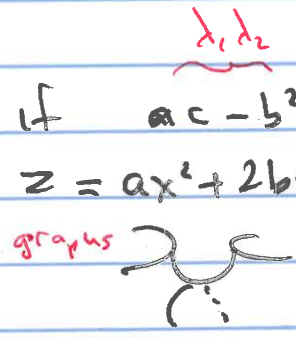
$$\begin{bmatrix} a & b \\ b & c \end{bmatrix} = A$$

when + definite?
- definite?
indefinite?

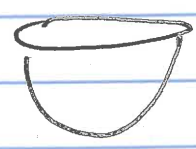
$$\lambda_1 \lambda_2 = \det = ac - b^2$$

$$\lambda_1 + \lambda_2 = \text{trace} = a + c.$$

$Q(x) = x^T A x$ is definite if $ac - b^2 < 0$.
 $z = ax^2 + 2bxy + cy^2$



$\left. \begin{matrix} ac - b^2 > 0 \\ a + c > 0 \end{matrix} \right\} + \text{definite}$



$\left. \begin{matrix} ac - b^2 > 0 \\ a + c < 0 \end{matrix} \right\} - \text{definite}$

