

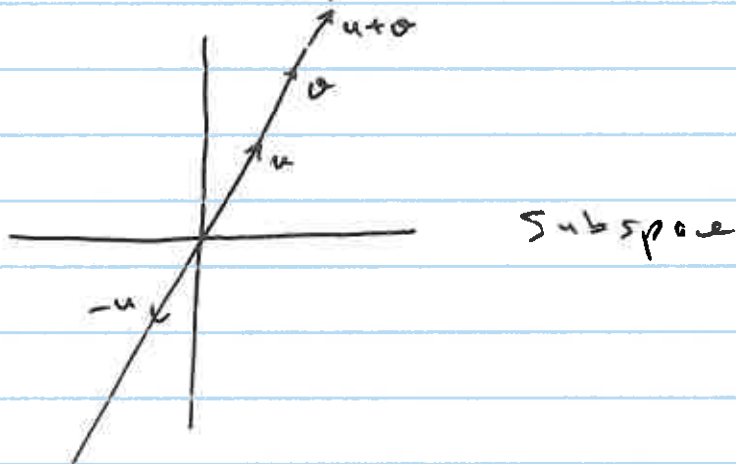
①

2.8 Subspaces,  $\text{Col}(A)$ ,  $\text{Nul}(A)$ 

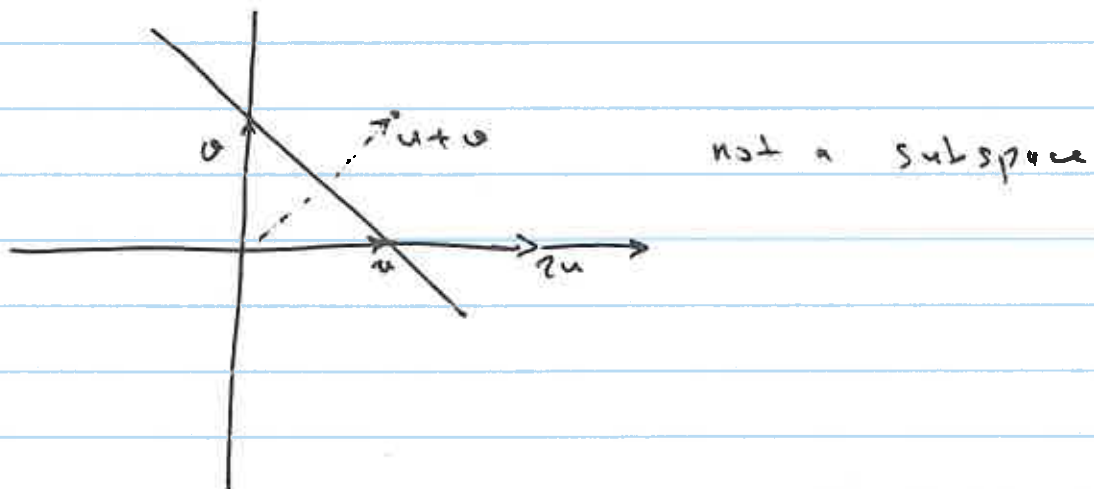
Def: A set  $H \subseteq \mathbb{R}^n$  is called a subspace if

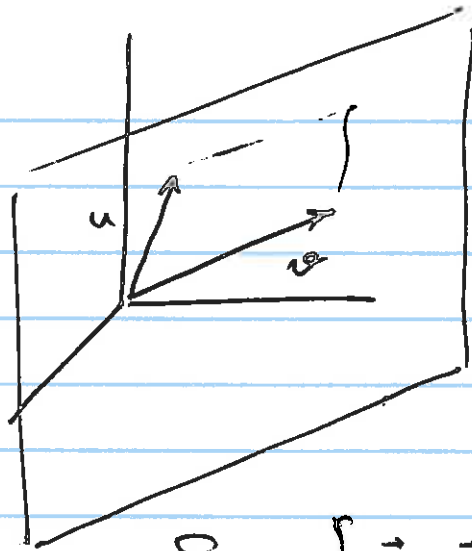
- $\vec{u}, \vec{v} \in H \Rightarrow \vec{u} + \vec{v} \in H$ , and
- $\vec{u} \in H, c \in \mathbb{R} \Rightarrow c \cdot \vec{u} \in H$ .

Ex ①  $\left\{ \begin{bmatrix} x \\ y \end{bmatrix} \mid y = x \right\} \subseteq \mathbb{R}^2$



②  $\left\{ \begin{bmatrix} x \\ y \end{bmatrix} \mid x + y = 1 \right\}$





In  $\mathbb{R}^3$

Take  $\vec{u}, \vec{v}$ , both non-zero, not parallel,

$\text{Span}\{\vec{u}, \vec{v}\} = 2\text{-plane thru origin}$   
 $\times$  tips of  $\vec{u} \times \vec{v}$

Prop For any given set of vectors  $\{\vec{w}_1, \vec{w}_2, \dots, \vec{w}_p\}$

in  $\mathbb{R}^n$ , the span  $\{\vec{w}_1, \vec{w}_2, \dots, \vec{w}_p\}$

$$= \left\{ c_1 \vec{w}_1 + c_2 \vec{w}_2 + \dots + c_p \vec{w}_p \mid c_1, c_2, \dots, c_p \in \mathbb{R} \right\}$$

= the set of all possible linear combinations of  $\vec{w}_1, \vec{w}_2, \dots, \vec{w}_p$

is a subspace of  $\mathbb{R}^n$ .

In  $\mathbb{R}^3$  The subspaces are:

- $\{\vec{0}\}$
- lines thru origin
- planes thru origin
- $\mathbb{R}^3$

Defn A subset B of a subspace H is called a basis if

- B is linearly independent
- B spans H.

Consequence of this:

- every vector in H is a linear combination of vectors from B, and
- every vector in H can be represented as a linear combination from B in a unique way.

$\Rightarrow$

$$\text{Span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right\}$$

$\Rightarrow$  the xy plane in x, y, z space.

$$\begin{bmatrix} 3 \\ 5 \\ 0 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + 5 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + 0 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 3 \\ 5 \\ 0 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + 4 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + 1 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

Why can I do this in different ways?

Ans:  $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right\}$  is not linearly independent

$$\text{If } H = \mathbb{R}^n, \quad B = \{ \vec{v}_1, \vec{v}_2, \dots, \vec{v}_p \}.$$

$$A = \underbrace{\begin{bmatrix} \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_p \end{bmatrix}}_{\text{as column vectors}} \xrightarrow{\text{RR}} \text{RREF}(A)$$

$$\{ \vec{v}_1, \vec{v}_2, \dots, \vec{v}_p \} \text{ spans } \mathbb{R}^n$$

$\Leftrightarrow$  Every row of  $\text{RREF}(A)$  has a leading 1 of a row.

$$\{ \vec{v}_1, \vec{v}_2, \dots, \vec{v}_p \} \text{ linearly independent}$$

$\Leftrightarrow$  Every column of  $\text{RREF}(A)$  has a leading 1 of a row.

$$\{ \vec{v}_1, \vec{v}_2, \dots, \vec{v}_p \} \text{ is a basis of } \mathbb{R}^n$$

$\Leftrightarrow \text{RREF}(A) = I_n$

Example

①

Given  $B = \left\{ \begin{bmatrix} 1 \\ 1 \\ -3 \end{bmatrix}, \begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix}, \begin{bmatrix} 5 \\ 1 \\ -4 \end{bmatrix} \right\}$

Is  $B$  a basis of  $\mathbb{R}^3$ ?

$$\begin{bmatrix} 1 & 3 & 5 \\ 1 & -1 & 1 \\ -3 & 2 & -4 \end{bmatrix} \rightarrow \rightarrow \rightarrow \begin{bmatrix} 1^* & 0 & 2 \\ 0 & 1^* & 1 \\ 0 & 0 & 0 \end{bmatrix} = \text{RREF}$$

correction

not basis for  $\mathbb{R}^3$

not spanning  $\mathbb{R}^3$

not lin independent

② Another example

$$B = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 4 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 5 \end{bmatrix} \right\}$$

$$\begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & 3 & 0 & 1 \\ 0 & 0 & 4 & 5 \end{bmatrix} \xrightarrow{\text{RREF}} \rightarrow \begin{bmatrix} 1 & 0 & 0 & * \\ 0 & 1 & 0 & * \\ 0 & 0 & 1 & * \end{bmatrix}$$

Basis for  $\mathbb{R}^3$       No

Span  $\mathbb{R}^3$       Yes

lin Indp      No

IMPORTANT \* \* \* \* \*

COLUMN SPACE

Given an  $m \times n$  matrix  $A$ , the subspace of

$\mathbb{R}^m$  spanned by the columns of  $A$

is called the column space of  $A$

denoted by  $COL(A)$ .

NULL SPACE

Given an  $m \times n$  matrix  $A$  the subspace

of  $\mathbb{R}^n$  defined by  $\{ \vec{x} \in \mathbb{R}^n \mid A \cdot \vec{x} = 0 \}$

is called the null-space of  $A$ ,

denoted by  $NUL(A)$

Method ① Do RREF

② see next page.

$$\text{Ex } A = \begin{bmatrix} 3 & -6 & 9 & 0 \\ 2 & -4 & 7 & 2 \\ 3 & -6 & 6 & -6 \end{bmatrix} \quad 3 \times 4$$

Find  $\text{COL}(A)$ ,  $\text{NUL}(A)$

$$\begin{bmatrix} 3 & -6 & 9 & 0 \\ 2 & -4 & 7 & 2 \\ 3 & -6 & 6 & -6 \end{bmatrix} \xrightarrow{\substack{R_1 - R_2 \\ R_1 \\ R_3}} \begin{bmatrix} 1 & -2 & 2 & -2 \\ 2 & -4 & 7 & 2 \\ 3 & -6 & 6 & -6 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & -2 & 0 & -6 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

NULL SPACE :  $A \cdot \vec{x} = 0$

$$\begin{bmatrix} 1 & -2 & 0 & -6 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

↑  
pivot

↑  
pivot

↑  
free parameters  $x_2, x_4$

$$x_1 - 2x_2 - 6x_4 = 0$$

$$x_3 + 2x_4 = 0$$

$$x_1 = 2x_2 + 6x_4$$

$$x_2 = x_2 \quad \text{free}$$

$$x_3 = -2x_4$$

$$x_4 = x_4 \quad \text{free}$$

Write soln in vector parameter form (8)

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = x_2 \begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 6 \\ 0 \\ -2 \\ 1 \end{bmatrix}$$

↙ basis for  $NUL(A)$

$$NULL SPACE = \text{span} \left\{ \begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 6 \\ 0 \\ -2 \\ 1 \end{bmatrix} \right\}$$

↙ in  $\mathbb{R}^4$

A is  
3x4  
matrix.

COLUMN SPACE :

$$\text{span} \left\{ \begin{bmatrix} 3 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 9 \\ 7 \\ 6 \end{bmatrix} \right\}$$

↙ in  $\mathbb{R}^3$

Why: column 1  
column 3 of  $RREF(A)$  are pivot.

Take column 1  
column 3 of  $A$

to get COLUMN space basis.



2/26/14  
p8

ADDITIONAL EXAMPLE (As promised in class)

Find bases for  $\text{col} A$  and  $\text{nul} A$  where

$$A = \begin{bmatrix} 2 & 3 & 2 \\ 1 & 4 & 6 \end{bmatrix}$$

Sol<sup>n</sup> Reduce  $\begin{bmatrix} 2 & 3 & 2 \\ 1 & 4 & 6 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 4 & 6 \\ 2 & 3 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 4 & 6 \\ 0 & -5 & -10 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 4 & 6 \\ 0 & 1 & 2 \end{bmatrix}$

$$A\vec{x} = \vec{0} \Rightarrow \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2x_3 \\ -2x_3 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix}$$

$\begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 2 \end{bmatrix}$   
↑ ↑ ↑  
pivots pivots free

Basis for null space  $\left\{ \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix} \right\}$

Basis for column space pivot columns of RREF(A)  
are #1, #2 columns.

$\hookrightarrow$   $\perp$  A #1, #2 columns

$$\left\{ \begin{bmatrix} 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ 4 \end{bmatrix} \right\} \text{ basis for } \text{col} A.$$