

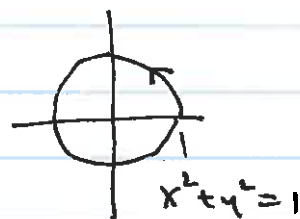
3.1

Defn A continuous function $\vec{x}: I \longrightarrow \mathbb{R}^n$ is called a path or a parametrized curve.

If $I = [a, b]$ then $\vec{x}(a), \vec{x}(b)$ are the end points.

(Ex) • lines $\vec{x}(t) = (1, 0, 5) + t(1, 6, -2)$
 $x(t) = \vec{p}_0 + t\vec{v}_0$

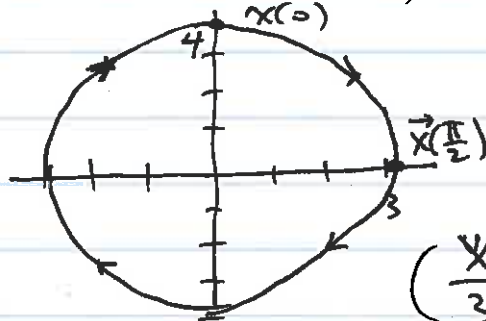
• $\vec{x}(t) = (\underbrace{\cos t}_x, \underbrace{\sin t}_y)$



• $\vec{x}(t) = (\underbrace{3 \sin t}_x, \underbrace{4 \cos t}_y): \mathbb{R} \rightarrow \mathbb{R}^2$

$\vec{x}(0) = (0, 4)$

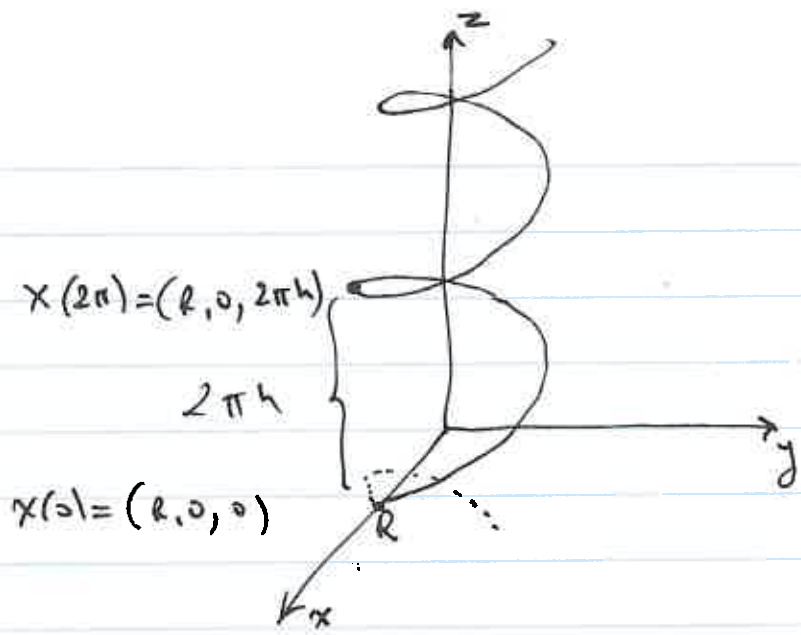
$\vec{x}(\frac{\pi}{2}) = (3, 0)$



Ellipse

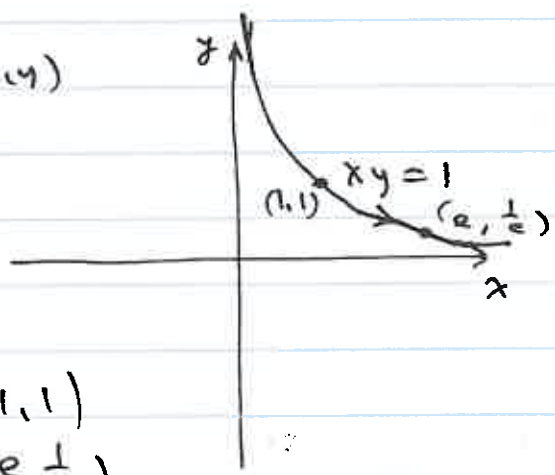
$(\frac{x}{3})^2 + (\frac{y}{4})^2 = 1$

• $\vec{x}(t) = (R \cos t, R \sin t, ht)$
 Called Helix.



p200 Ex #2 $\vec{x}(t) = e^t \vec{i} + e^{-t} \vec{j} = (e^t, e^{-t})$

$\vec{x} = (x, y)$

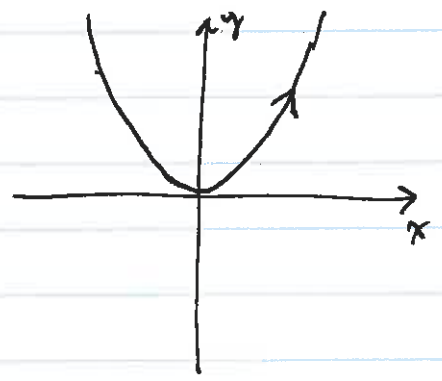


$x = e^t > 0$
 $y = e^{-t} > 0$
 $xy = 1$

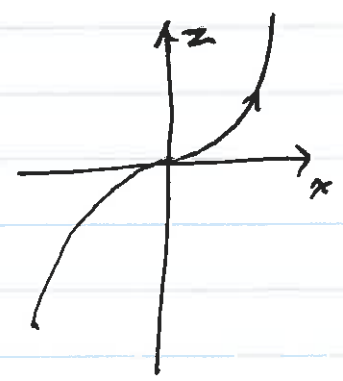
$\vec{x}(0) = (1, 1)$
 $\vec{x}(1) = (e, \frac{1}{e})$

p200 #6 $\vec{x} = (t, t^2, t^3)$

Top view $(x, y) = (t, t^2)$



$(x, z) = (t, t^3)$



③

$$(y, z) = (t^2, t^3)$$

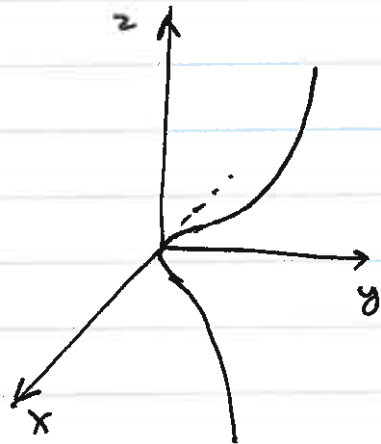
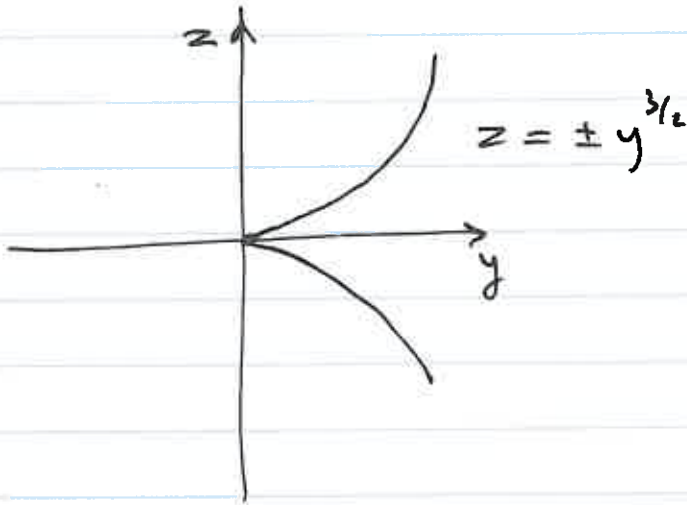
|| ||
y z

$$y = t^2$$

$$z = t^3$$

$$y^3 = z^2$$

$$z = \pm y^{3/2}$$



(4)

Defn Let $\vec{x}: I \subseteq \mathbb{R}^1 \rightarrow \mathbb{R}^n$ be a differentiable parametrized curve

$$\text{Velocity } v(t) = \frac{d\vec{x}}{dt} = \vec{x}'(t) = \dot{\vec{x}}(t)$$

$$\text{Speed} = \|\text{velocity}\| = \|\vec{x}'(t)\|$$

$$\text{Acceleration } \frac{dv}{dt} = \vec{x}''(t) = \ddot{\vec{x}}(t)$$

Unit tangent vector = direction of velocity

$$\begin{array}{ccc} \text{velocity} = (\text{unit tangent vector}) \cdot (\text{speed}) & & \\ \downarrow & & \downarrow \\ \vec{x}'(t) & = & \frac{\vec{x}'(t)}{\|\vec{x}'(t)\|} \cdot \|\vec{x}'(t)\| \end{array}$$

provided that $\|\vec{x}'(t)\| \neq 0$.

p200

Ex # 8 $\vec{x}(t) = 5 \cos t \mathbf{i} + 3 \sin t \mathbf{j}$

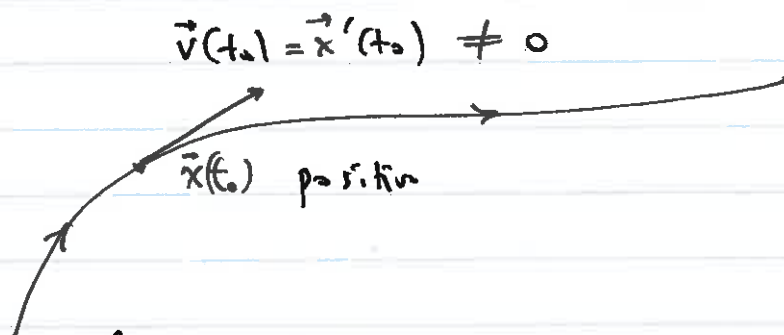
velocity $\vec{x}' = -5 \sin t \mathbf{i} + 3 \cos t \mathbf{j}$

speed $\|\vec{x}'\| = \sqrt{25 \sin^2 t + 9 \cos^2 t}$

acceleration $\vec{x}'' = -5 \cos t \mathbf{i} + (-3 \sin t) \mathbf{j}$

(5)

Tangent line to a parametric curve:



$$l(t) = \underbrace{\vec{x}(t_0) + \vec{x}'(t_0)(t - t_0)}_{\text{parametric line}}$$

#16 $4\cos t \vec{i} = 3\sin t \vec{j} + 5t\vec{k} = \vec{x}(t)$

Tangent line at $t = \frac{\pi}{3}$.

$$\vec{x}\left(\frac{\pi}{3}\right) = \left(4 \cdot \frac{1}{2}, -3 \frac{\sqrt{3}}{2}, 5 \cdot \frac{\pi}{3}\right)$$

$$\vec{x}'(t) = (-4\sin t, -3\cos t, 5)$$

$$\vec{x}'\left(\frac{\pi}{3}\right) = \left(-\frac{4\sqrt{3}}{2}, -3 \cdot \frac{1}{2}, 5\right)$$

Tangent line

$$l(t) = \left(2, -\frac{3\sqrt{3}}{2}, \frac{5\pi}{3}\right) + \left(t - \frac{\pi}{3}\right) \left(-2\sqrt{3}, -\frac{3}{2}, 5\right)$$