

22M:33

Discussion of “Normal Equations:
Approximate solution of an overdetermined system of linear
equations

J. Simon *

May 30, 2006

Suppose you are trying to solve a system of linear equations such as

$$\begin{aligned}2x + 3y &= 4 \\ x - y &= 5 \\ x + 2y &= 1 \\ -3x + 4y &= 7\end{aligned}$$

Even though there are more equations than unknowns, we might still hope there exist solutions. We can form the augmented coefficient matrix, and row-reduce it. In this case,

$$A = \begin{bmatrix} 2 & 3 & 4 \\ 1 & -1 & 5 \\ 1 & 2 & 1 \\ -3 & 4 & 7 \end{bmatrix} \implies rref(A) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}.$$

The third row of $rref(A)$ says “zero equals 1”, which tells us that the system has no solution.

Let’s look at the problem stated in terms of vectors. We seek coefficients $\{x, y\}$ such that

$$x \begin{bmatrix} 2 \\ 1 \\ 1 \\ -3 \end{bmatrix} + y \begin{bmatrix} 3 \\ -1 \\ 2 \\ 4 \end{bmatrix} = \begin{bmatrix} 4 \\ 5 \\ 1 \\ 7 \end{bmatrix}.$$

The desired output vector $[4, 5, 1, 7]^T$ does not lie in the span of the two vectors on the left side; that is the same thing as saying that there are no values for x and y to solve the system.

IF we cannot find a linear combination of $[2, 1, 1, -3]^T$ and $[3, -1, 2, 4]^T$ that exactly equals the one on the right, we can try to *find a linear combination that is as close as possible to the one on the right*.

We do this by finding the projection of $[4, 5, 1, 7]^T$ into the subspace \mathcal{U} of \mathbb{R}^4 spanned by $[2, 1, 1, -3]^T$ and $[3, -1, 2, 4]^T$.

* ©2006, all rights reserved

Here is how to find that projection (without going through the complicated process of making the basis orthonormal). We are going to pretend we have the projection (as a linear combination of the two column vectors that span \mathcal{U}) and find equations that the coefficients have to satisfy, then use those equations to find the coefficients.

The projection vector $\mathbf{p} = Proj_{\mathcal{U}}(\mathbf{v})$ is a some linear combination of the basis vectors for \mathcal{U} , that is

$$\mathbf{p} = x \begin{bmatrix} 2 \\ 1 \\ 1 \\ -3 \end{bmatrix} + y \begin{bmatrix} 3 \\ -1 \\ 2 \\ 4 \end{bmatrix},$$

where x and y are coefficients we want to find. Note that

$$\mathbf{p} = M \begin{bmatrix} x \\ y \end{bmatrix}. \tag{1}$$

Let $\mathbf{n} = \mathbf{v} - \mathbf{p}$. We have observed before that if we subtract from \mathbf{v} its projection to some subspace, then what is left is orthogonal to that subspace. So \mathbf{n} is orthogonal to both columns of the matrix

$$M = \begin{bmatrix} 2 & 3 \\ 1 & -1 \\ 1 & 2 \\ -3 & 4 \end{bmatrix}.$$

We can say the same thing in terms of the transpose of M , and then do some manipulations of the matrix equation:

$$\begin{aligned} \begin{bmatrix} 2 & 1 & 1 & -3 \\ 3 & -1 & 2 & 4 \end{bmatrix} (\mathbf{v} - \mathbf{p}) &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ \implies M^T \mathbf{v} &= M^T \mathbf{p} \\ \implies (\text{using equation ??}) M^T \mathbf{v} &= M^T M \begin{bmatrix} x \\ y \end{bmatrix}. \end{aligned}$$

So there we have our approach: We cannot solve the system

$$M \begin{bmatrix} x \\ y \end{bmatrix} = \mathbf{v},$$

instead we solve the so-called “normal system” associated with the given system

$$M^T M \begin{bmatrix} x \\ y \end{bmatrix} = M^T \mathbf{v}.$$

[End of handout]