

Ch 2 partial review:

Recall W is a subspace of R^n (vector space) if W is closed under scalar multiplication and vector addition.

I.e., W is a subspace of R^n if

$$\mathbf{v}_1, \mathbf{v}_2 \text{ in } W \text{ implies } \underline{c_1 \mathbf{v}_1} \oplus \underline{c_2 \mathbf{v}_2} \text{ in } W.$$

*closed under
linear combinations*

Note if W is a finite dimensional subspace, ~~then~~ for some vectors $\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_k$ in W : *iff*

$$W = \underline{\text{span}\{\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_k\}}$$

$$= \{c_1 \mathbf{w}_1 + c_2 \mathbf{w}_2 + \dots + c_k \mathbf{w}_k \mid c_i \in R\}$$

= the set of all linear combinations of the vectors
 $\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_k$.

Examples:

$$= \text{span}\{\mathbf{a}_1, \dots, \mathbf{a}_n\}$$

The column space of $A = [\mathbf{a}_1 \ \mathbf{a}_2 \ \dots \ \mathbf{a}_n]$

$$= \{c_1 \mathbf{a}_1 + c_2 \mathbf{a}_2 + \dots + c_n \mathbf{a}_n \mid c_i \in R\}$$

$$= \{\mathbf{b} \mid \mathbf{Ax} = \mathbf{b} \text{ has } \underline{\text{at least one}} \text{ solution}\}$$

is a subspace.

$$[\vec{a}_1 \ \dots \ \vec{a}_n] \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix} = \vec{b} \text{ in col } A$$

Nullspace of $A =$ solution set of $Ax = \mathbf{0}$ is a subspace:

If $\mathbf{v}_1, \mathbf{v}_2$ are solutions to $Ax = \mathbf{0}$, then $c_1\mathbf{v}_1 + c_2\mathbf{v}_2$ is also a solution:

$$A(c_1\vec{v}_1 + c_2\vec{v}_2) = A(c_1\vec{v}_1) + A(c_2\vec{v}_2) \\ = c_1 \underbrace{A\vec{v}_1}_{\mathbf{0}} + c_2 \underbrace{A\vec{v}_2}_{\mathbf{0}} = \mathbf{0}$$

The solution set of $Ax = \mathbf{b}$ is NOT a subspace unless $\mathbf{b} = \mathbf{0}$:

NOTE $\mathbf{0}$ is not in sol'n set so sol'n set to $Ax = \mathbf{b} \neq \mathbf{0}$ is NOT a SUBSPACE

If $\mathbf{v}_1, \mathbf{v}_2$ are solutions to $Ax = \mathbf{b}$, then $c_1\mathbf{v}_1 + c_2\mathbf{v}_2$ is a solution to

$$A(c_1\vec{v}_1 + c_2\vec{v}_2) = c_1 A\vec{v}_1 + c_2 A\vec{v}_2$$

$$\text{The sol'n set to } \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} \vec{x} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \\ = c_1 \vec{b} + c_2 \vec{b} = (c_1 + c_2) \vec{b} \neq \vec{b} \text{ unless } \vec{b} = \mathbf{0} \text{ or } c_1 + c_2 = 1$$

$$\Rightarrow \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -2x_2 + 1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix} x_2 + \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

Note $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ is a sol'n to $\begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} \vec{x} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$
 $\begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 3 \\ 0 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \end{bmatrix} \neq \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ so $3 \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ is not a sol'n

Ch 5: The eigenspace corresponding to an eigenvalue λ is a subspace.

Thus sol'n set to $\begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} \vec{x} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ is NOT a subspace

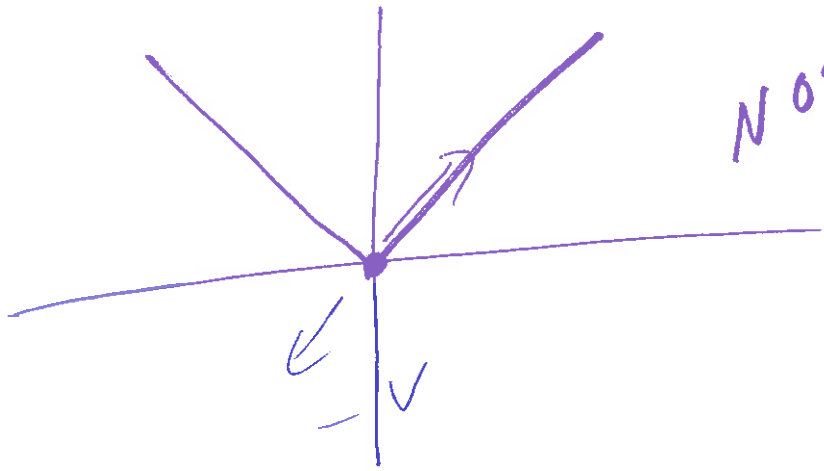
Claim the sol'n set
to $\begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ is
NOT A SUBSPACE

$\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ is in the sol'n set
since $\begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

But $0 \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ is not
in the sol'n set since

$$\begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \neq \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

Thus sol'n set to $\begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} \bar{x} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$
is NOT a subspace



NOT
A SUBSPACE

Defn: Let W be a subspace of R^k . A set \mathcal{T} is a basis for W if

i.) \mathcal{T} is linearly independent and

ii.) \mathcal{T} spans W .

small enough
large enough
goldilocks

I.e.,

\mathcal{T} is the smallest collections of vectors that span W .

Basis thm: Let W be a p -dimensional subspace of R^n .

i.) If $W = \text{span}\{w_1, \dots, w_p\}$, then $\{w_1, \dots, w_p\}$ is a basis for W .

ii.) If v_1, \dots, v_p are linearly independent vectors in W , then $\{v_1, \dots, v_p\}$ is a basis for W .

Thm: All basis for a finite-dimensional vector space have the same number of elements.

Defn:

$\dim(V)$ = the **dimension** of a finite-dim vector sp V
= the number of vectors in any basis for V .

If $\dim(V) = n$, then V is said to be n -dimensional.

rank A = Rank of a matrix A = dimension of Col A
= number of pivot columns of A .

nullity of A = dimension of Nul A

$AX = 0$

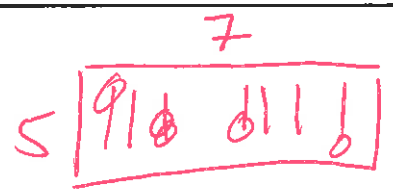
= number of free variables.

$\text{Rank}(A) + \text{nullity}(A) = \text{Number of columns of } A.$

That is,

The number of pivots of A + The number of free variables of A = The number of columns of A

Ex. 1) Suppose A is a 5×7 matrix.



If $\text{Rank}(A) = 4$, then $\text{nullity}(A) = 7 - 4 = 3$

$Ax = \mathbf{0}$ has infinite # of solutions.

$Ax = \mathbf{b}$ has no soln of ∞ # of solutions. $\begin{matrix} \cdot & \cdot & \cdot \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{matrix}$

If $\text{Rank}(A) = 5$, then $\text{nullity}(A) = 7 - 5 = 2$

$Ax = \mathbf{0}$ has ∞ # of solutions.

$Ax = \mathbf{b}$ has ∞ # of solutions. $\begin{matrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{matrix}$

If $\text{Rank}(A) = 5$, the column space of $A = \mathbb{R}^5$

$\text{col } A$ is a 5-dim subspace of \mathbb{R}^5 .

Thm 8': If A is a **SQUARE** $n \times n$ matrix, then the following are equivalent.

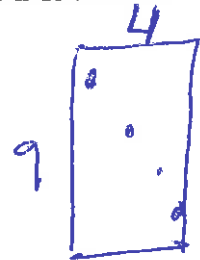
- a.) A is invertible.
- b.) The row-reduced echelon form of A is I_n , the identity matrix.
- c.) An echelon form of A has n leading entries [I.e., every column of an echelon form of A is a leading entry column – no free variables]. (A square $\Rightarrow A$ has leading entry in every column if and only if A has leading entry in every row).
- d.) The column vectors of A are linearly independent.
- e.) $Ax = 0$ has only the trivial solution.
- f.) $Ax = b$ has at most one sol'n for any b .
- g.) $Ax = b$ has a unique sol'n for any b .
- h.) $Ax = b$ is consistent for every $n \times 1$ matrix b .
- i.) $Ax = b$ has at least one sol'n for any b .
- j.) The column vectors of A span R^n . [every vector in R^n can be written as a linear combination of the columns of A].
- k.) There is a square matrix C such that $CA = I$.
- l.) There is a square matrix D such that $AD = I$.
- m.) A^T is invertible.
- n.) A is expressible as a product of elementary matrices.

- o.) The column vectors of A form a basis for R^n .
 [every vector in R^n can be written uniquely as a linear combination of the columns of A].
- p.) $\text{Col } A = R^n$.
- q.) $\dim \text{Col } A = n$.
- r.) $\text{rank of } A = n$.
- s.) $\text{Nul } A = \{0\}$, ✓
- t.) $\dim \text{Nul } A = 0$. ✓
- u.) A has nullity 0. ✓
- no free variables*
- pivot in every row*
- pivot in every column*
-

Rank(A) + nullity(A) = Number of columns of A .

Ex. 2) Suppose A is a 9×4 matrix.

If $\text{Rank}(A) = 4$, then $\text{nullity}(A) = 4 - 4 = 0$



$Ax = 0$ has unique solutions.

$Ax = b$ has at most one solutions.
none or one

If $\text{Rank}(A) = 3$, then $\text{nullity}(A) = 4 - 3 = 1$

$Ax = 0$ has ∞ # of solutions.

$Ax = b$ has no soln of ∞ # of solutions.

A is a 9×4 matrix

$$\text{RANK}(A) = 4$$

row equiv

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

column space is a 4-dim subspace of \mathbb{R}^9

Nulspace is a 0 -dim subspace \mathbb{R}^4

$$= \left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right\}$$



3.3: Cramer's Rule, Adjoint, Inverses, Area

Defn: Let $A_i(\mathbf{b})$ = the matrix derived from A by replacing the i^{th} column of A with \mathbf{b} .

Cramer's Rule: Suppose $A\mathbf{x} = \mathbf{b}$ where A is an $n \times n$ matrix such that $\det A \neq 0$. Then

$$x_i = \frac{\det A_i(\mathbf{b})}{\det A}.$$

Solve the following using Cramer's rule:

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 5 \\ 6 \end{bmatrix}$$

$$\det \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = (1)(4) - (3)(2) = 4 - 6 = -2$$

$$\det \begin{bmatrix} 5 & 2 \\ 6 & 4 \end{bmatrix} = (5)(4) - (6)(2) = 20 - 12 = 8$$

$$\det \begin{bmatrix} 1 & 5 \\ 3 & 6 \end{bmatrix} = (1)(6) - (3)(5) = 6 - 15 = -9$$

$$\text{Thus } x_1 = \frac{8}{-2} = -4, \quad x_2 = \frac{-9}{-2} = \frac{9}{2}.$$

Solve $\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{pmatrix} 5 \\ 6 \end{pmatrix}$

$$\begin{vmatrix} 1 & 2 \\ 3 & 4 \end{vmatrix} = 4 - 6 = -2$$

$$\begin{vmatrix} 5 & 2 \\ 6 & 4 \end{vmatrix} = 20 - 12 = 8$$

$$\begin{vmatrix} 1 & 5 \\ 3 & 6 \end{vmatrix} = 6 - 15 = -9$$

$$x_1 = \frac{8}{-2} = -4$$

$$x_2 = \frac{-9}{-2} = \frac{9}{2}$$

If $A\vec{x} = \vec{b}$

Observe for 2×2 case:

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x_1 & 0 \\ x_2 & 1 \end{bmatrix} = \begin{bmatrix} a_{11}x_1 + a_{12}x_2 & a_{12} \\ a_{21}x_1 + a_{22}x_2 & a_{22} \end{bmatrix}$$

$Ax = b$

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x_1 & 0 \\ x_2 & 1 \end{bmatrix} = \begin{bmatrix} b_1 & a_{12} \\ b_2 & a_{22} \end{bmatrix}$$

$$\begin{bmatrix} x_1 & 0 \\ x_2 & 1 \end{bmatrix}$$

$$AI_1(\mathbf{x}) = A_1(\mathbf{b})$$

$$\det(AI_1(\mathbf{x})) = \det(A_1(\mathbf{b}))$$

$$\det(A) \det(I_1(\mathbf{x})) = \det(A_1(\mathbf{b}))$$

$$\det(A) x_1 = \det(A_1(\mathbf{b}))$$

$$\text{Thus } x_1 = \frac{\det(A_1(\mathbf{b}))}{\det(A)}$$

Let $\vec{e}_i = \begin{bmatrix} 0 \\ \vdots \\ 1 \text{ in } i\text{th spot} \\ \vdots \\ 0 \end{bmatrix}$

$$\begin{bmatrix} 1 & x_1 & 0 \\ 0 & x_2 & 1 \end{bmatrix}$$

$$I_j(\mathbf{x}) = [\vec{e}_1 \ \vec{e}_2 \ \dots \ \vec{e}_n]$$

$$AI_j(\mathbf{x}) = [A\vec{e}_1 \ \dots \ A\vec{e}_{j-1} \ Ax \ A\vec{e}_{j+1} \ \dots \ A\vec{e}_n] = A_j(\mathbf{b})$$

$$[\vec{a}_1 \ \dots \ \vec{a}_{j-1} \ \vec{b} \ \vec{a}_{j+1} \ \dots \ \vec{a}_n] = A_j(\mathbf{b})$$

Solve the following using Cramer's rule:

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 10 & 0 \\ 5 & 0 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

~~$$\begin{vmatrix} 1 & 2 & 3 & 1 & 2 \\ 4 & 10 & 0 & 4 & 10 \\ 5 & 0 & 6 & 5 & 0 \end{vmatrix} = 60 + 0 + 0 - 150 - 0 - 48 = 60 - 198 = -138$$~~

$$\left[\begin{array}{ccc|c} 0 & 2 & 3 & 0 \\ 0 & 10 & 0 & 0 \\ 0 & 0 & 6 & 0 \end{array} \right]$$

$$\left[\begin{array}{c|c} 0 & \\ 0 & \\ 0 & \end{array} \right]$$

$$\left[\begin{array}{c|c} 0 & \\ 0 & \\ 0 & \end{array} \right]$$