

[18] 1.) Find the characteristic equation and diagonalize $A = \begin{bmatrix} -2 & 6 \\ 6 & -18 \end{bmatrix}$

NOTE: A is clearly not invertible (since $\det(A) = 0$ or equivalently columns are linearly dependent or equivalently (since A square) rows or linearly dependent). Thus 0 is an eigenvalue of A.

$Ax = 0$
 $A^T x = 0$

Find eigenvalues:

$$\det(A - \lambda I) = \begin{vmatrix} -2 - \lambda & 6 \\ 6 & -18 - \lambda \end{vmatrix} = (-2 - \lambda)(-18 - \lambda) - 36 = 36 + 20\lambda + \lambda^2 - 36 = \lambda^2 + 20\lambda = \lambda(\lambda + 20) = 0$$

Characteristic equation of A = $\lambda(\lambda + 20) = 0$.

Find eigenvectors:

$$\lambda = 0: \begin{bmatrix} -2 & 6 \\ 6 & -18 \end{bmatrix} \sim \begin{bmatrix} 1 & -3 \\ 0 & 0 \end{bmatrix} \text{ implies } \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3x_2 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \end{bmatrix} x_2$$

$$\text{Check: } \begin{bmatrix} -2 & 6 \\ 6 & -18 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} = 0 \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

$$\lambda = -20: \begin{bmatrix} 18 & 6 \\ 6 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & \frac{1}{3} \\ 0 & 0 \end{bmatrix} \text{ implies } \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -\frac{1}{3}x_2 \\ x_2 \end{bmatrix} = \begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix} x_2.$$

Thus $\begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix}$ is an e. vector of A. Hence $\begin{bmatrix} -1 \\ 3 \end{bmatrix}$ is also an e-vector of A.

$$\text{Check: } \begin{bmatrix} -2 & 6 \\ 6 & -18 \end{bmatrix} \begin{bmatrix} -1 \\ 3 \end{bmatrix} = \begin{bmatrix} 20 \\ -60 \end{bmatrix} = -20 \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$

$$\det P = 9 + 1 = 10$$

$$P = \begin{bmatrix} 3 & -1 \\ 1 & 3 \end{bmatrix} \quad D = \begin{bmatrix} 0 & 0 \\ 0 & -20 \end{bmatrix} \quad P^{-1} = \begin{bmatrix} \frac{3}{10} & \frac{1}{10} \\ -\frac{1}{10} & \frac{3}{10} \end{bmatrix}$$

$PP^{-1} = I$

Note: if you forgot the formula for P^{-1} , you could (either derive it or) notice that A is symmetric and P is orthogonal. Thus we can normalize the columns of P so that for the new orthonormal P, $P^{-1} = P^T$ (since columns of new P are orthonormal). Thus alternative answer:

$$P = \begin{bmatrix} \frac{3}{\sqrt{10}} & \frac{-1}{\sqrt{10}} \\ \frac{1}{\sqrt{10}} & \frac{3}{\sqrt{10}} \end{bmatrix} \quad D = \begin{bmatrix} 0 & 0 \\ 0 & -20 \end{bmatrix} \quad P^{-1} = \begin{bmatrix} \frac{3}{\sqrt{10}} & \frac{1}{\sqrt{10}} \\ -\frac{1}{\sqrt{10}} & \frac{3}{\sqrt{10}} \end{bmatrix}$$

A sym \Rightarrow P orthog e. vectors from different e. space are \perp

[16] 2.) Use Gram-Schmidt to find the QR factorization of $M = \begin{bmatrix} 6 & 3 \\ 6 & 0 \\ 3 & 3 \end{bmatrix}$.

Note one can work with scaled vectors to find Q (think of the pictures relating to orthogonal projection and orthogonal component), but not R . For those not comfortable with scaling, we will work with the vectors as given.

$$\begin{bmatrix} 6 \\ 6 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 6 \\ 6 \\ 3 \end{bmatrix} = 36 + 36 + 9 = 81$$

$$\begin{bmatrix} 6 \\ 6 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 3 \\ 0 \\ 3 \end{bmatrix} = 18 + 0 + 9 = 27$$

$$\text{proj} \begin{bmatrix} 6 \\ 6 \\ 3 \end{bmatrix} \begin{bmatrix} 3 \\ 0 \\ 3 \end{bmatrix} = \frac{27}{81} \begin{bmatrix} 6 \\ 6 \\ 3 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 6 \\ 6 \\ 3 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}$$

$$\text{Orthogonal component} = \begin{bmatrix} 3 \\ 0 \\ 3 \end{bmatrix} - \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ 2 \end{bmatrix}$$

$$\text{Normalize: length of } \begin{bmatrix} 6 \\ 6 \\ 3 \end{bmatrix} = \sqrt{81} = 9$$

$$\text{length of } \begin{bmatrix} 1 \\ -2 \\ 2 \end{bmatrix} = \sqrt{1+4+4} = 3$$

$$\text{Thus } Q = \begin{bmatrix} \frac{6}{9} & \frac{1}{3} \\ \frac{6}{9} & -\frac{2}{3} \\ \frac{3}{9} & \frac{2}{3} \end{bmatrix} = \begin{bmatrix} \frac{2}{3} & \frac{1}{3} \\ \frac{2}{3} & -\frac{2}{3} \\ \frac{1}{3} & \frac{2}{3} \end{bmatrix}$$

$$M = QR \text{ implies } Q^T M = Q^T QR = R$$

$$\text{Thus } R = Q^T M = \begin{bmatrix} \frac{2}{3} & \frac{2}{3} & \frac{1}{3} \\ \frac{1}{3} & -\frac{2}{3} & \frac{2}{3} \end{bmatrix} \begin{bmatrix} 6 & 3 \\ 6 & 0 \\ 3 & 3 \end{bmatrix} = \begin{bmatrix} 4+4+1 & 2+0+1 \\ 2-4+2 & 1-0+2 \end{bmatrix} = \begin{bmatrix} 9 & 3 \\ 0 & 3 \end{bmatrix}$$

NOTE: Columns of Q are orthonormal and R is upper triangular.

$$Q = \begin{bmatrix} \frac{2}{3} & \frac{1}{3} \\ \frac{2}{3} & -\frac{2}{3} \\ \frac{1}{3} & \frac{2}{3} \end{bmatrix} \quad R = \begin{bmatrix} 9 & 3 \\ 0 & 3 \end{bmatrix}$$

 perpendicular

1. (1 pt) local/Library/UI/Fall14/quiz2.9.pg

Suppose A is an invertible $n \times n$ matrix and v is an eigenvector of A with associated eigenvalue -5 . Convince yourself that v is an eigenvector of the following matrices, and find the associated eigenvalues:

1. A^8 , eigenvalue =

- A. 16
- B. 81
- C. 125
- D. 216
- E. 1024
- F. 390625
- G. 2000
- H. None of those above

2. A^{-1} , eigenvalue =

- A. -0.5
- B. -0.333
- C. -0.2
- D. -0.125
- E. 0
- F. 0.125
- G. 0.333
- H. 0.5
- I. None of those above

3. $A - 4I_n$, eigenvalue =

- A. -8
- B. -4
- C. -5
- D. 0
- E. 2
- F. 4
- G. -9
- H. 10
- I. None of those above

4. $8A$, eigenvalue =

- A. -36
- B. -28
- C. -40
- D. -12
- E. 0

$$\begin{aligned}
 A\vec{v} &= \lambda\vec{v} \\
 A^2\vec{v} &= A(A\vec{v}) \\
 &= A(\lambda\vec{v}) \\
 &= \lambda(A\vec{v}) \\
 &= \lambda(\lambda\vec{v}) \\
 &= \lambda^2\vec{v} \\
 &\vdots \\
 A^8\vec{v} &= \lambda^8\vec{v}
 \end{aligned}$$

$$\begin{aligned}
 (A - 4I_n)\vec{v} &= A\vec{v} - 4I_n\vec{v} \\
 &= \lambda\vec{v} - 4\vec{v} \\
 &= (\lambda - 4)\vec{v}
 \end{aligned}$$

- F. 24
- G. 36
- H. None of those above

2. (1 pt) local/Library/UI/Fall14/quiz2.10.pg

If $v_1 = \begin{bmatrix} 5 \\ -5 \end{bmatrix}$ and $v_2 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

are eigenvectors of a matrix A corresponding to the eigenvalues $\lambda_1 = -2$ and $\lambda_2 = 4$, respectively, then

a. $A(v_1 + v_2) =$

- A. $\begin{bmatrix} -3 \\ 5 \\ -2 \\ 4 \\ -6 \\ 5 \end{bmatrix}$
- B. $\begin{bmatrix} 10 \\ 6 \\ 12 \\ 4 \\ -6 \\ 10 \end{bmatrix}$
- C. $\begin{bmatrix} 10 \\ 6 \\ 12 \\ 4 \\ -6 \\ 10 \end{bmatrix}$
- D. $\begin{bmatrix} 10 \\ 6 \\ 12 \\ 4 \\ -6 \\ 10 \end{bmatrix}$
- E. $\begin{bmatrix} 10 \\ 6 \\ 12 \\ 4 \\ -6 \\ 10 \end{bmatrix}$
- F. $\begin{bmatrix} 10 \\ 6 \\ 12 \\ 4 \\ -6 \\ 10 \end{bmatrix}$
- G. None of those above

$$A\vec{v}_1 + A\vec{v}_2$$

b. $A(-3v_1) =$

- A. $\begin{bmatrix} -12 \\ -12 \\ -2 \\ 8 \\ -6 \\ 4 \end{bmatrix}$
- B. $\begin{bmatrix} -12 \\ -12 \\ -2 \\ 8 \\ -6 \\ 4 \end{bmatrix}$
- C. $\begin{bmatrix} -12 \\ -12 \\ -2 \\ 8 \\ -6 \\ 4 \end{bmatrix}$
- D. $\begin{bmatrix} 10 \\ 6 \\ 12 \\ 4 \\ -6 \\ 10 \end{bmatrix}$
- E. $\begin{bmatrix} 10 \\ 6 \\ 12 \\ 4 \\ -6 \\ 10 \end{bmatrix}$
- F. $\begin{bmatrix} 10 \\ 6 \\ 12 \\ 4 \\ -6 \\ 10 \end{bmatrix}$
- G. $\begin{bmatrix} 10 \\ 6 \\ 12 \\ 4 \\ -6 \\ 10 \end{bmatrix}$
- H. None of those above

Problem 1. 1. (1 pt) Library/TCNJ/TCNJ_MatrixEquations-
/problem4.pg

$$\text{Let } A = \begin{bmatrix} -5 & 1 & 3 \\ -3 & 3 & 5 \\ 2 & 4 & -2 \end{bmatrix} \text{ and } x = \begin{bmatrix} -4 \\ -5 \\ 3 \end{bmatrix}.$$

1. What does Ax mean?

Problem 2. 2. (1 pt) local/Library/UI/Fall14/HW7.12.pg

Suppose that A is a 5×9 matrix which has a null space of dimension 6. The rank of A =

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. none of the above

Problem 3. 3. (1 pt) Library/WHFreeman/Holt_linear_algebra-
/Chaps.1-4/2.3.42.pg

Let A be a matrix with more columns than rows.
Select the best statement.

- A. The columns of A are linearly independent, as long as no column is a scalar multiple of another column in A
- B. The columns of A are linearly independent, as long as they does not include the zero vector.
- C. The columns of A could be either linearly dependent or linearly independent depending on the case.
- D. The columns of A must be linearly dependent.
- E. none of the above

Problem 4. Suppose $A\vec{x} = \vec{0}$ has an infinite number of solutions, then given a vector \vec{b} of the appropriate dimension, $A\vec{x} = \vec{b}$ has

- A. No solution
- B. Unique solution
- C. Infinitely many solutions
- D. at most one solution

- E. either no solution or an infinite number of solutions
- F. either a unique solution or an infinite number of solutions
- G. no solution, a unique solution or an infinite number of solutions, depending on the system of equations
- H. none of the above

Problem 5. Suppose A is a square matrix and $A\vec{x} = \vec{0}$ has an infinite number of solutions, then given a vector \vec{b} of the appropriate dimension, $A\vec{x} = \vec{b}$ has

- A. No solution
- B. Unique solution
- C. Infinitely many solutions
- D. at most one solution
- E. either no solution or an infinite number of solutions
- F. either a unique solution or an infinite number of solutions
- G. no solution, a unique solution or an infinite number of solutions, depending on the system of equations
- H. none of the above

Problem 6. The vector \vec{b} is in $ColA$ if and only if $A\vec{v} = \vec{b}$ has a solution

- A. True
- B. False

Problem 7. The vector \vec{v} is in $NulA$ if and only if $A\vec{v} = \vec{0}$

- A. True
- B. False

Problem 8. If \vec{x}_1 and \vec{x}_2 are solutions to $A\vec{x} = \vec{0}$, then $-2\vec{x}_1 + 2\vec{x}_2$ is also a solution to $A\vec{x} = \vec{0}$.

- A. True
- B. False

Problem 9. If \vec{x}_1 and \vec{x}_2 are solutions to $A\vec{x} = \vec{b}$, then $-7\vec{x}_1 + 3\vec{x}_2$ is also a solution to $A\vec{x} = \vec{b}$.

- A. True
- B. False

$$A\vec{x}_1 = \vec{b} \quad A\vec{x}_2 = \vec{b}$$

$$\begin{aligned} A(-7\vec{x}_1 + 3\vec{x}_2) &= -7A\vec{x}_1 + 3A\vec{x}_2 \\ &= -7\vec{b} + 3\vec{b} = 4\vec{b} \\ &\neq \vec{b} \end{aligned}$$

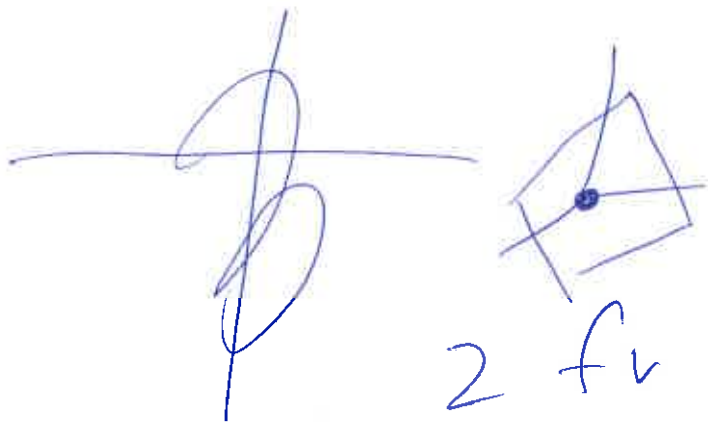
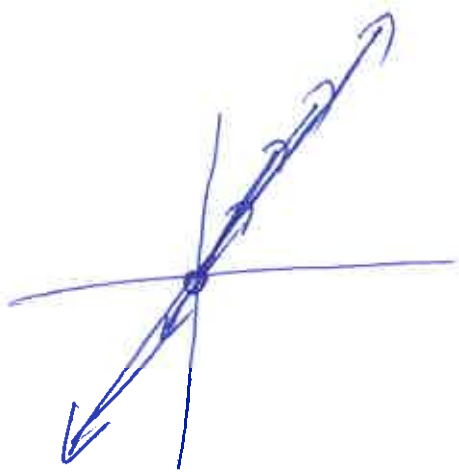
Homog Egn

$$A\vec{x} = \vec{0}$$

suppose \rightarrow

v_i are sol'n to $A\vec{x} = \vec{0}$

$\Rightarrow \sum c_i \vec{v}_i$ is also a sol'n to $A\vec{x} = \vec{0}$



1 free variable

Non homog egn

$$A\vec{x} = \vec{b}, \vec{b} \neq \vec{0}$$

If $\sum c_i \vec{v}_i$ is the general sol'n to homog egn $A\vec{x} = \vec{0}$

and \vec{u} is a sol'n to non homog $A\vec{x} = \vec{b}$

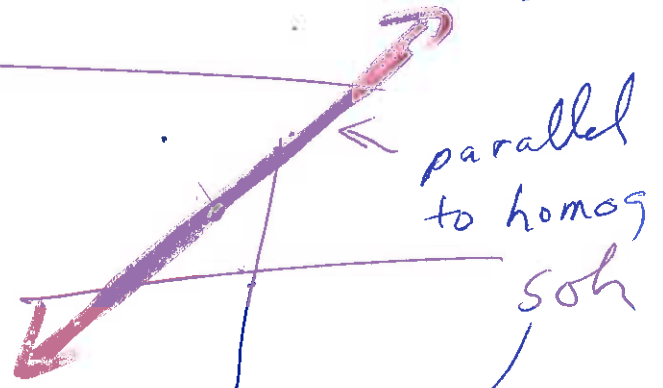
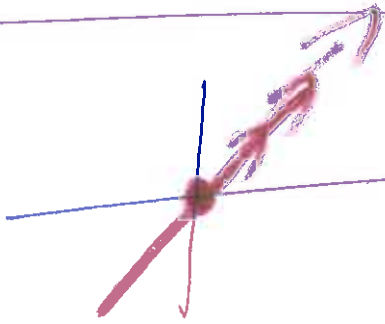
\Rightarrow General sol'n to $A\vec{x} = \vec{b}$

$$\vec{u} + \left(\sum c_i \vec{v}_i \right)$$

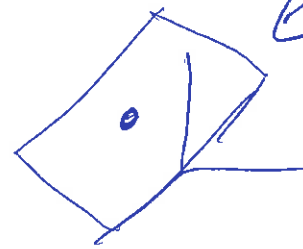
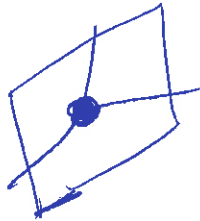
homog

non homog

1 free var



2 free var



homog

non homog

parallel copy

$$\sum_{i=1}^k c_i v_i \longrightarrow \vec{u} + \sum_{i=1}^k c_i \vec{v}_i$$

k free variables

$A^{-1}Ax = A^{-1}b \Rightarrow \vec{x} = A^{-1}\vec{b}$

solve using invers | solve using Cramer's Rule

1 or solve using REF

Thm 8': If A is a **SQUARE** $n \times n$ matrix, then the following are equivalent.

- a.) A is invertible. $\det A \neq 0$
- b.) The row-reduced echelon form of A is I_n , the identity matrix.
- c.) An echelon form of A has n leading entries [I.e., every column of an echelon form of A is a leading entry column - no free variables]. (A square $\Rightarrow A$ has leading entry in every column if and only if A has leading entry in every row).
- d.) The column vectors of A are linearly independent.
- e.) $Ax = 0$ has only the trivial solution.
- f.) $Ax = b$ has at most one sol'n for any b .
- g.) $Ax = b$ has a unique sol'n for any b .
- h.) $Ax = b$ is consistent for every $n \times 1$ matrix b .
- i.) $Ax = b$ has at least one sol'n for any b .
- j.) The column vectors of A span R^n . [every vector in R^n can be written as a linear combination of the columns of A].
- k.) There is a square matrix C such that $CA = I$.
- l.) There is a square matrix D such that $AD = I$.
- m.) A^T is invertible.
- n.) A is expressible as a product of elementary matrices.
- o.) The column vectors of A form a basis for R^n . [every vector in R^n can be written uniquely as a linear combination of the columns of A].
- p.) $\text{Col } A = R^n$
- q.) $\dim \text{Col } A = n$.
- r.) rank of $A = n$.
- s.) $\text{Nul } A = \{0\}$,
- t.) $\dim \text{Nul } A = 0$.
- u.) A has nullity 0.
- v.) $\lambda = 0$ is NOT an eigenvalue of A

No free variables

all columns are pivot columns

SQUARE

SQUARE

every row is a pivot row

no row of all zero's in EF

of free variable

EX: $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ or $\begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$

3.3: Cramer's Rule, Adjoint, Inverses, Area

Defn: Let $A_i(\mathbf{b})$ = the matrix derived from A by replacing the i^{th} column of A with \mathbf{b} .

Cramer's Rule: Suppose $A\mathbf{x} = \mathbf{b}$ where A is an $n \times n$ matrix such that $\det A \neq 0$. Then

$$x_i = \frac{\det A_i(\mathbf{b})}{\det A}$$

unique solution

Solve the following using Cramer's rule:

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 5 \\ 6 \end{bmatrix}$$

$$\det \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = (1)(4) - (3)(2) = 4 - 6 = -2 = \det A$$

$$\det \begin{bmatrix} 5 & 2 \\ 6 & 4 \end{bmatrix} = (5)(4) - (6)(2) = 20 - 12 = 8 = \det A_1(\mathbf{b})$$

$$\det \begin{bmatrix} 1 & 5 \\ 3 & 6 \end{bmatrix} = (1)(6) - (3)(5) = 6 - 15 = -9 = \det A_2(\mathbf{b})$$

Thus $x_1 = \frac{8}{-2} = -4$, $x_2 = \frac{-9}{-2} = \frac{9}{2}$.

Defn: For a square matrix A , the (classical) **adjoint** of A is the matrix

$$\text{Adj} A = [c_{ij}], \text{ where } c_{ij} = (-1)^{i+j} \det A_{ji}.$$

In other words, the ij^{th} entry of $\text{Adj} A$ is the ji^{th} cofactor of A .

Find the adjoint of $\begin{bmatrix} 1 & 2 & 3 \\ 4 & 10 & 0 \\ 5 & 0 & 6 \end{bmatrix}$

$$x_1 = \frac{\det A_1 \begin{bmatrix} 5 \\ 6 \end{bmatrix}}{\det A} = \frac{8}{-2} = -4$$

$$x_2 = \frac{\det A_2 \begin{bmatrix} 5 \\ 6 \end{bmatrix}}{\det A} = \frac{-9}{-2} = \frac{9}{2}$$

A square

A NOT invertible



$$\det A = 0$$



$\lambda = 0$ is an e. value of A



free variables



column linearly dependent



SQUARE

row of all zeros in EF



$$\text{col } A \neq \mathbb{R}^n$$



etc

$$\begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix}$$

$$\text{or } \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

↑ e.g.

EX;

$$\begin{bmatrix} 1 & * \\ 0 & 0 \end{bmatrix}$$

What if A is

NOT square

EX $\begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & 4 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 3 \\ 0 & 0 & 0 \end{bmatrix}$

or $\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$

$\text{col } A \neq \mathbb{R}^3$

$A\vec{x} = \vec{b}$ has unique sol'n

or no sol'n

1. (1 pt) Library/Rochester/setLinearAlgebra23QuadraticForms-ur Ja_23_5.pg

If $A = \begin{bmatrix} 2 & -6 & 9 \\ -6 & 6 & -5 \\ 9 & -5 & -7 \end{bmatrix}$ and $Q(x) = x \cdot Ax = x^T A x$

Then $Q(x_1, x_2, x_3) = 2x_1^2 + 6x_2^2 - 7x_3^2 - 12x_1x_2 + 18x_1x_3 - 10x_2x_3$.

2. (1 pt) Library/Rochester/setLinearAlgebra23QuadraticForms-ur Ja_23_1.pg

Write the matrix of the quadratic form $Q(x) = 9x_1^2 + 2x_2^2 - 1x_3^2 - 1x_1x_2 + 3x_1x_3 - 9x_2x_3$.

$A = \begin{bmatrix} 9 & -1/2 & 3/2 \\ -1/2 & 2 & -9/2 \\ 3/2 & -9/2 & -1 \end{bmatrix}$

3. (1 pt) Library/Rochester/setLinearAlgebra23QuadraticForms-ur Ja_23_4.pg

If $A = \begin{bmatrix} 2 & 8 \\ 8 & 3 \end{bmatrix}$ and $Q(x) = x \cdot Ax$

Then $Q(e_1) = 2$ and $Q(e_2) = 3$. Hint: $e_1 = (1, 0)$, $e_2 = (0, 1)$

4. (1 pt) Library/Rochester/setLinearAlgebra23QuadraticForms-ur Ja_23_2.pg

Find the eigenvalues of the matrix

$M = \begin{bmatrix} -55 & 5 \\ 5 & -55 \end{bmatrix}$

Enter the two eigenvalues, separated by a comma:

Classify the quadratic form $Q(x) = x^T A x$:

- A. $Q(x)$ is indefinite $> 0 \text{ \& } < 0$
- B. $Q(x)$ is negative definite > 0
- C. $Q(x)$ is positive definite < 0
- D. $Q(x)$ is positive semidefinite ≥ 0
- E. $Q(x)$ is negative semidefinite ≤ 0

5. (1 pt) Library/Rochester/setLinearAlgebra23QuadraticForms-ur Ja_23_3.pg

The matrix $A = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & 0 \\ 0 & 0 & 4 \end{bmatrix}$

has three distinct eigenvalues, $\lambda_1 < \lambda_2 < \lambda_3$,
 $\lambda_1 = \underline{\hspace{1cm}}$,
 $\lambda_2 = \underline{\hspace{1cm}}$,
 $\lambda_3 = \underline{\hspace{1cm}}$.

Classify the quadratic form $Q(x) = x^T A x$:

- A. $Q(x)$ is positive definite
- B. $Q(x)$ is positive semidefinite
- C. $Q(x)$ is indefinite
- D. $Q(x)$ is negative definite
- E. $Q(x)$ is negative semidefinite

Handwritten blue scribbles and arrows pointing to the right.

7.2

$$[x_1 \ x_2 \ x_3] \begin{bmatrix} 2 & -6 & 9 \\ -6 & 6 & -5 \\ 9 & -5 & -7 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$[x_1 \ x_2 \ x_3] \begin{bmatrix} 2x_1 - 6x_2 + 9x_3 \\ -6x_1 + 6x_2 - 5x_3 \\ 9x_1 - 5x_2 - 7x_3 \end{bmatrix}$$

$$= \underline{2x_1^2} - 6x_1x_2 + 9x_1x_3 + \underline{6x_2^2} - 6x_1x_2 - 5x_2x_3 - \underline{7x_3^2} + 9x_1x_3 - 5x_2x_3$$

$$2x_1^2 + 6x_2^2 - 7x_3^2 - 12x_1x_2 + 18x_1x_3 - 10x_2x_3$$

7.2

$$[x_1 \ x_2 \ x_3] \begin{bmatrix} 3 & 2 & 1 \\ 2 & 4 & 6 \\ 1 & 6 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = Q(x_1, x_2, x_3)$$

$$Q(x_1, x_2, x_3) = [x_1 \ x_2 \ x_3] \begin{bmatrix} 3x_1 + 2x_2 + 1x_3 \\ 2x_1 + 4x_2 + 6x_3 \\ x_1 + 6x_2 + 5x_3 \end{bmatrix}$$

$$= 3x_1^2 + 2x_1x_2 + x_1x_3$$

$$4x_2^2 + 2x_1x_2 + 6x_2x_3$$

$$5x_3^2 + x_1x_3 + 6x_2x_3$$

$$3x_1^2 + 4x_2^2 + 5x_3^2 + 4x_1x_2 + 2x_1x_3 + 12x_2x_3$$

$$= Q(x_1, x_2, x_3)$$

$$Q(x_1, x_2, x_3) = 5x_1^2 + 6x_2^2 + 3x_3^2 + 7x_1x_2 + 8x_1x_3$$

$$= x^T \begin{pmatrix} 5 & 7/2 & 8/2 \\ 7/2 & 6 & 0/2 \\ 8/2 & 0/2 & 3 \end{pmatrix} x$$

$$x^T A x$$