

1	5	6	7
5	2	8	9
6	8	3	10
7	9	10	4

A symmetric if $A = A^T$

7.1: Special case $A = A^T$
 combines ch 5 & ch 6

$A = A^T$ symmetry
 across diagonal

Example 2:

Orthogonally diagonalize $A =$

$$A = \begin{bmatrix} 1 & -1 & 1 \\ -1 & 1 & -1 \\ 1 & -1 & 1 \end{bmatrix}$$

Step 1: Find the eigenvalues of A :

ch 5

$$\det(A - \lambda I) = \begin{vmatrix} 1 - \lambda & -1 & 1 \\ -1 & 1 - \lambda & -1 \\ 1 & -1 & 1 - \lambda \end{vmatrix} = \begin{vmatrix} 1 - \lambda & -1 & 1 \\ -1 & 1 - \lambda & -1 \\ 0 & -\lambda & -\lambda \end{vmatrix}$$

$$= (1 - \lambda) \begin{vmatrix} 1 - \lambda & -1 \\ -\lambda & -\lambda \end{vmatrix} - (-1) \begin{vmatrix} -1 & 1 \\ -\lambda & -\lambda \end{vmatrix} + 0 \begin{vmatrix} -1 & 1 \\ 1 - \lambda & -1 \end{vmatrix}$$

$$= (1 - \lambda)[(1 - \lambda)(-\lambda) - \lambda] + [\lambda + \lambda]$$

$$= (1 - \lambda)(-\lambda)[(1 - \lambda) + 1] + 2\lambda = (1 - \lambda)(-\lambda)(2 - \lambda) + 2\lambda$$

Note I can factor out $-\lambda$, leaving only a quadratic to factor:

$$= -\lambda[(1 - \lambda)(2 - \lambda) - 2]$$

$$= -\lambda[\lambda^2 - 3\lambda + 2 - 2] = -\lambda[\lambda^2 - 3\lambda] = -\lambda^2[\lambda - 3]$$

Thus there are 2 eigenvalues:

$\lambda = 0$ with algebraic multiplicity 2. Since A is symmetric, geometric multiplicity = algebraic multiplicity = 2. Thus the dimension of the eigenspace corresponding to $\lambda = 0$ [$= \text{Nul}(A - 0I) = \text{Nul}(A)$] is 2.

$\lambda = 3$ w/ algebraic multiplicity = 1 = geometric multiplicity.

$A - 0I$
 2 fr
 $\Rightarrow A$ diag

1 fv

Thus we can find an orthogonal basis for R^3 where two of the basis vectors comes from the eigenspace corresponding to eigenvalue 0 while the third comes from the eigenspace corresponding to eigenvalue 3.

If not symmetric, check if diagonalizable by finding # of free variables

Do you have enough l.i e. vectors to create square P (ann $=$ gm) $g = m$ (2)

Solve $(A - 0I)x = \vec{0}$

2.) Find a basis for each of the eigenspaces:

2a.) $\lambda = 0$; $A - 0I = A = \begin{bmatrix} 1 & -1 & 1 \\ -1 & 1 & -1 \\ 1 & -1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{array}{l} 0 \\ 0 \\ 0 \end{array}$

ch 5

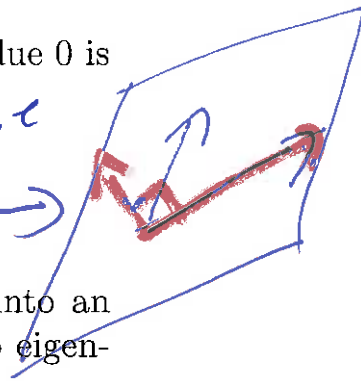
$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_2 - x_3 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

Thus a basis for eigenspace corresponding to eigenvalue 0 is

Since from same eigen value they don't have to be \perp

$$\left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\}$$

2-d plane



We can now use Gram-Schmidt to turn this basis into an orthogonal basis for the eigenspace corresponding to eigenvalue 0 or we can continue finding eigenvalues.

3a.) Create orthonormal basis using Gram-Schmidt for the eigenspace corresponding to eigenvalue 0:

ch 6

Let $v_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ and $v_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$

Step 1:

$$\text{proj}_{v_1} v_2 = \left(\frac{v_2 \cdot v_1}{v_1 \cdot v_1} \right) v_1 = \frac{-1+0+0}{1+1+0} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = -\frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ -\frac{1}{2} \\ 0 \end{bmatrix}$$



If A symmetric $\frac{1}{2}$ asked to orthog diagonalize

Step 2: The vector component of \mathbf{v}_2 orthogonal to \mathbf{v}_1 is

\perp $\mathbf{v}_2 - \text{proj}_{\mathbf{v}_1} \mathbf{v}_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} - \begin{bmatrix} -\frac{1}{2} \\ -\frac{1}{2} \\ 0 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 1 \end{bmatrix}$

Thus an orthogonal basis for the eigenspace corresponding to eigenvalue 0 is

Can check orthogonality via dot product = 0

$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 1 \end{bmatrix} = 0$

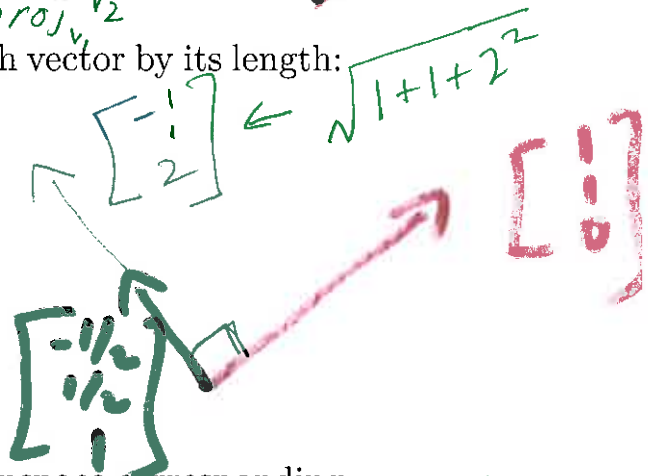
$\left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right\}$

$\mathbf{v}_1, \mathbf{v}_2 - \text{proj}_{\mathbf{v}_1} \mathbf{v}_2$

To create orthonormal basis, divide each vector by its length:

$\left\| \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right\| = \sqrt{1^2 + 1^2 + 0^2} = \sqrt{2}$

$\left\| \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right\| = \sqrt{\frac{1}{4} + \frac{1}{4} + 1} = \sqrt{\frac{3}{2}}$



Thus an orthonormal basis for the eigenspace corresponding to eigenvalue 0 is

$\left\{ \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix}, \begin{bmatrix} -\frac{\sqrt{2}}{2\sqrt{3}} \\ \frac{\sqrt{2}}{2\sqrt{3}} \\ \sqrt{\frac{2}{3}} \end{bmatrix} \right\} = \left\{ \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix}, \begin{bmatrix} -\frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{6}} \\ \sqrt{\frac{2}{3}} \end{bmatrix} \right\}$

unit length = 1

$\begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \\ 0/\sqrt{2} \end{bmatrix}$

$\begin{bmatrix} -1/2 / \sqrt{3/2} \\ 1/2 / \sqrt{3/2} \\ 1 / \sqrt{3/2} \end{bmatrix}$

$\begin{bmatrix} -1/\sqrt{6} \\ 1/\sqrt{6} \\ 2/\sqrt{6} \end{bmatrix}$



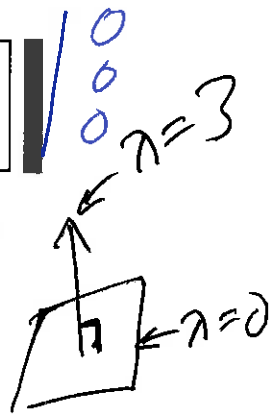
$$\text{Solve } (A - 3I)\vec{x} = 0$$

2b.) Find a basis for eigenspace corresponding to $\lambda = 3$:

$$A - 3I = \begin{bmatrix} -2 & -1 & 1 \\ -1 & -2 & -1 \\ 1 & -1 & -2 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & -2 \\ 0 & -3 & -3 \\ 0 & -3 & -3 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

Thus a basis for eigenspace corresponding to eigenvalue 3 is

$$\left\{ \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right\}$$



FYI: Alternate method to find 3rd vector: Since you have two linearly independent vectors from the eigenspace corresponding to eigenvalue 0, you only need one more vector which is orthogonal to these two to form a basis for \mathbb{R}^3 . Note since A is symmetric, any such vector will be an eigenvector of A with eigenvalue 3. Note this shortcut only works because we know what the eigenspace corresponding to eigenvalue 3 looks like: a line perpendicular to the plane representing the eigenspace corresponding to eigenvalue 0.

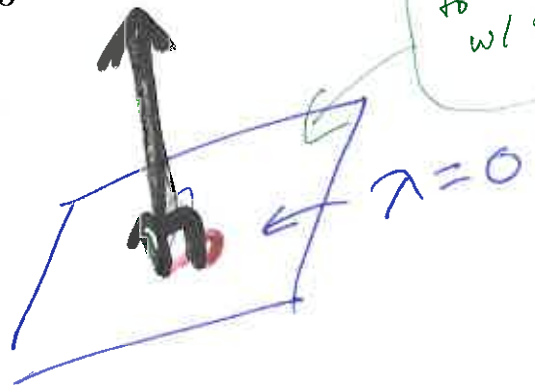
3b.) Create orthonormal basis for the eigenspace corresponding to eigenvalue 3:

We only need to normalize:

$$\left\| \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right\| = \sqrt{1^2 + (-1)^2 + 1^2} = \sqrt{3}$$

Ch 7:

~~Ch 7~~
 A symmetric
 \Rightarrow e. vector
 w/ e. value 3
 will be
 \perp
 to e. vector
 w/ e. value 0



5

Thus orthonormal basis for eigenspace corresponding to eigenvalue 3 is

$$\left\{ \begin{bmatrix} \frac{1}{\sqrt{3}} \\ -\frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix} \right\}$$

4.) Construct D and P

$$D = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

$$P = \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ 0 & \sqrt{\frac{2}{3}} & \frac{1}{\sqrt{3}} \end{bmatrix}$$

orthonormal matrix

Make sure order of eigenvectors in D match order of eigenvalues in P .

5.) P orthonormal implies $P^{-1} = P^T$

in 7.1
 P^{-1} is easy to find

$$\text{Thus } P^{-1} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{6}} & \sqrt{\frac{2}{3}} \\ \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \end{bmatrix}$$

$$\text{Thus } \begin{bmatrix} 1 & -1 & 1 \\ -1 & 1 & -1 \\ 1 & -1 & 1 \end{bmatrix} = A = PDP^{-1} =$$

$$\begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{3}} \\ 0 & \sqrt{\frac{2}{3}} & \frac{1}{\sqrt{3}} \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{6}} & \sqrt{\frac{2}{3}} \\ \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \end{bmatrix}$$

Answer

Not true if A is NOT symmetric

7.1: Orthogonal Diagonalization

Equivalent Questions:

- Given an $n \times n$ matrix, does there exist an orthonormal basis for \mathbb{R}^n consisting of eigenvectors of A ?
- Given an $n \times n$ matrix, does there exist an orthonormal matrix P such that $P^{-1}AP = P^TAP$ is a diagonal matrix?
- Is A symmetric?

Defn: A matrix is symmetric if $A = A^T$.

or the normal
 $PP^T = I$

Recall An invertible matrix P is orthogonal if $P^{-1} = P^T$
normal

Defn: A matrix A is orthogonally diagonalizable if there exists an orthogonal matrix P such that $P^{-1}AP = D$ where D is a diagonal matrix.

Thm: If A is an $n \times n$ matrix, then the following are equivalent:

- A is orthogonally diagonalizable.
- There exists an orthonormal basis for \mathbb{R}^n consisting of eigenvectors of A .
- A is symmetric.

\Rightarrow normalize columns of P
||
orthonormal basis for \mathbb{R}^n

Thm: If A is a symmetric matrix, then:

- The eigenvalues of A are all real numbers.
- Eigenvectors from different eigenspaces are orthogonal.
- Geometric multiplicity of an eigenvalue = its algebraic multiplicity

$A = A^T$

Diagonalizable \Leftrightarrow



Note

A symmetric \Rightarrow A diag

" " \Rightarrow A orthog
diag

A orthog diag \Rightarrow A symmetric

A diag \Rightarrow A may
or may
not be
symmetric

A is symmetric

$\Rightarrow A$ diagonalizable

A is not symmetric

$\Rightarrow A$ may or may not be diagonalizable

(depends on if $a_m = g_m$ for all e. values)

A diagonalizable $\Rightarrow A$ may or may not be symmetric

A is orthogonally diagonalizable



A is symmetric

can choose P to have orthogonal columns

7.1 cont



They don't need to be e. vectors to apply Gram-Schmidt just l.i.

Note if $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ are linearly independent:

ch 6

(1.) You can use the Gram-Schmidt algorithm to find an orthogonal basis for $span\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$.

(2.) You can normalize these orthogonal vectors to create an orthonormal basis for $span\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$.

(3.) These basis vectors are not normally eigenvectors of $A = [\mathbf{v}_1 \dots \mathbf{v}_n]$ even if A is symmetric (note that there are an infinite number of orthogonal basis for $span\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ even if $n = 2$ and $span\{\mathbf{v}_1, \mathbf{v}_2\}$ is just a 2-dimensional plane)

Ch 6

Ch 5

Note if A is a $n \times n$ square matrix that is diagonalizable, then you can find n linearly independent eigenvectors of A .

Each eigenvector is in $col(A)$: If \mathbf{v} is an eigenvector of A with eigenvalue λ , then $A\mathbf{v} = \lambda\mathbf{v}$. Thus $\frac{1}{\lambda}A\mathbf{v} = \mathbf{v}$. Hence $A(\frac{1}{\lambda}\mathbf{v}) = \mathbf{v}$. Thus \mathbf{v} is in $col(A)$.

Thus $col(A)$ is an n -dimensional subspace of R^n . That is $col(A) = R^n$, and you can find a basis for $col(A) = R^n$ consisting of eigenvectors of A .

But these eigenvectors are NOT usually orthogonal UNLESS they come from different eigenspaces AND the matrix A is symmetric.

If A is NOT symmetric, then eigenvectors from different eigenspaces need NOT be orthogonal.

Multiple ways to find basis for R^n

- ① $col(A)$ if A has no free variables and A is square
- ② Find e. vectors usually different basis

Ch 6: Matrices

may not be square

12/1/2014

QR decomposition:
 $A = QR$
 Q is orthonormal
 R is upper triangular

To find QR decomposition:
 1.) Q: Use Gram-Schmidt to find orthonormal basis for column space of A
 2.) Let $R = Q^T A$

Find the QR decomposition of

$$A = \begin{bmatrix} 1 & 4 \\ 2 & 3 \end{bmatrix}$$

1.) Use Gram-Schmidt to find orthonormal basis for column space of A

Find the QR decomposition of

$$A = \begin{bmatrix} 1 & 4 \\ 2 & 3 \end{bmatrix}$$

1.) Use Gram-Schmidt to find orthonormal basis for column space of A

$\text{col}(A) = \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ 3 \end{bmatrix} \right\}$

Find the QR decomposition of

$$A = \begin{bmatrix} 1 & 4 \\ 2 & 3 \end{bmatrix}$$

1.) Use Gram-Schmidt to find orthogonal basis for column space of A

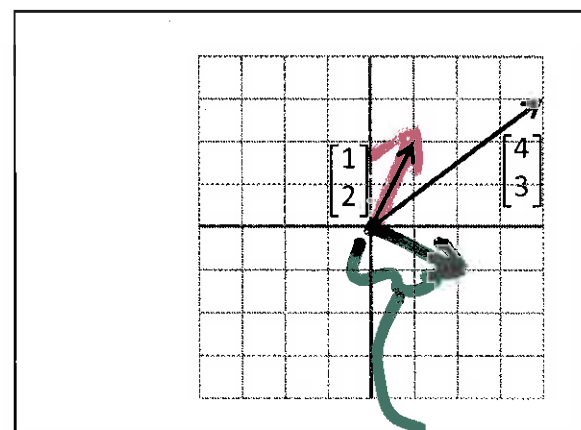
$\text{col}(A) = \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ 3 \end{bmatrix} \right\}$

Find the QR decomposition of

$$A = \begin{bmatrix} 1 & 4 \\ 2 & 3 \end{bmatrix}$$

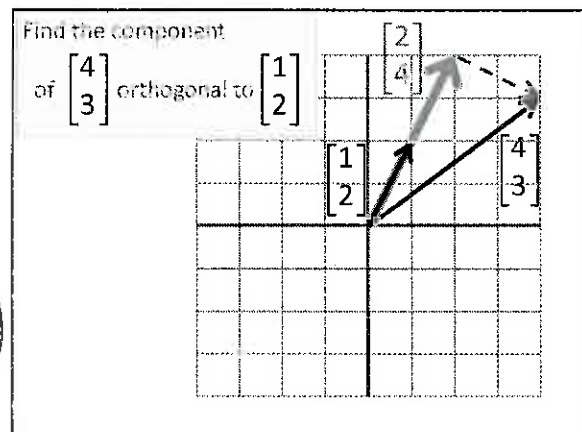
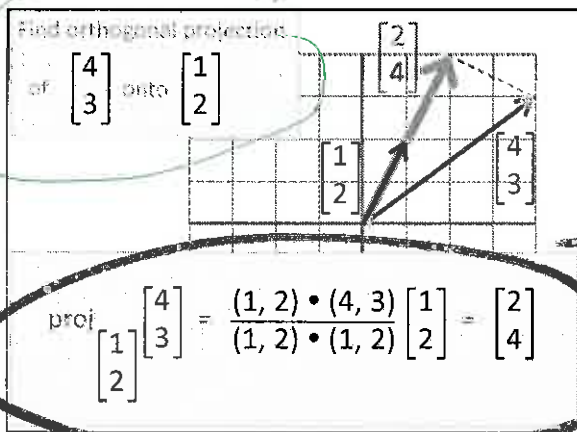
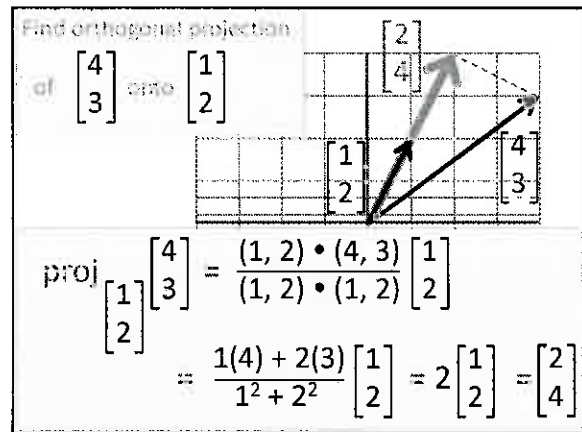
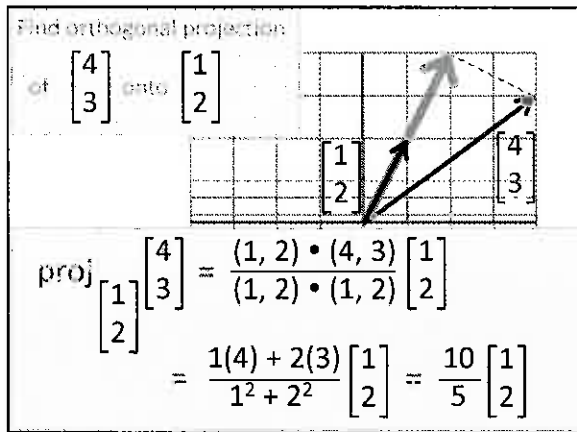
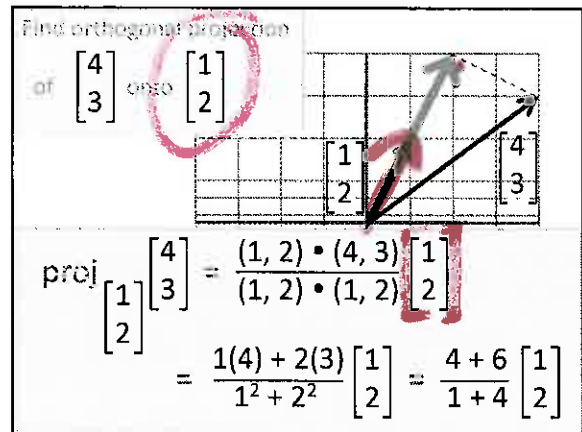
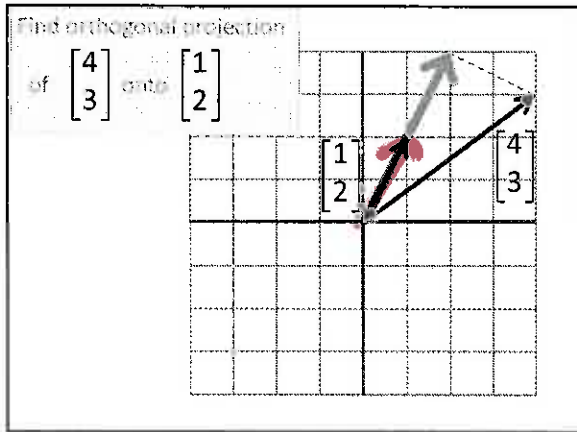
1.) Use Gram-Schmidt to find orthogonal basis for column space of A

$\text{col}(A) = \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ 3 \end{bmatrix} \right\} = \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, ? \right\}$



For QR

Keep first vector



Find the component of $\begin{bmatrix} 4 \\ 3 \end{bmatrix}$ orthogonal to $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$

$\begin{bmatrix} 4 \\ 3 \end{bmatrix} - \begin{bmatrix} 2 \\ 4 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$

Short-cut for \mathbb{R}^2 case:

$\vec{v}_2 - \text{proj}_{\vec{v}_1} \vec{v}_2$

Find the QR decomposition of

$$A = \begin{bmatrix} 1 & 4 \\ 2 & 3 \end{bmatrix}$$

1.) Use Gram-Schmidt to find orthogonal basis for column space of A

$$\text{col}(A) = \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ 3 \end{bmatrix} \right\} = \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ -1 \end{bmatrix} \right\}$$

Find the length of each vector:

$$\left\| \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\| = \sqrt{1^2 + 2^2} = \sqrt{5}$$

$$\left\| \begin{bmatrix} 2 \\ -1 \end{bmatrix} \right\| = \sqrt{(-1)^2 + 2^2} = \sqrt{5}$$

Divide each vector by its length:

$$\text{col}(A) = \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ 3 \end{bmatrix} \right\} = \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ -1 \end{bmatrix} \right\}$$

$$= \text{span} \left\{ \begin{bmatrix} \frac{1}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} \end{bmatrix}, \begin{bmatrix} \frac{2}{\sqrt{5}} \\ -\frac{1}{\sqrt{5}} \end{bmatrix} \right\}$$

$\text{col}(A) = \text{span} \left\{ \begin{bmatrix} \frac{1}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} \end{bmatrix}, \begin{bmatrix} \frac{2}{\sqrt{5}} \\ -\frac{1}{\sqrt{5}} \end{bmatrix} \right\}$

$Q = \begin{bmatrix} \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} & -\frac{1}{\sqrt{5}} \end{bmatrix}$

$A = QR$

perp unit vec

o.n basis for col A

$$Q^T A = Q^T Q R$$

$$Q^T A = R$$

$Q^{-1} = Q^T$
since Q orthonormal

$$A = QR$$

$$A = QR$$

$$Q^{-1}A = Q^{-1}QR$$

$$Q^{-1}A = R$$

Q has orthonormal columns:

$$\text{Thus } Q^{-1} = Q^T$$

$$\text{Thus } R = Q^{-1}A = Q^T A$$

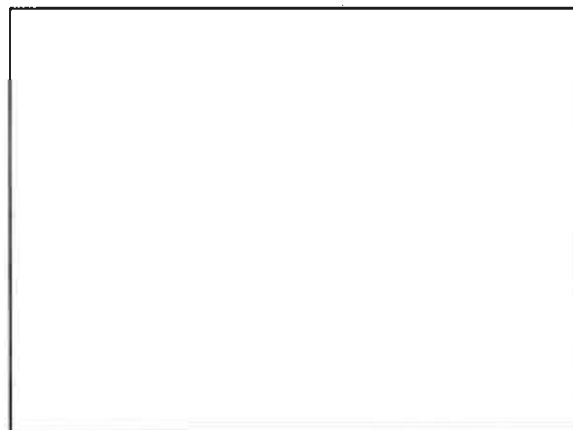
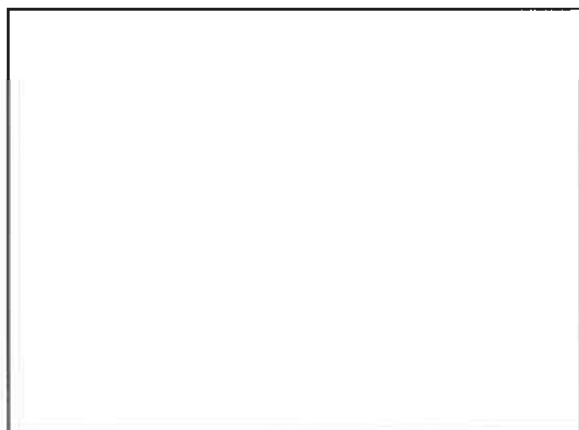
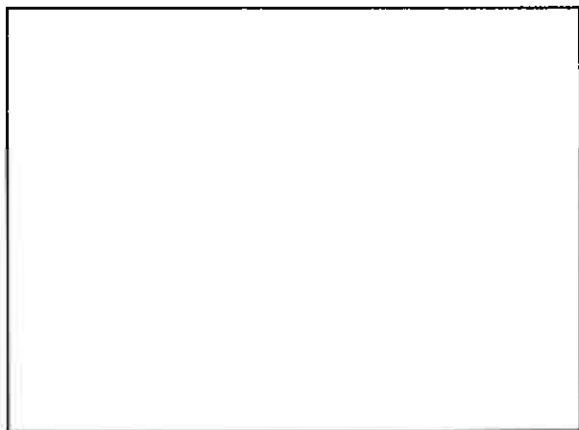
Find the QR decomposition of

$$A = \begin{bmatrix} 1 & 4 \\ 2 & 3 \end{bmatrix} = QR$$

$$R = Q^{-1}A = Q^T A = \begin{bmatrix} \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} & -\frac{1}{\sqrt{5}} \end{bmatrix} \begin{bmatrix} 1 & 4 \\ 2 & 3 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{5}{\sqrt{5}} & \frac{10}{\sqrt{5}} \\ 0 & \frac{5}{\sqrt{5}} \end{bmatrix} = \begin{bmatrix} \sqrt{5} & 2\sqrt{5} \\ 0 & \sqrt{5} \end{bmatrix}$$

Note R is upper triangular



Thm: Let $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ be an orthogonal basis for an inner product space V . Let \mathbf{a} be an arbitrary vector in V . Then

$$\mathbf{a} = c_1 \mathbf{v}_1 + \dots + c_n \mathbf{v}_n$$

$$\text{where } c_j = \frac{\langle \mathbf{a}, \mathbf{v}_j \rangle}{\|\mathbf{v}_j\|^2} \text{ for } j = 1, 2, \dots, n.$$

Note if $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ is an orthonormal basis, then

$$\|\mathbf{v}_j\| = 1 \text{ and } c_j = \langle \mathbf{a}, \mathbf{v}_j \rangle$$

Thm: Let \mathbf{a}, \mathbf{v} be nonzero vectors in R^k .

The vector component of \mathbf{a} along \mathbf{v}

= orthogonal projection of \mathbf{a} on \mathbf{v}

$$= \text{proj}_{\mathbf{v}} \mathbf{a} = \frac{\mathbf{a} \cdot \mathbf{v}}{\|\mathbf{v}\|^2} \mathbf{v}$$

The vector component of \mathbf{a} orthogonal to \mathbf{v}

$$= \mathbf{a} - \text{proj}_{\mathbf{v}} \mathbf{a} = \mathbf{a} - \frac{\mathbf{a} \cdot \mathbf{v}}{\|\mathbf{v}\|^2} \mathbf{v}$$

Thm: Let $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ be an orthogonal basis for subspace W of an inner product space V . Let \mathbf{a} be an arbitrary vector in V . Then

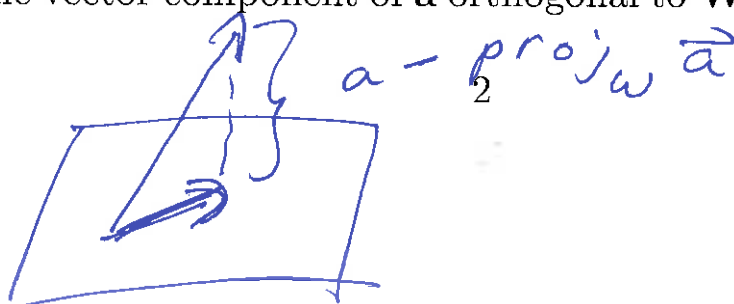
$$\text{proj}_W \mathbf{a} = c_1 \mathbf{v}_1 + \dots + c_n \mathbf{v}_n$$

$$\text{where } c_j = \frac{\langle \mathbf{a}, \mathbf{v}_j \rangle}{\|\mathbf{v}_j\|^2} \text{ for } j = 1, 2, \dots, n.$$

Note if $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ is an orthonormal basis, then

$$\|\mathbf{v}_j\| = 1 \text{ and } c_j = \langle \mathbf{a}, \mathbf{v}_j \rangle$$

The vector component of \mathbf{a} orthogonal to $W = \mathbf{a} - \text{proj}_W \mathbf{a}$



Thm (Gram-Schmidt process for constructing an orthogonal basis):

Let $\mathcal{T} = \{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_n\}$ be a basis for an inner product space V . Let $\mathcal{T}' = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ be defined as follows:

$$\mathbf{v}_1 = \mathbf{a}_1$$

$$\mathbf{v}_2 = \mathbf{a}_2 - \underbrace{\frac{\langle \mathbf{a}_2, \mathbf{v}_1 \rangle}{\langle \mathbf{v}_1, \mathbf{v}_1 \rangle}}_{\text{blue underline}} \mathbf{v}_1$$

$$\mathbf{v}_3 = \mathbf{a}_3 - \underbrace{\frac{\langle \mathbf{a}_3, \mathbf{v}_1 \rangle}{\langle \mathbf{v}_1, \mathbf{v}_1 \rangle} \mathbf{v}_1 - \frac{\langle \mathbf{a}_3, \mathbf{v}_2 \rangle}{\langle \mathbf{v}_2, \mathbf{v}_2 \rangle} \mathbf{v}_2}_{\text{blue underline}}$$

.

.

.

$$\mathbf{v}_n = \mathbf{a}_n - \frac{\langle \mathbf{a}_n, \mathbf{v}_1 \rangle}{\langle \mathbf{v}_1, \mathbf{v}_1 \rangle} \mathbf{v}_1 - \frac{\langle \mathbf{a}_n, \mathbf{v}_2 \rangle}{\langle \mathbf{v}_2, \mathbf{v}_2 \rangle} \mathbf{v}_2 - \dots - \frac{\langle \mathbf{a}_n, \mathbf{v}_{n-1} \rangle}{\langle \mathbf{v}_{n-1}, \mathbf{v}_{n-1} \rangle} \mathbf{v}_{n-1}$$

Then the set \mathcal{T}' is an orthogonal basis for V .

An orthonormal basis for V is given by

$$\mathcal{T}'' = \left\{ \frac{\mathbf{v}_1}{\|\mathbf{v}_1\|}, \frac{\mathbf{v}_2}{\|\mathbf{v}_2\|}, \dots, \frac{\mathbf{v}_n}{\|\mathbf{v}_n\|} \right\}$$