

*repeated root*

Derivation of general solutions:

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If  $b^2 - 4ac > 0$  we guessed  $e^{rt}$  is a solution and noted that any linear combination of solutions is a solution to a homogeneous linear differential equation.

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Section 3.3: If  $b^2 = 4ac < 0$ , :

Changed format of  $y = c_1 e^{r_1 t} + c_2 e^{r_2 t}$  to linear combination of real-valued functions instead of complex valued functions by using Euler's formula:

$$e^{it} = \cos(t) + i \sin(t)$$

$$\text{Hence } e^{(d+in)t} = e^{dt} e^{int} = e^{dt} [\cos(nt) + i \sin(nt)]$$

$$\text{Let } r_1 = d + in, r_2 = d - in$$

$$\begin{aligned} y &= c_1 e^{r_1 t} + c_2 e^{r_2 t} \\ &= c_1 e^{dt} [\cos(nt) + i \sin(nt)] + c_2 e^{dt} [\cos(-nt) + i \sin(-nt)] \\ &= c_1 e^{dt} \cos(nt) + i c_1 e^{dt} \sin(nt) + c_2 e^{dt} \cos(nt) - i c_2 e^{dt} \sin(nt) \\ &= (c_1 + c_2) e^{dt} \cos(nt) + i(c_1 - c_2) e^{dt} \sin(nt) \\ &= k_1 e^{dt} \cos(nt) + k_2 e^{dt} \sin(nt) \end{aligned}$$


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Section 3.4: If  $b^2 - 4ac = 0$ , then  $r_1 = r_2$ . Hence one solution is  $y = e^{r_1 t}$  Need second solution.

If  $y = e^{rt}$  is a solution,  $y = ce^{rt}$  is a solution.

How about  $y = v(t)e^{rt}$ ?

$$\begin{aligned} y' &= v'(t)e^{rt} + v(t)re^{rt} \\ y'' &= v''(t)e^{rt} + v'(t)re^{rt} + v'(t)re^{rt} + v(t)r^2e^{rt} \\ &= v''(t)e^{rt} + 2v'(t)re^{rt} + v(t)r^2e^{rt} \end{aligned}$$

$$ay'' + by' + cy = 0$$

$$a(v''e^{rt} + 2v're^{rt} + vr^2e^{rt}) + b(v'e^{rt} + v're^{rt}) + cv e^{rt} = 0$$

$$a(v''(t) + 2v'(t)r + v(t)r^2) + b(v'(t) + v(t)r) + cv(t) = 0$$

$$av''(t) + 2av'(t)r + av(t)r^2 + bv'(t) + bv(t)r + cv(t) = 0$$

$$av''(t) + (2ar + b)v'(t) + (ar^2 + br + c)v(t) = 0$$

$$av''(t) + (2a(\frac{-b}{2a}) + b)v'(t) + 0 = 0$$

since  $ar^2 + br + c = 0$  and  $r = \frac{-b}{2a}$

$$av''(t) + (-b + b)v'(t) = 0 \quad \text{Thus } av''(t) = 0.$$

Hence  $v''(t) = 0$  and  $v'(t) = k_1$  and  $v(t) = k_1 t + k_2$

Hence  $v(t)e^{r_1 t} = (k_1 t + k_2)e^{r_1 t}$  is a soln

Thus  $te^{r_1 t}$  is a nice second solution.

Hence general solution is  $y = c_1 e^{r_1 t} + c_2 t e^{r_1 t}$

3.6

Solve  $y'' - 2y' + y = e^t \ln(t)$

1) Find homogeneous solutions: Solve  $y'' - 2y' + y = 0$

Guess:  $y = e^{rt}$ , then  $y' = r e^{rt}$ ,  $y'' = r^2 e^{rt}$ , and

$$r^2 e^{rt} - 2r e^{rt} + e^{rt} = 0 \text{ implies } r^2 - 2r + 1 = 0$$

$$(r - 1)^2 = 0, \text{ and hence } r = 1$$

General homogeneous solution:  $y = c_1 e^t + c_2 t e^t$

since have two linearly independent solutions:  $\{e^t, t e^t\}$

2.) Find a non-homogeneous solution:

Sect. 3.5 method: Educated guess

Variable of parameters

Sect. 3.6: Guess  $y = u_1(t)e^t + u_2(t)te^t$  and solve for  $u_1$  and  $u_2$

$$u_1(t) = \int \frac{\phi_2(t)g(t)}{W(\phi_1, \phi_2)} dt = - \int \frac{(te^t)(e^t \ln(t))}{e^{2t}} dt = - \int t \ln(t) dt = - \left[ \frac{t^2 \ln(t)}{2} - \int \frac{t}{2} \right] = - \frac{t^2 \ln(t)}{2} + \frac{t^2}{4}$$

$$u_2(t) = \int \frac{\phi_1(t)g(t)}{W(\phi_1, \phi_2)} dt = \int \frac{(e^t)(e^t \ln(t))}{e^{2t}} dt = \int \ln(t) dt = t \ln(t) - t$$

$$W(\phi_1, \phi_2) = \begin{vmatrix} \phi_1 & \phi_2 \\ \phi_1' & \phi_2' \end{vmatrix} = \begin{vmatrix} e^t & te^t \\ e^t & te^t + te^t \end{vmatrix} = e^{2t} te^t - te^{2t}$$

$$u = \ln(t) \quad dv = dt$$

$$du = \frac{dt}{t} \quad v = t$$

$$\text{General solution: } y = c_1 e^t + c_2 t e^t + \left(-\frac{t^2 \ln(t)}{2} + \frac{t^2}{4}\right) e^t + (t \ln(t) - t) t e^t$$

which simplifies to  $y = c_1 e^t + c_2 t e^t + \left(\frac{\ln(t)}{2} - \frac{3}{4}\right) t^2 e^t$

$$\rightarrow y = c_1 \phi_1 + c_2 \phi_2 + u_1 \phi_1 + u_2 \phi_2$$

homo non-homo

FYI

Sect. 3.6: Guess  $y = u_1(t)e^t + u_2(t)te^t$  and solve for  $u_1$  and  $u_2$

$$y' = u_1' e^t + u_1 e^t + u_2' t e^t + u_2 (e^t + te^t) = e^{2t} + t e^{2t} - t e^{2t} - e^{2t}$$

Two unknown functions,  $u_1$  and  $u_2$ , but only one equation ( $y'' - 2y' + y = e^t \ln(t)$ ). Thus might be OK to choose 2nd eq'n.

Avoid 2nd derivative in  $y''$ : Choose  $u_1' e^t + u_2' t e^t = 0$

$$\text{Hence } y' = u_1 e^t + u_2 (e^t + te^t)$$

$$\text{and } y'' = u_1' e^t + u_1 e^t + u_2' (e^t + te^t) + u_2 (e^t + te^t)$$

$$= u_1' e^t + u_1 e^t + u_2' e^t + u_2' t e^t + u_2 (2e^t + te^t)$$

$$= u_1 e^t + u_2 e^t + u_2 (2e^t + te^t)$$

$$\text{Solve } y'' - 2y' + y = e^t \ln(t)$$

$$u_1 e^t + u_2 e^t + u_2 (2e^t + te^t) - 2[u_1 e^t + u_2 (e^t + te^t)] + u_1 e^t + u_2 t e^t = e^t \ln(t)$$

$$u_2 e^t + 2u_2 e^t + u_2 t e^t - 2u_2 e^t - 2u_2 t e^t + u_2 t e^t = e^t \ln(t)$$

$$u_2 = \ln(t) \text{ or in other words, } \frac{du_2}{dt} = \ln(t)$$

$$\text{Thus } \int du_2 = \int \ln(t) dt$$

$u_2 = t \ln(t) - t$ . Note only need one solution, so don't need  $+C$ .

$$y = u_1(t)e^t + [t \ln(t) - t] t e^t$$

$u_1' e^t + u_2' t e^t = 0$ . Thus  $u_1' + u_2' t = 0$ . Hence  $u_1' = -u_2' t = -t \ln(t)$

$$\text{Thus } u_1 = - \int t \ln(t) dt = - \frac{t^2 \ln(t)}{2} + \frac{t^2}{4}$$

Thus the general solution is

$$y = c_1 e^t + c_2 t e^t + \left(-\frac{t^2 \ln(t)}{2} + \frac{t^2}{4}\right) e^t + (t \ln(t) - t) t e^t$$

$\uparrow kL$  3.7 ↓ mg  
 $mg - kL = 0$   
 $m u''(t) + \gamma u'(t) + k u(t) = 0, \quad m, \gamma, k \geq 0$   
 $m, k > 0$   
 $r_1, r_2 = \frac{-\gamma \pm \sqrt{\gamma^2 - 4km}}{2m} \leftarrow m r^2 + \gamma r + k = 0$

$\gamma^2 - 4km > 0: u(t) = A e^{r_1 t} + B e^{r_2 t}$

$\gamma^2 - 4km = 0: u(t) = (A + Bt)e^{r_1 t}, \quad r_1 = -\frac{\gamma}{2m}$   
 AS  $t \rightarrow \infty, u(t) \rightarrow 0$

$\gamma^2 - 4km < 0: u(t) = e^{-\frac{\gamma t}{2m}} (A \cos(\mu t) + B \sin(\mu t))$   
 $= e^{-\frac{\gamma t}{2m}} (R \cos(\mu t - \delta))$

where  $A = R \cos(\delta), B = R \sin(\delta)$

$\mu =$  quasi frequency,  $\frac{2\pi}{\mu} =$  quasi period

$r_1, r_2 = -\frac{\gamma}{2m} \pm i \frac{\sqrt{4km - \gamma^2}}{2m}$

$y = c_1 e^{-\frac{\gamma t}{2m}} \cos\left(\frac{\sqrt{4km - \gamma^2}}{2m} t\right) + c_2 e^{-\frac{\gamma t}{2m}} \sin\left(\frac{\sqrt{4km - \gamma^2}}{2m} t\right)$

Note if  $\gamma = 0$ , then

No damping, no negative exponential term, so oscillates forever

Overdamped:  $\gamma > 2\sqrt{km}$

Suppose a mass weighs 64 lbs stretches a spring 4 ft. If there is no damping and the spring is stretched an additional foot and set in motion with an upward velocity of  $\sqrt{8}$  ft/sec, find the equation of motion of the mass.

Weight = mg:  $m = \frac{\text{weight}}{g} = \frac{64}{32} = 2$

$mg - kL = 0$  implies  $k = \frac{mg}{L} = \frac{64}{4} = 16$

$m u''(t) + \gamma u'(t) + k u(t) = F_{\text{external}}$

$[\gamma^2 - 4km < 0: u(t) = e^{-\frac{\gamma t}{2m}} (A \cos(\mu t) + B \sin(\mu t))$   
 Hence  $u(t) = A \cos(\mu t) + B \sin(\mu t)$  since  $\gamma = 0$ .

$2u''(t) + 16u(t) = 0$

$u''(t) + 8u(t) = 0, \quad u(0) = 1, u'(0) = -\sqrt{8}$

$r^2 + 8 = 0 \rightarrow r = \pm \sqrt{-8} = \pm i\sqrt{8} = 0 \pm i\sqrt{8}$

$u(t) = c_1 e^{it\sqrt{8}} + c_2 e^{-it\sqrt{8}}$

$u(t) = A \cos(\sqrt{8}t) + B \sin(\sqrt{8}t)$

$u(0) = 1: 1 = A \cos(0) + B \sin(0) = A$

$u'(t) = -\sqrt{8} A \sin(\sqrt{8}t) + \sqrt{8} B \cos(\sqrt{8}t)$

$u'(0) = -\sqrt{8}: -\sqrt{8} = -\sqrt{8} A \sin(0) + \sqrt{8} B \cos(0)$

$B = -1$

Thus  $u(t) = \cos(\sqrt{8}t) - \sin(\sqrt{8}t)$