

# Ch 3

## Second order differential equation:

Linear equation with constant coefficients:

If the second order differential equation is

$$ay'' + by' + cy = 0,$$

then  $y = e^{rt}$  is a solution

Need to have two independent solutions.

Solve the following IVPs:

1.)  $y'' - 6y' + 9y = 0$        $y(0) = 1, y'(0) = 2$

2.)  $4y'' - y' + 2y = 0$        $y(0) = 3, y'(0) = 4$

3.)  $4y'' + 4y' + y = 0$        $y(0) = 6, y'(0) = 7$

4.)  $2y'' - 2y = 0$        $y(0) = 5, y'(0) = 9$

$ay'' + by' + cy = 0, y = e^{rt}$ , then

$ar^2e^{rt} + bre^{rt} + ce^{rt} = 0$  implies  $ar^2 + br + c = 0$ ,

Suppose  $r = r_1, r_2$  are solutions to  $ar^2 + br + c = 0$

$$r_{1,2} = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

If  $r_1 \neq r_2$ , then  $b^2 - 4ac \neq 0$ . Hence a general solution is  $y = c_1e^{r_1t} + c_2e^{r_2t}$  (2 real solns to)

If  $b^2 - 4ac = 0$ , general solution is  $y = c_1e^{r_1t} + c_2te^{r_1t}$ .

If  $b^2 - 4ac < 0$ , change format to linear combination of real-valued functions instead of complex valued functions by using Euler's formula.

general solution is  $y = c_1e^{dt} \cos(nt) + c_2e^{dt} \sin(nt)$  where  $r = d \pm in$

If  $b^2 - 4ac = 0, r_1 = r_2$ , so need 2nd (independent) solution:  $te^{r_1t}$

Hence general solution is  $y = c_1e^{r_1t} + c_2te^{r_1t}$ .

Initial value problem: use  $y(t_0) = y_0, y'(t_0) = y'_0$  to solve for  $c_1, c_2$  to find unique solution.

# Ch 3

Derivation of general solutions:

If  $b^2 - 4ac > 0$  we guessed  $e^{rt}$  is a solution and noted that any linear combination of solutions is a solution to a homogeneous linear differential equation.

Section 3.3: If  $b^2 - 4ac < 0$ , :

Changed format of  $y = c_1 e^{r_1 t} + c_2 e^{r_2 t}$  to linear combination of real-valued functions instead of complex valued functions by using Euler's formula:

$$e^{it} = \cos(t) + i \sin(t)$$

$$\text{Hence } e^{(d+in)t} = e^{dt} e^{int} = e^{dt} [\cos(nt) + i \sin(nt)]$$

$$\text{Let } r_1 = d + in, r_2 = d - in$$

$$\begin{aligned} y &= c_1 e^{r_1 t} + c_2 e^{r_2 t} \\ &= c_1 e^{dt} [\cos(nt) + i \sin(nt)] + c_2 e^{dt} [\cos(-nt) + i \sin(-nt)] \\ &= c_1 e^{dt} \cos(nt) + i c_1 e^{dt} \sin(nt) + c_2 e^{dt} \cos(nt) - i c_2 e^{dt} \sin(nt) \\ &= (c_1 + c_2) e^{dt} \cos(nt) + i(c_1 - c_2) e^{dt} \sin(nt) \\ &= k_1 e^{dt} \cos(nt) + k_2 e^{dt} \sin(nt) \end{aligned}$$

← acceptable

ugly when  $r_1, r_2$  are complex

Section 3.4: If  $b^2 - 4ac = 0$ , then  $r_1 = r_2$ . Hence one solution is  $y = e^{r_1 t}$ . Need second solution.

If  $y = e^{rt}$  is a solution,  $y = ce^{rt}$  is a solution.

How about  $y = v(t)e^{rt}$ ?

$$\begin{aligned} y' &= v'(t)e^{rt} + v(t)re^{rt} \\ y'' &= v''(t)e^{rt} + v'(t)re^{rt} + v'(t)re^{rt} + v(t)r^2e^{rt} \\ &= v''(t)e^{rt} + 2v'(t)re^{rt} + v(t)r^2e^{rt} \end{aligned}$$

$$ay'' + by' + cy = 0$$

$$a(v''e^{rt} + 2v're^{rt} + vr^2e^{rt}) + b(v'e^{rt} + v're^{rt}) + cv e^{rt} = 0$$

$$a(v''(t) + 2v'(t)r + v(t)r^2) + b(v'(t) + v(t)r) + cv(t) = 0$$

$$av''(t) + 2av'(t)r + av(t)r^2 + bv'(t) + bv(t)r + cv(t) = 0$$

$$av''(t) + (2ar + b)v'(t) + (ar^2 + br + c)v(t) = 0$$

$$av''(t) + (2a(\frac{-b}{2a}) + b)v'(t) + 0 = 0$$

←  $e^{rt}$  soln

since  $ar^2 + br + c = 0$  and  $r = \frac{-b}{2a}$

$$av''(t) + (-b + b)v'(t) = 0. \quad \text{Thus } av''(t) = 0.$$

$$\text{Hence } v''(t) = 0 \text{ and } v'(t) = k_1 \text{ and } v(t) = k_1 t + k_2$$

Hence  $v(t)e^{r_1 t} = (k_1 t + k_2)e^{r_1 t}$  is a soln

Thus  $te^{r_1 t}$  is a nice second solution.

Hence general solution is  $y = c_1 e^{r_1 t} + c_2 t e^{r_1 t}$

← one repeated root