

Note: You must be able to identify which techniques you need to use. For example:

Integration:

- \* Integration by substitution
- \* Integration by parts
- \* Integration by partial fractions

Note: Partial fractions are also used in ch 6 for a different application.

For differential equations:

Is the differential equation 1st order or 2nd order?

If 2nd order: Section 3.1, solve  $ay'' + by' + cy = 0$ .

Guess  $y = e^{rt}$ .

$ar^2e^{rt} + bre^{rt} + ce^{rt} = 0$  implies  $ar^2 + br + c = 0$ .

Need to have two independent solutions.

If  $y = \phi_1, y = \phi_2$  are solutions to a LINEAR HOMOGENEC differential equation,  $y = c_1\phi_1 + c_2\phi_2$  is also a solution

If 1st order: Is the equation linear or separable or Bernoulli?

Solving first order differential equation:

Method 1 (sect. 2.2): Separate variables.

Method 2 (sect. 2.1): If linear  $[y'(t) + p(t)y(t) = g(t)]$ , multiply equation by an integrating factor

$$u(t) = e^{\int p(t)dt}$$

$$\begin{aligned} y' + py &= g \\ y'u + upy &= ug \\ (uy)' &= ug \\ \int (uy)' &= \int ug \\ uy &= \int ug \\ &\text{etc...} \end{aligned}$$

Method 3 (sect. 2.4): Solve Bernoulli's equation,

$$y' + p(t)y = g(t)y^n,$$

when  $n > 1$  by changing it to a linear equation by substituting  $v = y^{1-n}$

direction field = slope field = graph of  $\frac{dy}{dt}$  in  $t, v$ -plane.

\*\*\* can use slope field to determine behavior of  $v$  including as  $t \rightarrow \infty$ .

Equilibrium Solution = constant solution

stable, unstable, semi-stable.

IVP = plug in to find constants

2.3, 2.5, 2.6

Section 2.4: Existence and Uniqueness.

In general, for  $y' = f(t, y)$ ,  $y(t_0) = y_0$ , solution may or may not exist and solution may or may not be unique.

But we have 2 theorems that guarantee both existence and uniqueness of solutions under certain conditions:

1st order LINEAR differential equation:

Thm 2.4.1: If  $p : (a, b) \rightarrow R$  and  $g : (a, b) \rightarrow R$  are continuous and  $a < t_0 < b$ , then there exists a unique function  $y = \phi(t)$ ,  $\phi : (a, b) \rightarrow R$  that satisfies the initial value problem

$$y' + p(t)y = g(t),$$

$$y(t_0) = y_0$$

1st order differential equation (general case):

Thm 2.4.2: Suppose  $z = f(t, y)$  and  $z = \frac{\partial f}{\partial y}(t, y)$  are continuous on  $(a, b) \times (c, d)$  and the point  $(t_0, y_0) \in (a, b) \times (c, d)$ , then there exists an interval  $(t_0 - h, t_0 + h) \subset (a, b)$  such that there exists a unique function  $y = \phi(t)$  defined on  $(t_0 - h, t_0 + h)$  that satisfies the following initial value problem:

$$y' = f(t, y), \quad y(t_0) = y_0.$$

Note the initial value problem

$$y' = y^{\frac{1}{3}}, \quad y(0) = 0$$

has an infinite number of different solutions.

$$y^{-\frac{1}{3}} dy = dt$$

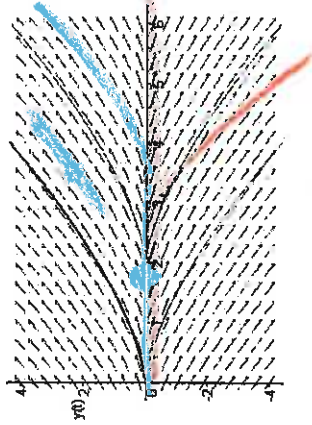
$$\frac{3}{2} y^{\frac{2}{3}} = t + C$$

$$y = \pm (\frac{2}{3}t + C)^{\frac{3}{2}}$$

$y(0) = 0$  implies  $C = 0$

Thus  $y = \pm (\frac{2}{3}t)^{\frac{3}{2}}$  are solutions.

$y = 0$  is also a solution, etc.



Compare to Thm 2.4.2:

$f(t, y) = y^{\frac{1}{3}}$  is continuous near  $(0, 0)$   
 But  $\frac{\partial f}{\partial y}(t, y) = \frac{1}{3}y^{-\frac{2}{3}}$  is not continuous near  $(0, 0)$  since it isn't defined at  $(0, 0)$ .

Section 2.4 example:  $\frac{dy}{dt} = \frac{1}{(1-t)(2-y)}$

$F(y, t) = \frac{1}{(1-t)(2-y)}$  is continuous for all  $t \neq 1, y \neq 2$

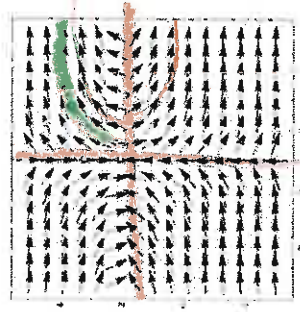
$$\frac{\partial F}{\partial y} = \frac{\partial \left( \frac{1}{(1-t)(2-y)} \right)}{\partial y} = \frac{1}{(1-t)} \frac{\partial (2-y)^{-1}}{\partial y} = \frac{1}{(1-t)(2-y)^2}$$

$\frac{\partial F}{\partial y}$  is continuous for all  $t \neq 1, y \neq 2$

Thus the IVP  $\frac{dy}{dt} = \frac{1}{(1-t)(2-y)}, y(t_0) = y_0$  has a unique solution if  $t_0 \neq 1, y_0 \neq 2$ .

Note that if  $y_0 = 2, \frac{dy}{dt} = \frac{1}{(1-t)(2-y)}, y(t_0) = 2$  has two solutions if  $t_0 \neq 1$  (and if we allow vertical slope in domain. Note normally our convention will be to NOT allow vertical slope in domain of solution).

Note that if  $t_0 = 1, \frac{dy}{dt} = \frac{1}{(1-t)(2-y)}, y(1) = y_0$  has no solutions.



$$(1, 1/((1-t)(2-y))) / \text{sqrt}(1 + 1/((1-t)(2-y))^2)$$

existence & uniqueness

Solve via separation of variables:  $\frac{dy}{dt} = \frac{1}{(1-t)(2-y)}$

$$\int (2-y)dy = \int \frac{dt}{1-t} \text{ implies } 2y - \frac{y^2}{2} = -\ln|1-t| + C$$

$$y^2 - 4y - 2\ln|1-t| + C = 0$$

$$y = \frac{4 \pm \sqrt{16 + 4(2\ln|1-t| + C)}}{2} = 2 \pm \sqrt{4 + 2\ln|1-t| + C}$$

$$y = 2 \pm \sqrt{2\ln|1-t| + C}$$

Find domain:  $2\ln|1-t| + C > 0$  &  $t \neq 1$  &  $y \neq 2$

NOTE: the convention in this class to choose largest possible connected domain where tangent line to solution is never vertical.

$2\ln|1-t| \geq -C$  and  $t \neq 1$  and  $y \neq 2$  implies

$$\ln|1-t| > -\frac{C}{2}$$

Note: we want to find domain for this  $C$  and thus this  $C$  can't swallow constants).

$|1-t| > e^{-C/2}$  since  $e^x$  is an increasing function.

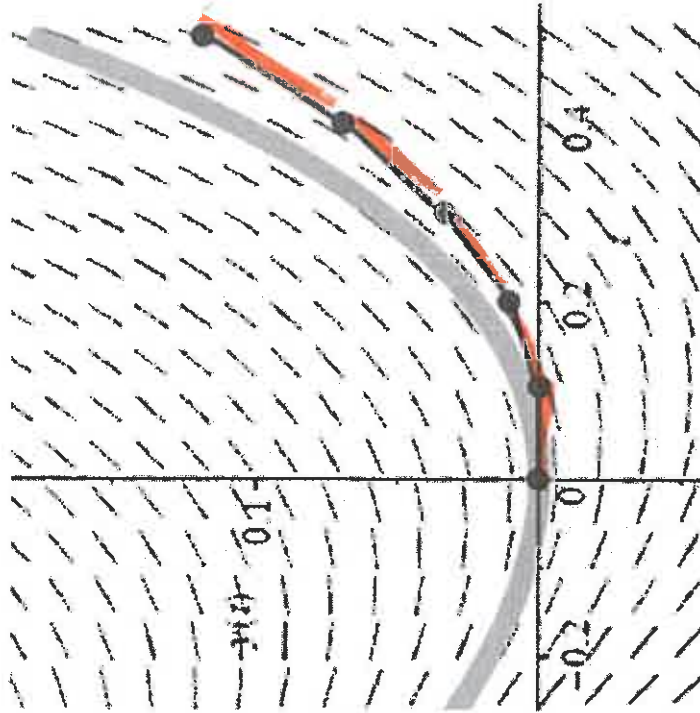
$$1-t < -e^{-C/2} \text{ or } 1-t > e^{-C/2}$$

$$\text{Domain: } \begin{cases} t > e^{-C/2} + 1 & \text{if } t_0 > 1 \\ t < -e^{-C/2} + 1 & \text{if } t_0 < 1. \end{cases}$$

2.7: Approximating soln to IVP using multiple tangent lines.

Example:  $y' = t + 2y, y(0) = 0$

$$y(t) = \begin{cases} 0 & 0 \leq t \leq 0.1 \\ 0.1t - 0.01 & 0.1 \leq t \leq 0.2 \\ 0.22t - 0.034 & 0.2 \leq t \leq 0.3 \\ 0.364t - 0.0772 & 0.3 \leq t \leq 0.4 \\ 0.5328t - 0.14672 & 0.4 \leq t \leq 0.5 \end{cases}$$



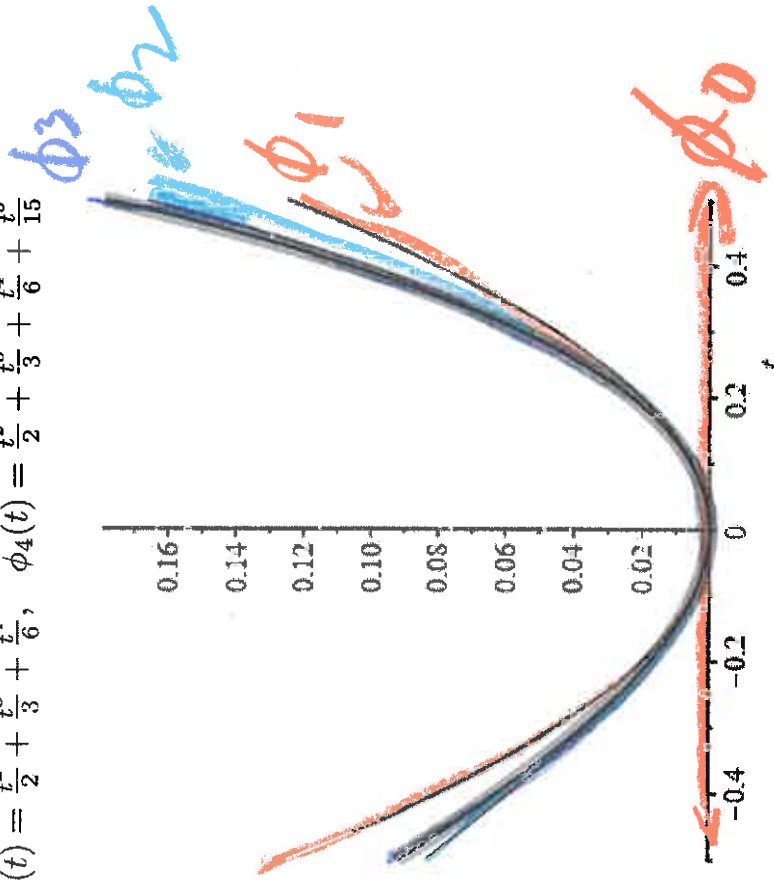
2.8: Approximating soln to IVP using seq of fns,

$$\phi_{n+1}(t) = \int_0^t f(s, \phi_n(s)) ds$$

Example:  $y' = t + 2y, y(0) = 0$

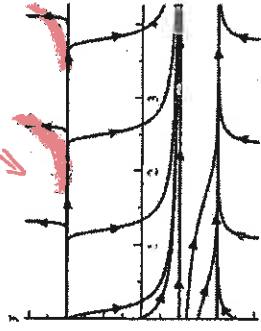
$$\phi_0(t) = 0, \quad \phi_1(t) = \frac{t^2}{2}, \quad \phi_2(t) = \frac{t^2}{2} + \frac{t^3}{3},$$

$$\phi_3(t) = \frac{t^2}{2} + \frac{t^3}{3} + \frac{t^4}{6}, \quad \phi_4(t) = \frac{t^2}{2} + \frac{t^3}{3} + \frac{t^4}{6} + \frac{t^5}{15}$$



## First Order Separable

- General Form:  $F(y) dy = G(x) dx$
- Usually looks like this in its starting form:
  - $dy/dx = f(y) * f(x)$
  - Can divide by  $f(y)$  and multiply both sides by  $dx$  to get above form
- Usually use when you need to divide or multiply by  $y$  to get it on the left
- Can directly integrate to solve
  - $\int F(y) dy = \int G(x) dx$
  - If  $y$  is in denominator, use natural log rule
  - Otherwise use normal integration



## Equilibrium

- Stable
- Unstable
- Semi-stable
- Integral curves

## Autonomous Equations

- General Form:  $dy/dt = f(y)$
- Usually used to model populations or other logistic trends that taper off
- General Solution form:  $y = c * e^{\int f(t) dt}$  ← Hopefully looks familiar
- Note this is the solution in the special case of  $y' = ry$
- Note this special case is 1<sup>st</sup> order linear homogeneous  $y' - ry = 0$ .
- Can make direction graph to model the equation with different initial conditions

## Direction Graphs

- Are often used with autonomous equations since there is only one variable to change
  - Can do with two variables but it takes longer
- When  $dy/dx = 0$ , you might have equilibrium solutions
  - Equilibrium solutions = constant solutions
  - If  $y = c$  is a constant solution, then  $y' = 0$ .
  - $y' = 0$  implies  $f(t, y) = 0$ , but this may or may not give you constant solution(s).
- Phase lines can't show the pattern of growth, but can show what direction the trends follow
- Phase lines can be used to determine long-term behavior of solutions.
- Phase lines can be misleading if IVP has no solution or multiple solutions.

## Second Order

- General Form:  $y'' + p(t)y' + q(t)y = g(t)$
- Alternatively  $P(t)y'' + Q(t)y' + R(t)y = G(t)$
- But you can divide by  $P(t)$  to get above equation
- But for 2<sup>nd</sup> and higher order, don't need to divide by  $P(t)$  before solving (unlike first order case when using integrating factor).
- Homogeneous vs Non-Homogeneous
  - $G(t)$  and  $g(t)$  equal 0 in formats above
- Get into characteristic form:
  - $ar^2 + br + c = 0$
- Solve for roots/put into  $e^{rt}$  format
- Write as sum of two individual solutions to cover entire solution set

# First Order Linear Differential Equation

$$ty' + (t+1)y = t$$

$$y(\ln 2) = 1$$

$$y' + \frac{(t+1)}{t}y = 1$$

$$y' + (1 + \frac{1}{t})y = 1$$

→ integrating factor

$$e^{\int p(x) dx} = e^{\int (1 + \frac{1}{t}) dt} = e^{t + \ln t} = e^t \cdot e^{\ln t} = \underline{te^t}$$

$$\int te^t y' + te^t (1 + \frac{1}{t})y = \int te^t$$

$$u = t \\ dv = e^t$$

u	dv	∫
t	e <sup>t</sup>	+
1	e <sup>t</sup>	-
0	e <sup>t</sup>	+

$$te^t \cdot y = te^t - e^t + C$$

$$y = 1 - \frac{1}{t} + \frac{C}{te^t}$$

$$x = x - \frac{1}{\ln 2} + \frac{C}{2 \ln 2}$$

$$\frac{1}{\ln 2} = \frac{C}{2 \ln 2} \Rightarrow C = 2$$

$$y(t) = 1 - \frac{1}{t} + \frac{2}{te^t}$$

$$t \neq 0 \rightarrow t \in (-\infty, 0) \cup (0, \infty)$$

↓

$$t \in (0, \infty) \text{ since } 0 < \ln 2 < \infty$$

# Separable Equation

$$\frac{dy}{dx} = \frac{3x^2 - e^x}{2y - 5}$$

$$2y - 5 = 0 \Rightarrow y = \frac{5}{2}$$

2

$$y(0) = 1$$

$$\int (2y - 5) dy = \int (3x^2 - e^x) \cdot dx$$

$$y^2 - 5y = x^3 - e^x + C$$

$$(1)^2 - 5(1) = 0^3 - e^0 + C \Rightarrow C = -3$$

$$y^2 - 5y = x^3 - e^x - 3 \quad \leftarrow \text{implicit}$$

$$y^2 - 5y + b^2 = x^3 - e^x - 3 + b^2 \quad b = \frac{-5}{2}$$

$$y^2 - 5y + \frac{25}{4} = x^3 - e^x - 3 + \frac{25}{4}$$

$$\left(y - \frac{5}{2}\right)^2 = x^3 - e^x + \frac{13}{4}$$

$$y - \frac{5}{2} = \pm \sqrt{x^3 - e^x + \frac{13}{4}}$$

$$y = \frac{5}{2} + \sqrt{x^3 - e^x + \frac{13}{4}}$$

choose +

$$\text{since } y(0) = \frac{5}{2} + \sqrt{0 - e^0 + \frac{13}{4}}$$

$$= \frac{5}{2} + \sqrt{\frac{9}{4}}$$

$$= 1$$

while

$$\frac{5}{2} - \sqrt{0 - e^0 + \frac{13}{4}} \neq 1$$

$$x^3 - e^x + \frac{13}{4} \geq 0$$

and  $y \neq \frac{5}{2}$

$$\Rightarrow x^3 - e^x + \frac{13}{4} > 0$$

Note the convention

in this class is to exclude points from domain where tangent line is vertical (so no dividing by 0)

We also want our sol'n to be a function (thus choose +/- depending on initial value)

At time  $t=0$ , a tank contains  $Q_0$  lb of salt dissolved in 100 gal of water. Assume that water containing  $\frac{1}{4}$  lb of salt per gallon is entering the tank at a rate of 3 gal/min, and that the well-stirred solution is leaving the tank at the same rate. Find an expression for the amount of salt,  $Q(t)$ , in the tank at any time  $t$ .

\*  $Q(0) = Q_0$

In =  $\frac{1}{4} \frac{\text{lb}}{\text{gal}} * 3 \frac{\text{gal}}{\text{min}}$

100 gal =  $V$

Out =  $3 \frac{\text{gal}}{\text{min}} * \frac{Q}{100} \frac{\text{lb}}{\text{gal}}$

$$\frac{dQ}{dt} = \frac{1}{4}(3) - 3\left(\frac{Q}{100}\right)$$

$$Q' + \frac{3Q}{100} = \frac{3}{4}$$

$$u(t) Q' + u(t) \frac{3Q}{100} = u(t) \frac{3}{4}$$

$$u(t) = e^{\int \frac{3}{100} dt} = e^{(3/100)t}$$

$$e^{3/100 t} Q' + e^{3/100 t} * \frac{3Q}{100} = e^{3/100 t} * \frac{3}{4}$$

$$\int (e^{3/100 t} * y)' = \int e^{3/100 t} * \frac{3}{4}$$

continues on  $\Rightarrow 3.5$



$$\left( e^{\frac{3}{100}t} * y \right)'$$
$$\frac{3y}{100} e^{\frac{3}{100}t} + y' \cdot e^{\frac{3}{100}t}$$

Product Rule checks ✓ ü

continues on  $\Rightarrow$  3.6

3.5

$$e^{\frac{3}{100}t} * y = \frac{100}{3} e^{\frac{3}{100}t} * \frac{3}{4} = 25 e^{\frac{3}{100}t} + C$$

$$Q = 25 + C / e^{\frac{3}{100}t}$$

$$Q(0) = Q_0$$

$$Q_0 = 25 + C$$

$$Q_0 - 25 = C$$

$$Q = 25 + (Q_0 - 25) / e^{\frac{3}{100}t}$$

$$Q = 25 + (Q_0 - 25) e^{-\frac{3t}{100}}$$

$$2y'' - 3y' + \frac{1}{2}y = 0 \Rightarrow 2r^2 - 3r + 1 = 0$$

$$y'' - \frac{3}{2}y' + \frac{1}{2}y = 0$$

$$r^2 - \frac{3}{2}r + \frac{1}{2} = 0$$

$$r = \frac{\frac{3}{2} \pm \sqrt{(-\frac{3}{2})^2 - 4(1)(\frac{1}{2})}}{2(1)}$$

$$r = \frac{\frac{3}{2} \pm \sqrt{\frac{9}{4} - 2}}{2}$$

$$r = 1, \frac{1}{2}$$

$$y_1 = e^{(1)t}$$

$$y_2 = e^{(\frac{1}{2})t}$$

$$y = c_1 y_1 + c_2 y_2$$

$$y = c_1 e^t + c_2 e^{t/2}$$

$$y(0) = 0 \quad y'(0) = 0$$

OR

4

$$2r^2 - 3r + 1 = 0$$

$$\Rightarrow r = \frac{3 \pm \sqrt{9 - 4(2)(1)}}{2(2)}$$

OR

$$2r^2 - 3r + 1 = (2r-1)(r-1)$$

(1)  $0 = c_1 + c_2 \quad e^0 = 1$

$y' = c_1 e^x + \frac{1}{2} c_2 e^{x/2}$

(2)  $0 = c_1 + \frac{1}{2} c_2$

$c_1 = -c_2$

$c_1 = -\frac{1}{2} c_2$

$c_2 = 0 \Rightarrow c_1 = 0$

$y = x^3 - e^x + \frac{1}{3}$   $y(0) = 1$   
 $1 = 1 + \sqrt{-1 + \frac{1}{3}}$   
 $1 = \frac{1}{3} + \sqrt{\frac{2}{3}}$

*(Note: The above equations are circled in red in the original image)*

OK, but related to earlier problem

Solve the equation

6

$$\frac{dy}{dt} = y(2-y)$$

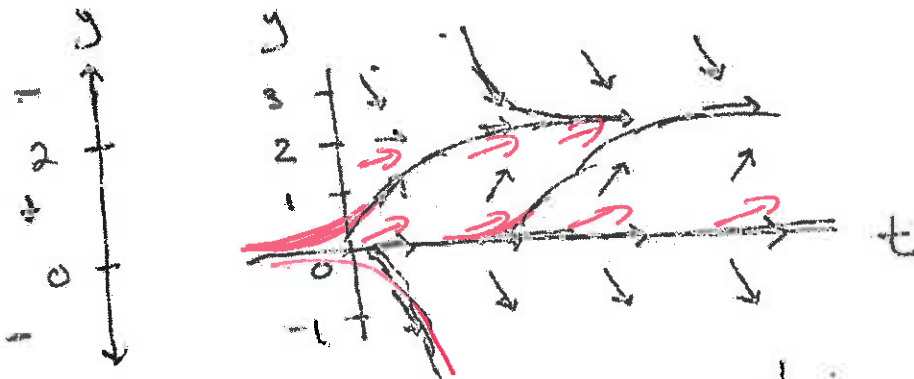
and ~~then~~ find the equilibrium solutions and classify them as asymptotically stable or unstable.

$$0 = y(2-y) :$$

$$y = 0 \text{ or } 2$$

$$\frac{dy}{dt} = 1(2-1) = 1$$

$$\frac{dy}{dt} = -1(2+1) = -3$$



$$\frac{dy}{dt} = 3(-1) = -3$$

$y = 0$  unstable

$y = 2$  stable

$$\frac{dy}{dt} = y(2-y)$$

$$\int \frac{dy}{y(2-y)} = \int dt$$

$$\frac{A}{y} + \frac{B}{2-y} = \frac{1}{y(2-y)}$$

$$\frac{(2-y)A + By}{y(2-y)} = \frac{1}{y(2-y)}$$

$$(2-y)A + By = 1$$

$$A = \frac{1}{2} \quad B = \frac{1}{2}$$

$$(2-y)\frac{1}{2} + \frac{1}{2}y = 1$$

$$\int \left( \frac{1/2}{y} + \frac{1/2}{2-y} \right) dy = \int dt$$

$$\frac{1}{2} \ln y - \frac{1}{2} \ln(2-y) = t + C$$

$$\frac{1}{2} \ln \left( \frac{y}{2-y} \right) = t + C \quad C = 2C_1$$

$$e^{\ln \left( \frac{y}{2-y} \right)} = e^{2t} + C_1 \quad C_2 = e^{C_1}$$

$$\boxed{\frac{y}{2-y} = e^{2t} \cdot C_2}$$

$$C = \frac{1}{2}$$

Solve for y

## 3.4 repeated root

Derivation of general solutions:

Ch 3: we guessed  $e^{rt}$  is a solution and noted that any linear combination of solutions is a solution to a homogeneous linear differential equation.

Section 3.1: If  $b^2 - 4ac > 0$ :  $y = c_1 e^{r_1 t} + c_2 e^{r_2 t}$

Section 3.3: If  $b^2 - 4ac < 0$ :

Changed format of  $y = c_1 e^{r_1 t} + c_2 e^{r_2 t}$  to linear combination of real-valued functions instead of complex valued functions by using Euler's formula:

$$e^{it} = \cos(t) + i \sin(t)$$

Hence  $e^{(d+in)t} = e^{dt} e^{int} = e^{dt} [\cos(nt) + i \sin(nt)]$

Let  $r_1 = d + in, r_2 = d - in$

$$\begin{aligned} y &= c_1 e^{r_1 t} + c_2 e^{r_2 t} \\ &= c_1 e^{dt} [\cos(nt) + i \sin(nt)] + c_2 e^{dt} [\cos(-nt) + i \sin(-nt)] \\ &= c_1 e^{dt} \cos(nt) + i c_1 e^{dt} \sin(nt) + c_2 e^{dt} \cos(nt) - i c_2 e^{dt} \sin(nt) \\ &= (c_1 + c_2) e^{dt} \cos(nt) + i(c_1 - c_2) e^{dt} \sin(nt) \\ &= k_1 e^{dt} \cos(nt) + k_2 e^{dt} \sin(nt) \end{aligned}$$

Section 3.4: If  $b^2 - 4ac = 0$ , then  $r_1 = r_2$ . Hence one solution is  $y = e^{r_1 t}$ . Need second solution.  
 If  $y = e^{rt}$  is a solution,  $y = ce^{rt}$  is a solution.  
 How about  $y = v(t)e^{rt}$ ? **Guess similar**  
 $y' = v'(t)e^{rt} + v(t)re^{rt}$  unknow fn - homog. 3.6  
 $y'' = v''(t)e^{rt} + v'(t)re^{rt} + v'(t)re^{rt} + v(t)r^2 e^{rt}$   
 $= v''(t)e^{rt} + 2v'(t)re^{rt} + v(t)r^2 e^{rt}$   
 $ay'' + by' + cy = 0$

$a(v''(t)e^{rt} + 2v'(t)re^{rt} + v(t)r^2 e^{rt}) + b(v'(t)e^{rt} + v(t)r e^{rt}) + cv e^{rt} = 0$   
 $a(v''(t) + 2v'(t)r + v(t)r^2) + b(v'(t) + v(t)r) + cv(t) = 0$   
 $av''(t) + 2av'(t)r + av(t)r^2 + bv'(t) + bv(t)r + cv(t) = 0$   
 $av''(t) + (2ar + b)v'(t) + (ar^2 + br + c)v(t) = 0$  do as if it was a normal eqn. number of terms is 3  
 $av''(t) + (2a(-\frac{b}{2a}) + b)v'(t) + 0 = 0$  since  $ar^2 + br + c = 0$  and  $r = -\frac{b}{2a}$

$av''(t) + (-b + b)v'(t) = 0$ . Thus  $av''(t) = 0$ .  
 Hence  $v''(t) = 0$  and  $v'(t) = k_1$  and  $v(t) = k_1 t + k_2$   
 Hence  $v(t)e^{r_1 t} = (k_1 t + k_2)e^{r_1 t}$  is a soln **repeated root**  
 Thus  $te^{r_1 t}$  is a nice second solution.

Hence general solution is  $y = c_1 e^{r_1 t} + c_2 t e^{r_1 t}$   
 $r = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$   
**for 3.4 repeated case**

**number**  
~~LINEAR~~  
 L.H.M.S

**3.6**  
 similar  
 unknown fn - homog.  
 similar  
 number of terms is 3  
 do as if it was a normal eqn.  
 since  $ar^2 + br + c = 0$  and  $r = -\frac{b}{2a}$

**repeated root**

**for 3.4 repeated case**