

3.7/8 Mechanical Vibrations:

$$mu''(t) + \gamma u'(t) + ku(t) = F_{external}, \quad m, \gamma, k \geq 0$$

$$mg - kL = 0, \quad F_{damping}(t) = -\gamma u'(t)$$

m = mass,

k = spring force proportionality constant,

γ = damping force proportionality constant

$g = 9.8 \text{ m/sec}^2$ or 32 ft/sec^2 . Weight = mg .

Electrical Vibrations:

Voltage drop across inductor + resistor + capacitor
= the supplied voltage

$$L \frac{dI(t)}{dt} + RI(t) + \frac{1}{C} Q(t) = E(t), \quad L, R, C \geq 0 \text{ and } I = \frac{dQ}{dt}$$

$$LQ''(t) + RQ'(t) + \frac{1}{C} Q(t) = E(t)$$

L = inductance (henrys),

R = resistance (ohms)

C = capacitance (farads)

$Q(t)$ = charge at time t (coulombs)

$I(t)$ = current at time t (amperes)

$E(t)$ = impressed voltage (volts).

1 volt = 1 ohm · 1 ampere = 1 coulomb / 1 farad =
1 henry · 1 amperes / 1 second

Trig background:

$$\cos(y \mp x) = \cos(x \mp y) = \cos(x)\cos(y) \pm \sin(x)\sin(y)$$

Let $c_1 = R\cos(\delta)$, $c_2 = R\sin(\delta)$ in

$$\begin{aligned}c_1\cos(\omega_0 t) + c_2\sin(\omega_0 t) \\&= R\cos(\delta)\cos(\omega_0 t) + R\sin(\delta)\sin(\omega_0 t) \\&= R\cos(\omega_0 t - \delta)\end{aligned}$$

Amplitude = R

frequency = ω_0 (measured in radians per unit time).

period = $\frac{2\pi}{\omega_0}$ phase (displacement) = δ

$c_1 = R\cos(\delta)$, $c_2 = R\sin(\delta)$ implies

$$\begin{aligned}c_1^2 + c_2^2 &= R^2\cos^2(\delta) + R^2\sin^2(\delta) \\&= R^2(\cos^2(\delta) + \sin^2(\delta)) = R^2\end{aligned}$$

and $\frac{R\sin(\delta)}{R\cos(\delta)} = \tan(\delta) = \frac{c_2}{c_1}$

BUT easier to plot to convert Euclidean coordinates $(c_1, c_2) = (R\cos(\delta), R\sin(\delta))$ into polar coordinates $(R, \delta) = (\text{length}, \text{angle})$.

3.7: Homogeneous equation (no external force):

$$mu''(t) + \gamma u'(t) + ku(t) = 0, \quad m, \gamma, k \geq 0$$

$$r_1, r_2 = \frac{-\gamma \pm \sqrt{\gamma^2 - 4km}}{2m}$$

Critical damping: $\gamma = 2\sqrt{km}$

$$\gamma^2 - 4km = 0: u(t) = (c_1 + c_2 t)e^{r_1 t}$$

Note $r_1 = -\frac{\gamma}{2m} < 0$. **Thus** $u(t) \rightarrow 0$ as $t \rightarrow \infty$

Overdamped: $\gamma > 2\sqrt{km}$

$$\gamma^2 - 4km > 0: u(t) = c_1 e^{r_1 t} + c_2 e^{r_2 t}$$

Note $r_1, r_2 < 0$. **Thus** $u(t) \rightarrow 0$ as $t \rightarrow \infty$

Example $u(t) = 4e^{-t} - 3e^{-2t}$

If $t > 0$, $4e^{-t} > 3e^{-2t}$

As $t \rightarrow \infty$, $e^{-2t} \rightarrow 0$ faster than $e^{-t} \rightarrow 0$

If $t < 0$, $4e^{-t} < 3e^{-2t}$

As $t \rightarrow -\infty$, $e^{-2t} \rightarrow \infty$ faster than $e^{-t} \rightarrow \infty$

Underdamped: $\gamma < 2\sqrt{km}$

$$\begin{aligned}\gamma^2 - 4km < 0: u(t) &= e^{-\frac{\gamma t}{2m}} (c_1 \cos \mu t + c_2 \sin \mu t) \\ &= e^{-\frac{\gamma t}{2m}} R \cos(\mu t - \delta) \\ \text{where } c_1 &= R \cos(\delta), c_2 = R \sin(\delta)\end{aligned}$$

μ = quasi frequency, $\frac{2\pi}{\mu}$ = quasi period

Note if $\gamma \neq 0$, **then** $u(t) \rightarrow 0$ **as** $t \rightarrow \infty$

Note if $\gamma = 0$, then

NOTE if $\gamma \neq 0$, **then homogeneous solution goes to 0 as** $t \rightarrow \infty$.

Thus initial values have very little effect on the long-term behaviour of solution if $\gamma \neq 0$.

Note: The larger γ is, the faster the homogeneous solution goes to 0 as $t \rightarrow \infty$.

3.8: $F_{external} \neq 0$

$$mu''(t) + \gamma u'(t) + ku(t) = F_{external}, \quad m, \gamma, k \geq 0$$

General solution: $u(t) = c_1\phi_1 + c_2\phi_2 + \psi$

where ϕ_1, ϕ_2 are homogeneous solutions and ψ is a non-homogeneous solution.

NOTE if $\gamma \neq 0$, then homogeneous solution

$$c_1\phi_1 + c_2\phi_2 \text{ goes to } 0 \text{ as } t \rightarrow \infty.$$

Thus if $\gamma \neq 0$, then $u(t) \rightarrow \psi$ as $t \rightarrow \infty$.

No damping ($\gamma = 0$) example: $u'' + u = \cos(t)$

Step 1: Solve homogeneous $u'' + u = 0$

$$r^2 + 1 = 0 \text{ implies } r = \pm i$$

Homogeneous solution $u(t) = c_1\cos(t) + c_2\sin(t)$

Step 2: Find a non-homogeneous solution.

Guess $u(t) =$

Plug in plus lots of work implies $A = 0$ and $B = \frac{1}{2}$

Thus general non-homogeneous solution:

$$u(t) = c_1\cos(t) + c_2\sin(t) + \frac{1}{2}t\sin(t)$$

No damping example $u'' + u = \cos(\omega t)$ where $\omega \neq 1$.

Step 1: Solve homogeneous $u'' + u = 0$

$$r^2 + 1 = 0 \text{ implies } r = \pm i$$

Homogeneous solution $u(t) = c_1 \cos(t) + c_2 \sin(t)$

Step 2: Find a non-homogeneous solution.

Since $\omega \neq 1$, guess $u(t) =$

Trig background:

$$\cos(y \mp x) = \cos(x \mp y) = \cos(x)\cos(y) \pm \sin(x)\sin(y)$$

$$\cos(u) + \cos(v) = 2\cos\left(\frac{u+v}{2}\right)\cos\left(\frac{u-v}{2}\right)$$

$$\cos(u) - \cos(v) = -2\sin\left(\frac{u+v}{2}\right)\sin\left(\frac{u-v}{2}\right)$$

$$\sin(u) + \sin(v) = 2\sin\left(\frac{u+v}{2}\right)\cos\left(\frac{u-v}{2}\right)$$

$$\sin(u) - \sin(v) = \sin(u) + \sin(-v) = 2\sin\left(\frac{u-v}{2}\right)\cos\left(\frac{u+v}{2}\right) \blacksquare$$

Derivation:

$$\text{Let } x = \left(\frac{u+v}{2}\right) \text{ and } y = \left(\frac{u-v}{2}\right)$$

$$\cos(u) = \cos\left(\left(\frac{u+v}{2}\right) + \left(\frac{u-v}{2}\right)\right)$$

$$= \cos\left(\frac{u+v}{2}\right)\cos\left(\frac{u-v}{2}\right) - \sin\left(\frac{u+v}{2}\right)\sin\left(\frac{u-v}{2}\right)$$

$$\cos(v) = \cos\left(\left(\frac{u+v}{2}\right) - \left(\frac{u-v}{2}\right)\right)$$

$$= \cos\left(\frac{u+v}{2}\right)\cos\left(\frac{u-v}{2}\right) + \sin\left(\frac{u+v}{2}\right)\sin\left(\frac{u-v}{2}\right)$$

$$\text{Ex: } u(t) = \cos(t) + \cos(3t) =$$

Graph:

Example with damping:

$$u'' + \gamma u' + u = \cos(\omega t) \text{ where } \gamma \text{ is small.}$$