### Lecture 1: The Euler characteristic

of a series of preparatory lectures for the Fall 2013 online course MATH:7450 (22M:305) Topics in Topology: Scientific and Engineering Applications of Algebraic Topology

Target Audience: Anyone interested in **topological data analysis** including graduate students, faculty, industrial researchers in bioinformatics, biology, computer science, cosmology, engineering, imaging, mathematics, neurology, physics, statistics, etc.

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http://www.math.uiowa.edu/~idarcy/AppliedTopology.html



# Counting







Example:



7 vertices,9 edges,2 faces.





3 vertices, 3 edges, 1 face. 6 vertices, 9 edges, 4 faces.

## The formula: Euler characteristic

#### **Euler characteristic (simple form):**

 $\boldsymbol{\chi}$  = number of vertices – number of edges + number of faces

Or in short-hand,

## x = |V| - |E| + |F|

where V = set of vertices E = set of edges F = set of faces

& the notation |X| = the number of elements in the set X.























#### Video Insert illustrating topology



## Note a coffee cup is topologically equivalent to a donut



gif from https://en.wikipedia.org/wiki/ File:Mug\_and\_Torus\_morph.gif









That means that if two objects are topologically the same, they have the same Euler characteristic.



**x**=1



**x**=1





**x**=1



**x**=1



**x**=1





That means that if two objects are topologically the same, they have the same Euler characteristic.

Example:

Euler characteristic		
2	sphere = { x in R <sup>3</sup> :   x    = 1 }	
1	ball ={xin R <sup>3</sup> :   x  ≤1}	
	disk = { x in $R^2$ :   x    $\le 1$ }	
	$= \{ x \text{ in } R :   x   \le 1 \}$	••



That means that if two objects are topologically the same, they have the same Euler characteristic.

But objects with the same Euler characteristic need not be topologically equivalent.  $\checkmark$ 

### Let *R* be a subset of *X* A *deformation retrac*t of *X* onto *R* is a continuous map $F: X \times [0, 1] \rightarrow X$ , $F(x, t) = f_t(x)$ such that $f_0$ is the identity map, $f_1(X) = R$ , and $f_t(r) = r$ for all *r* in *R*.



If R is a deformation retract of X, then  $\chi(R) = \chi(X)$ .

Let *R* be a subset of *X* 

- A *deformation retract* of X onto R is a
- continuous map  $F: X \times [0, 1] \rightarrow X, F(x, t) = f_t(x)$

such that  $f_0$  is the identity map,

![](_page_25_Figure_5.jpeg)

![](_page_26_Figure_0.jpeg)

Mobius band and torus images from https://en.wikipedia.org/wiki/Euler characteristic

![](_page_27_Figure_0.jpeg)

2-dimensional orientable surface without boundary	
	2
	0
	-2
	-4
ī	-4

Graphs: Identifying Trees

Defn: A *tree* is a connected graph that does not contain a cycle

![](_page_29_Figure_2.jpeg)

![](_page_30_Picture_1.jpeg)

#### **x** = 2

#### x = |V| - |E| + |F|

#### x = 2 - 1 = 1

![](_page_32_Picture_2.jpeg)

#### x = 3 - 1 = 2

#### x = |V| - |E| + |F|

![](_page_33_Picture_1.jpeg)

x = 3 - 2 = 1

#### x = |V| - |E| + |F|

![](_page_34_Picture_1.jpeg)

x = 4 - 3 = 1

![](_page_35_Picture_1.jpeg)

x = 5 - 4 = 1

#### x = |V| - |E| + |F|

![](_page_36_Picture_1.jpeg)

![](_page_37_Picture_1.jpeg)

#### x = |V| - |E| + |F|

![](_page_38_Picture_1.jpeg)