Hardware Multiplication

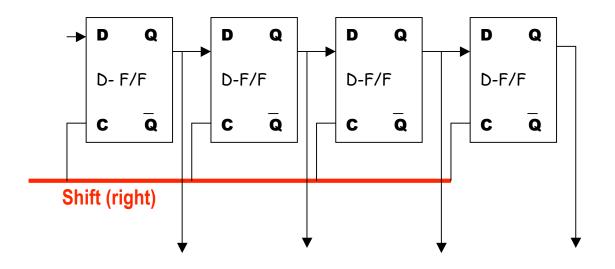
| Multiplicand | | | | 1 | 0 | 0 | 1 |
|--------------|---|---|---|---|---|---|---|
| Multiplier | | | | 1 | 0 | 1 | 0 |
| | | | | 0 | 0 | 0 | 0 |
| | | | 1 | 0 | 0 | 1 | 0 |
| | | 0 | 0 | 0 | 0 | 0 | 0 |
| | 1 | 0 | 0 | 1 | 0 | 0 | 0 |
| Product | 1 | 0 | 1 | 1 | 0 | 1 | 0 |

The basic operations are ADD and SHIFT. Now let us see how it is implemented by hardware. By now, you know all the building blocks.

The Building Blocks

<u>A shift register</u>

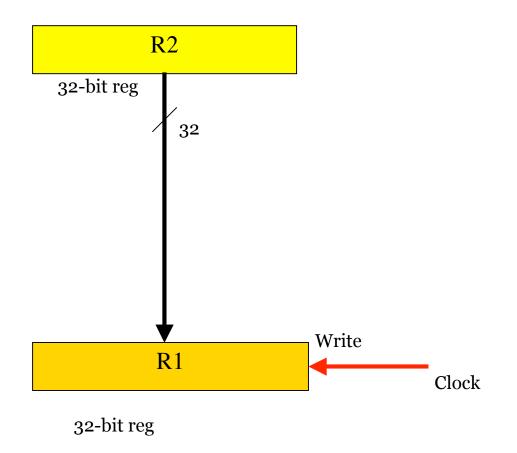
Review how a D flip-flop works



With each clock pulse on the shift line, data moves one place to the right.

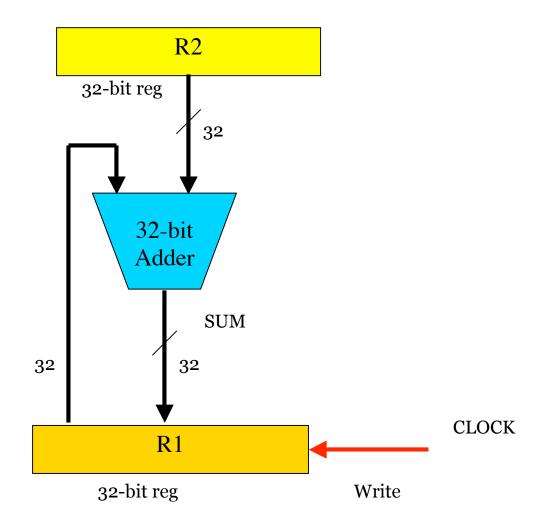
How to implement a simple register transfer r1:= r2?

Executing r1:= r2



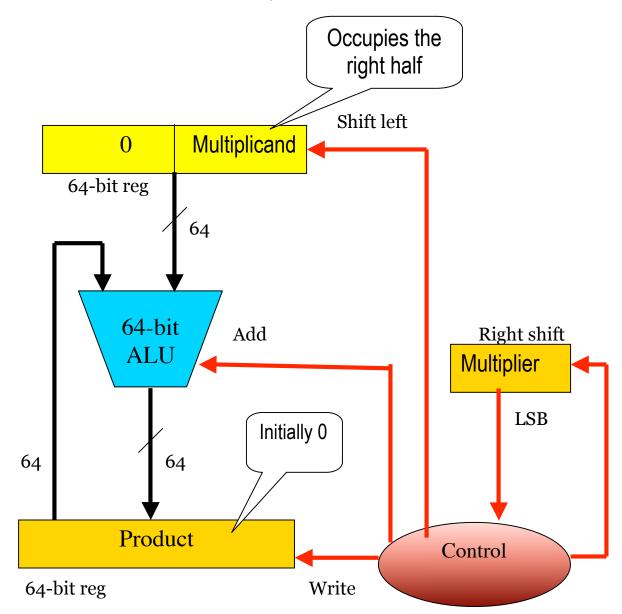
It requires only one clock pulse to complete the operation.

Executing r1 := r1 + r2



It requires only one clock pulse to complete the operation.

<u> A Hardware Multiplier</u>



If LSB of Multiplier = 1 then *add* else *skip*; Shift left multiplicand & shift right multiplier

How to implement the control unit?

<u>Division</u>

The restoring division algorithm follows the simple idea from the elementary school days. It involves subtraction and shift. Here is an implementation by hardware

