## Hardware Multiplication

| Multiplicand |  |  | 1 | 0 | 0 | 1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Multiplier |  | 1 | 0 | 1 | 0 |  |
|  |  |  |  | 0 | 0 | 0 |
|  |  |  | 1 | 0 | 0 | 1 |
|  |  | 0 | 0 | 0 | 0 | 0 |
|  | 1 | 0 | 0 | 1 | 0 | 0 |
| Product | 1 | 0 | 1 | 1 | 0 | 1 |

The basic operations are ADD and SHIFT. Now let us see how it is implemented by hardware.

By now, you know all the building blocks.

## The Building Blocks

## A shift register

Review how a $D$ flip-flop works


With each clock pulse on the shift line, data moves one place to the right.

## Executing r1:= r2

How to implement a simple register transfer r1:= r2?


32-bit reg

It requires only one clock pulse to complete the operation.

## Executing r1:= r1 + r2



It requires only one clock pulse to complete the operation.

## A Hardware Multiplier



If LSB of Multiplier $=1$ then add else skip; Shift left multiplicand \& shift right multiplier

## Division

The restoring division algorithm follows the simple idea from the elementary school days. It involves subtraction and shift. Here is an implementation by hardware


