# Chord Advanced issues

#### **Analysis**

#### Theorem. Search takes O (log N) time

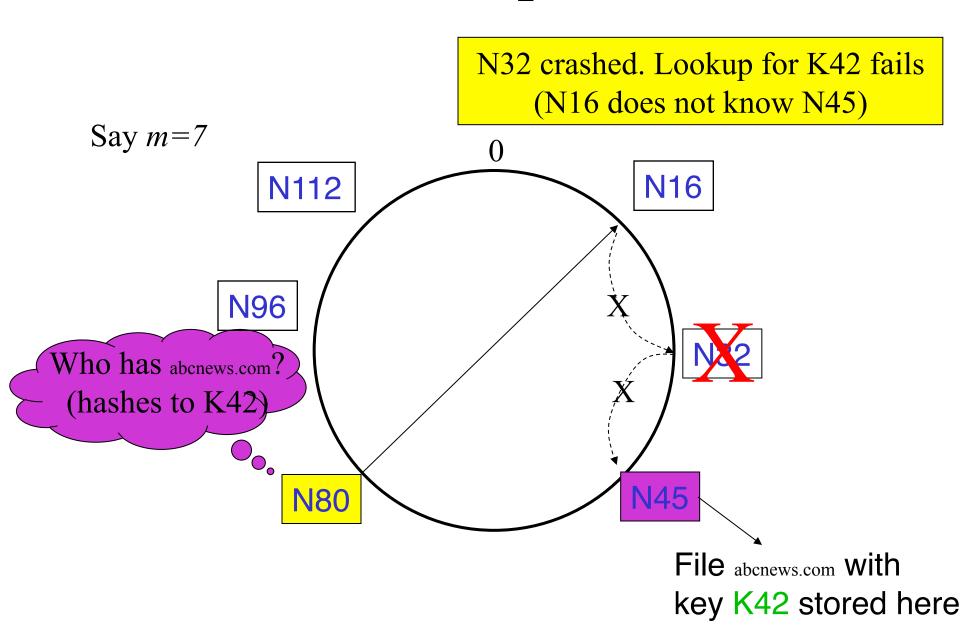
(Note that in general, when there are m fingers, 2<sup>m</sup> may be much larger than N)

Proof. After  $log\ N$  forwarding steps, distance to key is at most  $2^m/N$  (N=  $2^{\log N}$ ). Number of nodes in the remaining range is O (log N) with high probability (this is property of consistent hashing). So by using *successors* in that range, it will take at most an additional O (log N) forwarding steps.

#### Analysis (contd.)

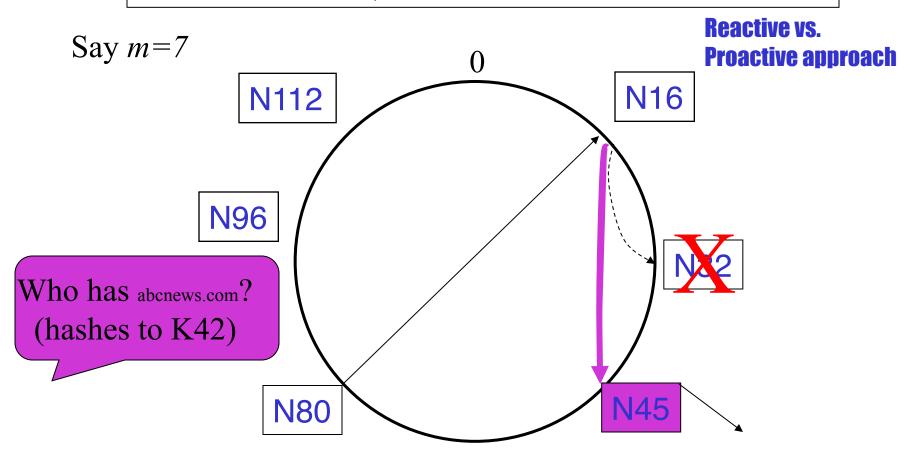
O(log N) search time is true if finger and successor entries correct. But what if these entries are wrong (which is possible during join or leave operations, or process crash?

#### Search under peer failures



#### Search under peer failures

One solution: maintain *r* multiple *successor* entries in case of a failure, use other successor entries.



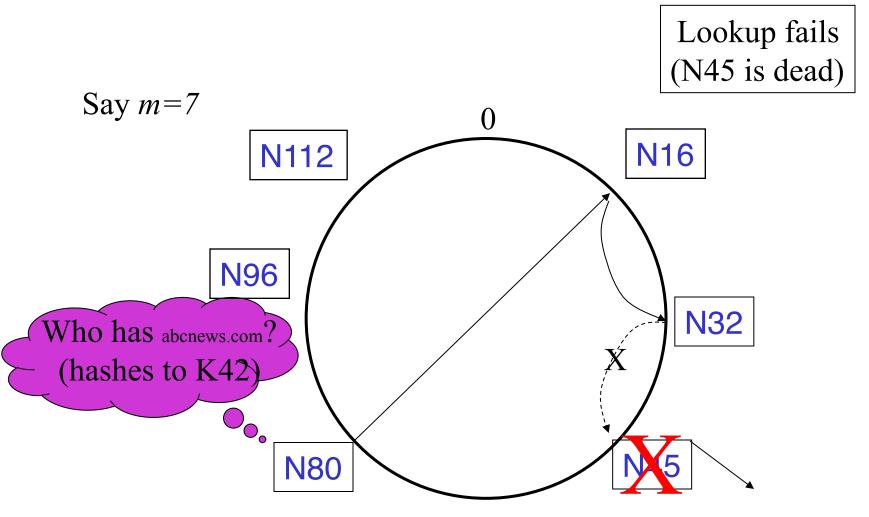
File abcnews.com with key K42 stored here

#### Search under peer failures

Choosing r=2log(N) suffices to maintain the correctness "with high probability." Say 50% of nodes fail (i.e prob of failure = ½). For a given node, Probability (at least one successor alive) =

$$1 - \left(\frac{1}{2}\right)^{2\log N} = 1 - \frac{1}{N^2}$$

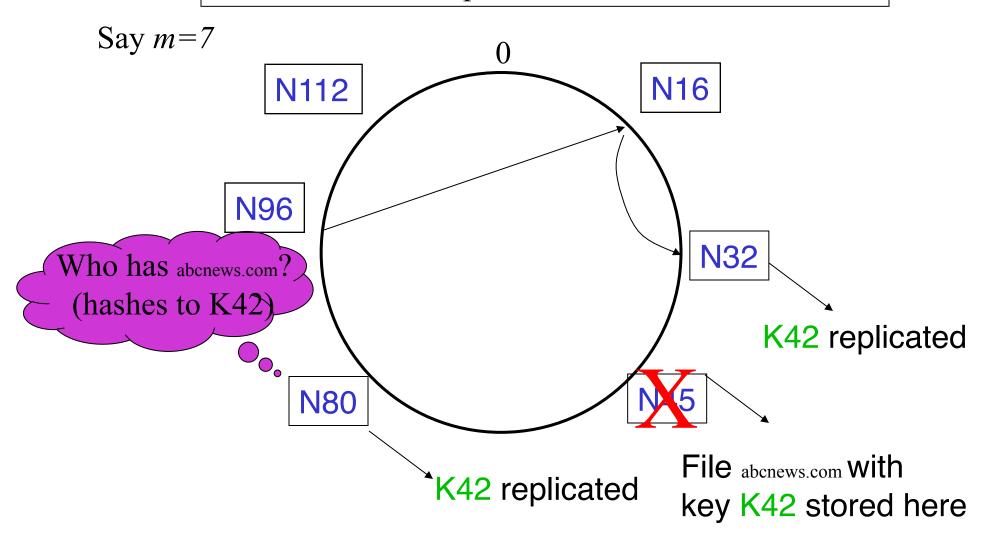
### Search under peer failures (2)



File abcnews.com with key K42 stored here

#### Search under peer failures (2)

One solution: replicate file/key at r successors and predecessors



#### Dealing with dynamic issues

Peers fail

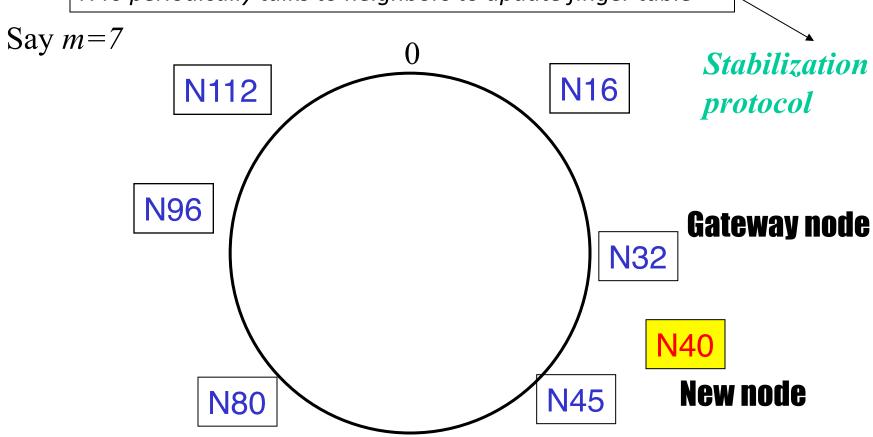
New peers join

Peers leave

Need to update *successor*s and *fingers*, and ensure keys reside in the right places

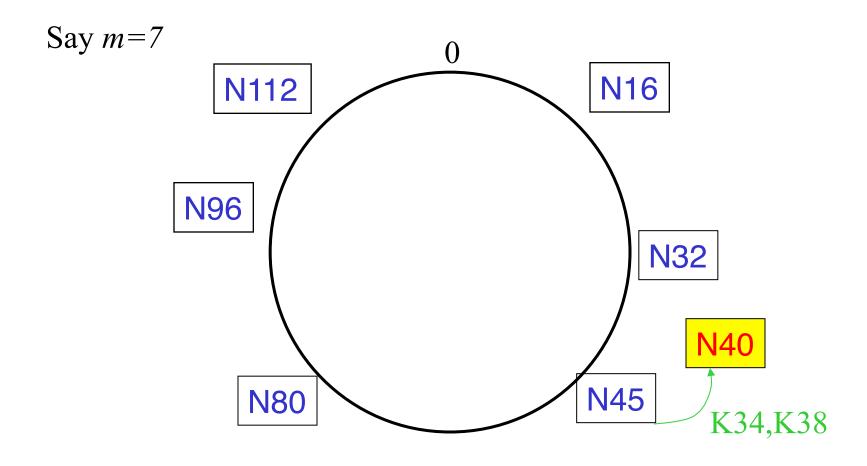
### New peers joining

Some gateway node directs N40 to its successor N45 N32 updates successor to N40 N40 initializes successor to N45, and obtains fingers from it N40 periodically talks to neighbors to update finger table

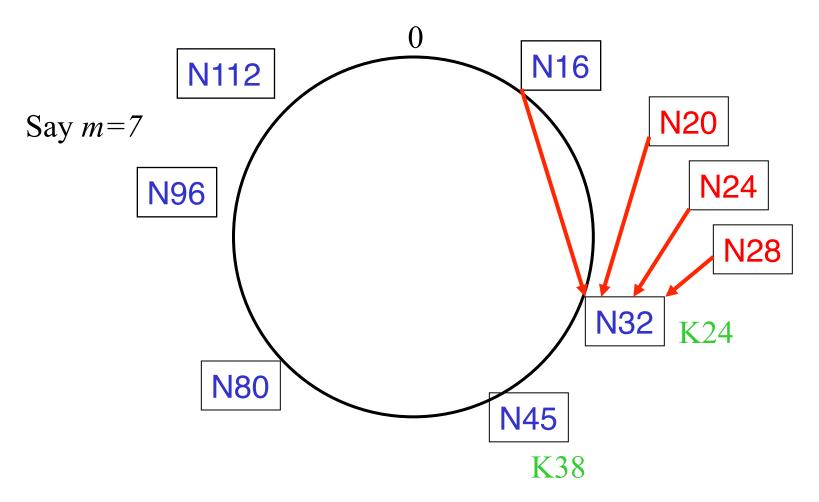


# New peers joining (2)

N40 may need to copy some files/keys from N45 (files with fileid between 32 and 40)



#### Concurrent join

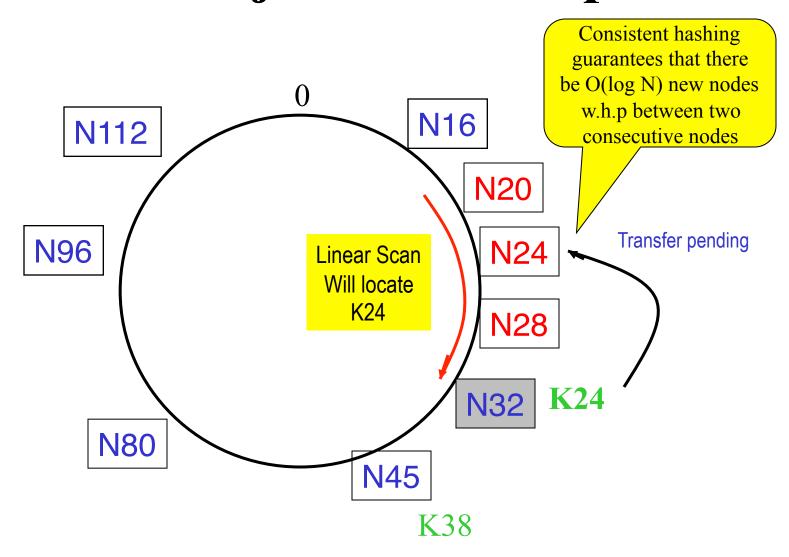


Argue that each node will eventually be reachable

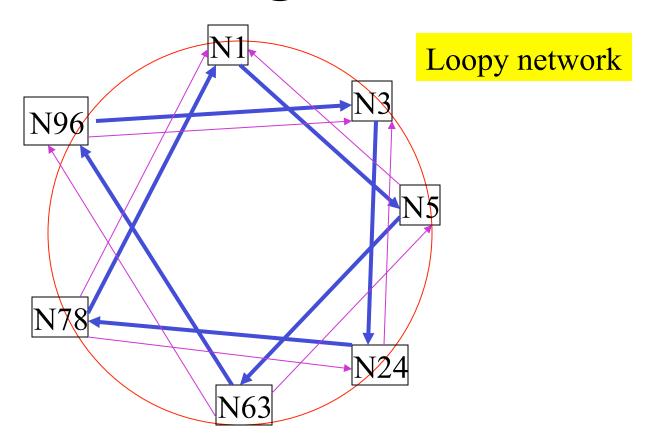
#### Effect of join on lookup

If in a stable network with N nodes, another set of N nodes joins the network, and the join protocol correctly sets their successors, then lookups will take O(log N) steps w.h.p

#### Effect of join on lookup

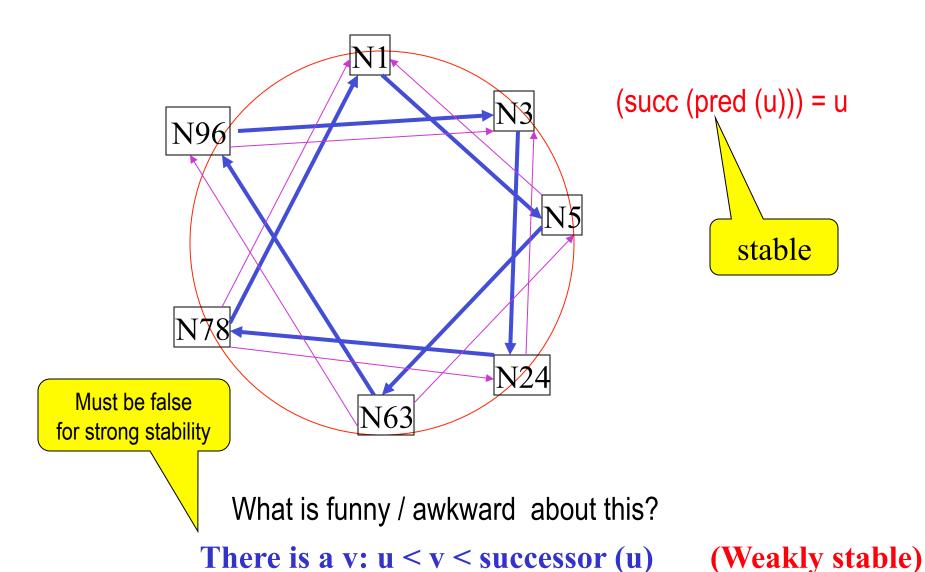


#### Weak and Strong Stabilization



For all u: (successor (predecessor (u))) = u. Still it is **weakly stable** but not **strongly stable**. Why?

### Loopy network



#### Strong stabilization

The key idea of recovery from loopiness is: Let each node u ask its successor to walk around the ring until it reaches a node  $v : u < v \le successor(u)$ . If

There exists a v: u <v < successor(u)

then loopiness exists, and reset successor(u):=v

Takes  $O(N^2)$  steps. But loopiness is a rare event.

No protocol for recovery exists from a split ring.

#### New peers joining (3)

 A new peer affects O(log N) other finger entries in the system. So, the number of messages per peer join= O(log(N)\*log(N))

Similar set of operations for dealing with peers leaving

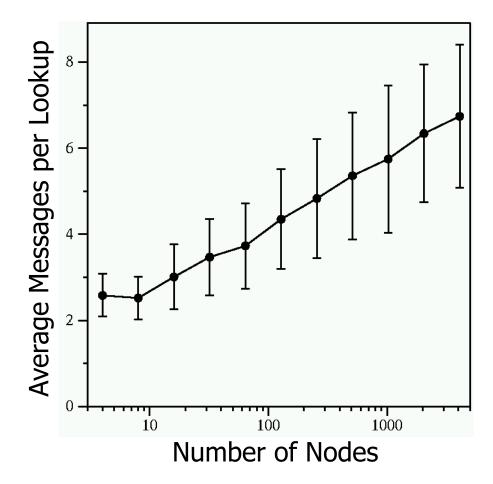
#### **Bidirectional Chord**

Each node u has fingers to

How does it help?

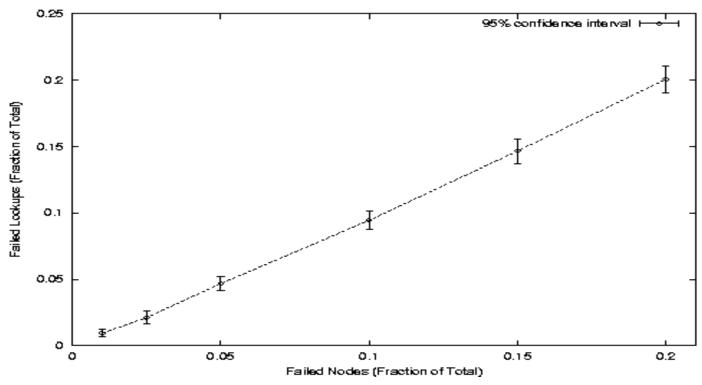
## Cost of lookup

- □ Cost is O(Log N) as predicted by theory
- □ constant is 1/2



#### Robustness

- □ Simulation results: static scenario
- □ Failed lookup means original node with key failed (no replica of keys)



Result implies good balance of keys among nodes!

# Strengths

- Consistent hashing guarantees balance
- Proven performance in many different aspects
  - "with high probability" proofs
- Good tolerance to random node failures

#### Weakness

- Network proximity not addressed
- Protocol security
  - Malicious data insertion
  - □ Malicious Chord table information
- Keyword search