

# Distributed Consensus

Reaching agreement is a fundamental problem in distributed computing. Some examples are

*Leader election / Mutual Exclusion*

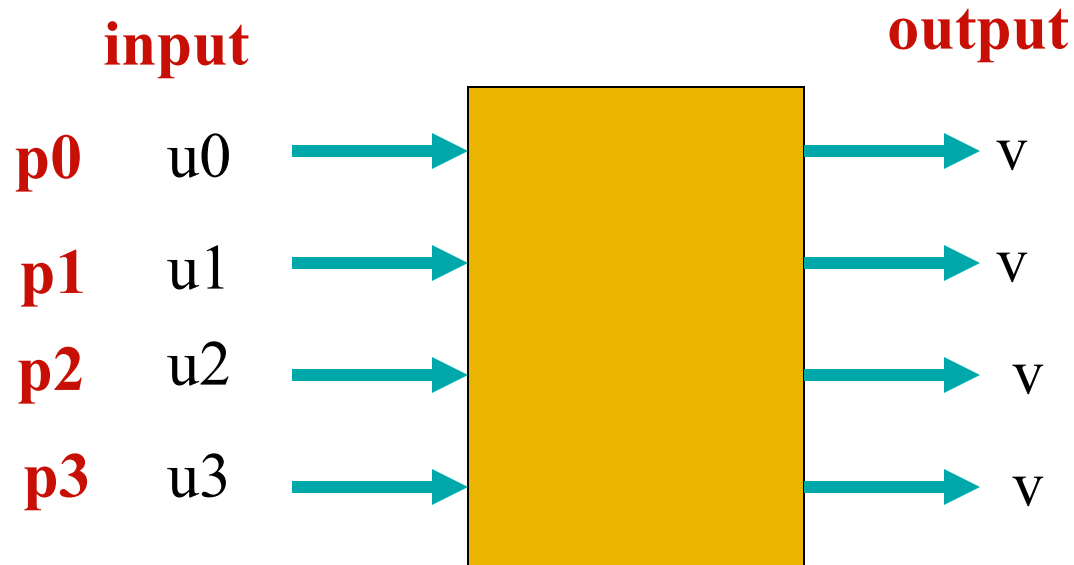
*Commit or Abort in distributed transactions*

*Reaching agreement about which process has failed*

*Clock phase synchronization*

*Air traffic control system: all aircrafts must have the same view*

# Problem Specification



Each process  $p_k$  has an input value  $u_k$ . These processes run a program to exchange their inputs, so that finally the outputs of all non-faulty processes become identical, even if one or more processes fail at any time. Furthermore, the output  $v$  must be equal to the value of at least one process.

# Problem Specification

**Termination.** Every non-faulty process must eventually decide.

**Agreement.** The final decision of every non-faulty process must be identical.

**Validity.** If every non-faulty process begins with the same initial value  $v$ , then their final decision must be  $v$ .

# Observation

- If there is no failure, then reaching consensus is trivial. All-to-all broadcast followed by applying a choice function ...
- Consensus in presence of failures can however be complex. The complexity depends on the system model and the type of failures

# Asynchronous Consensus

Seven members of a busy household decided **to hire a cook**, since they do not have time to prepare their own food. Each member *separately interviewed* every applicant for the cook's position. Depending on how it went, each member voted **"yes" (means "hire")** or **"no" (means "don't hire")**.

These members will now have to communicate with one another to **reach a uniform final decision** about whether the applicant will be hired. The process will be repeated with the next applicant, until someone is hired.

*Consider various modes of communication like **shared memory** or **message passing**. Also assume that one process (i.e. a member) may crash at any time.*

# Asynchronous Consensus

## Theorem.

In a **purely asynchronous** distributed system, the consensus problem is **impossible** to solve if even a **single process crashes**.

Result due to **Fischer, Lynch, Patterson** (commonly known as FLP 85). Received the most influential paper award of ACM PODC in 2001

# Proof

## *Bivalent and Univalent states*

A decision state is **bivalent**, if starting from that state, there exist two distinct executions leading to two distinct decision values **0** or **1**. Otherwise it is **univalent**.

A **univalent** state may be either **0-valent** or **1-valent**.

# Proof (continued)

## Lemma.

No execution can lead from a 0-valent to a 1-valent state or vice versa.

## Proof.

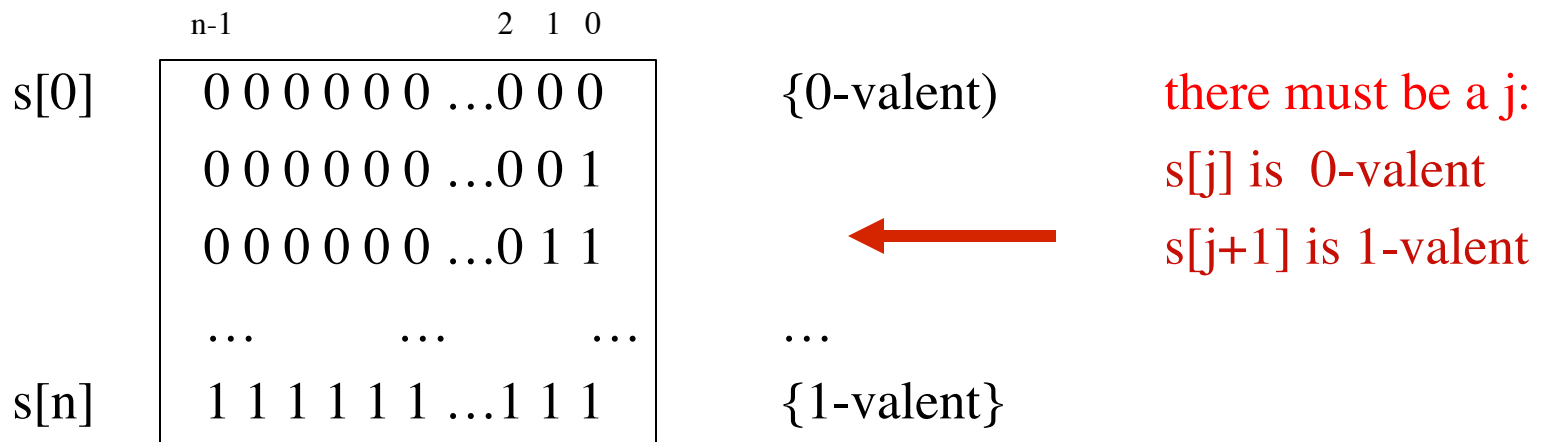
Follows from the definition of 0-valent and 1-valent states.



# Proof

**Lemma.** Every consensus protocol must have a **bivalent initial state**.

**Proof by contradiction.** *Suppose not. Then consider the following input patterns:*

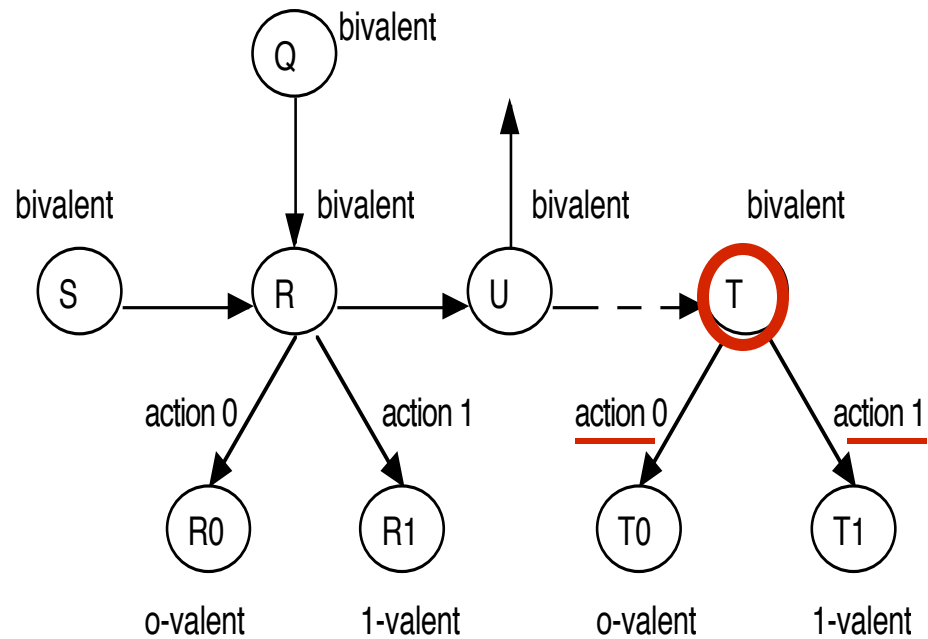


What if process j crashes at the first step?

# Proof of FLP (continued)

## Lemma.

In a consensus protocol, starting from any initial bivalent state **S**, there must exist a reachable bivalent state **T**, such that every action taken by some process **p** in state **T** leads to either a 0-valent or a 1-valent state.



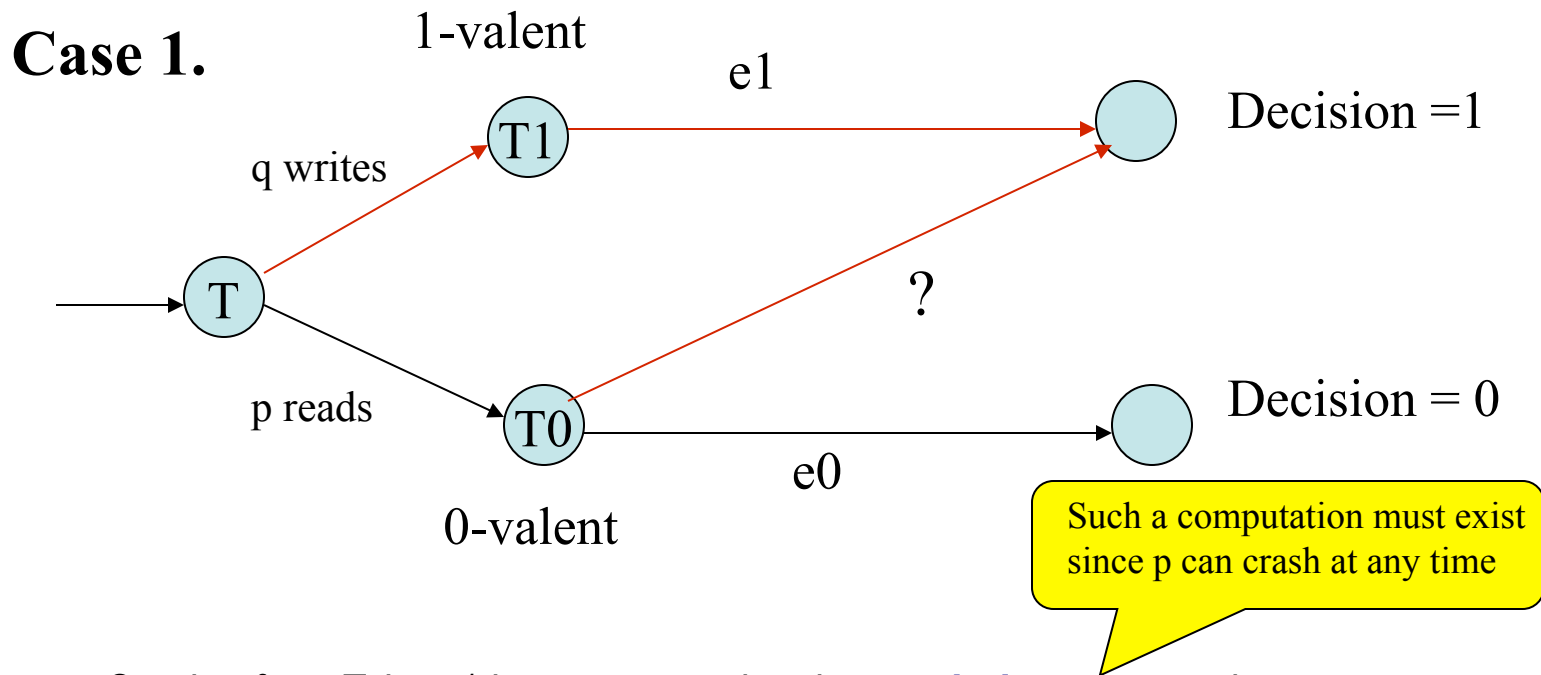
Note that bivalent states should not form a cycle, since it affects termination.

Actions 0 and 1 from T must be taken by the **same process** **p**. Why?

# Proof of FLP (continued)

*Assume shared memory communication.*

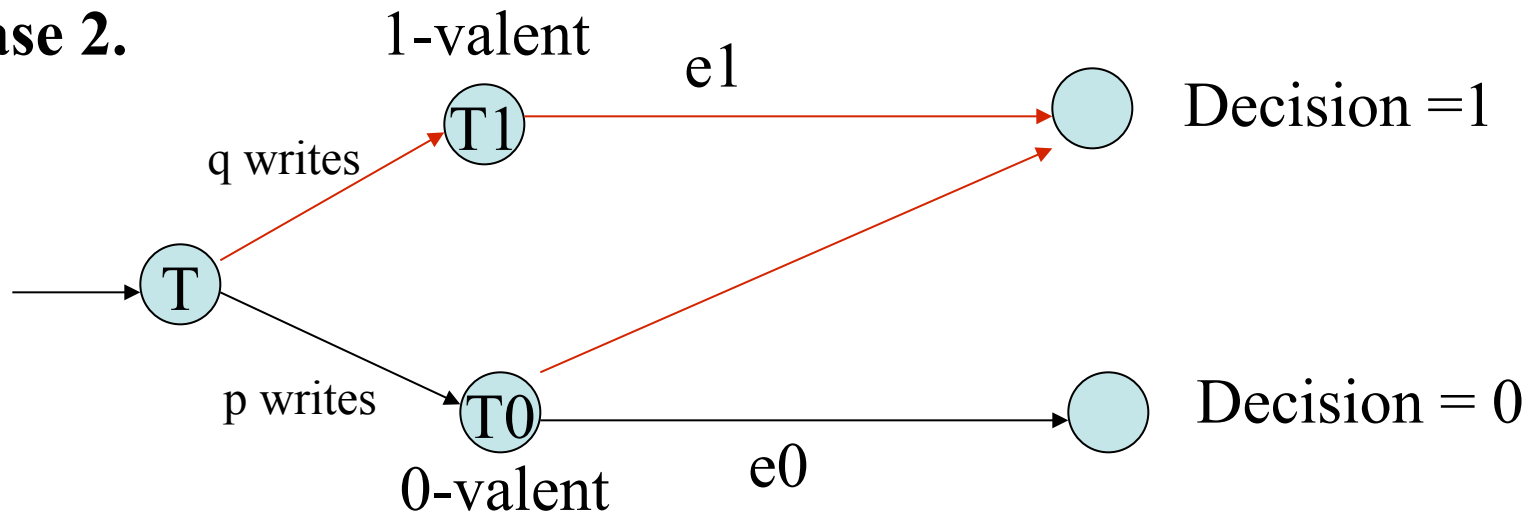
*Also assume that  $p \neq q$ . Various cases are possible*



Starting from T, let  $e_1$  be a computation that **excludes any step** by p. Let p crash after reading. Then  $e_1$  is a valid computation from  $T_0$  too. To all non-faulty processes, these two computations are identical, but the outcomes are different! This is not possible! But then, starting from a **0-valent** state, a computation reaches **decision = 1** which is not feasible

# Proof (continued)

Case 2.



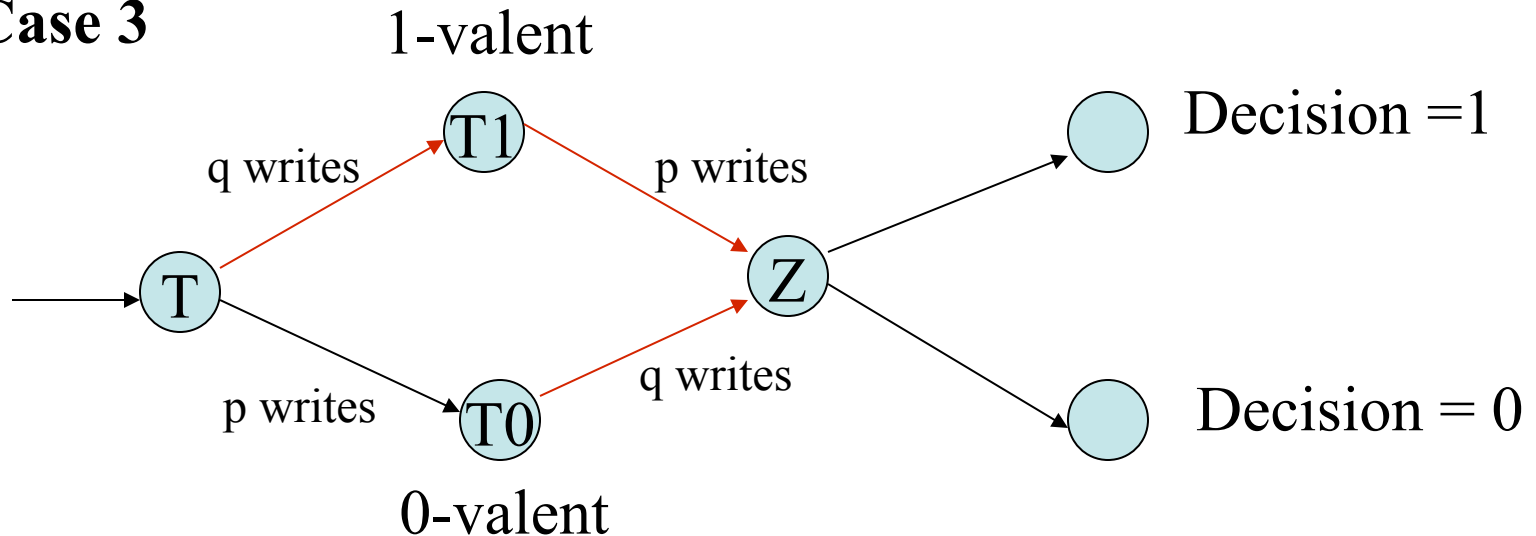
Both write on the **same variable**, and **p writes first**.

- From  $T$ , let  $e1$  be a computation that **excludes any step** by  $p$ .
- Let  $p$  crash after writing. Process  $q$ 's writing will overwrite it.  
Therefore  $e1$  is a valid computation from  $T0$  too.

**To all non-faulty processes, these two computations are identical, (q overwrites the value written by p) but the outcomes are different!**

# Proof (continued)

Case 3



Let both  $p$  and  $q$  write, **but on different variables.**

Then regardless of the order of these writes, both computations lead

to the same *intermediate global state Z*, which must be univalent.

Is  $Z$  1-valent or 0-valent? Both are absurd.

# Proof (continued)

Similar arguments can be made for communication using the message passing model too (See Nancy Lynch's book). These lead to the fact that  $p$ ,  $q$  cannot be distinct processes, and  $p = q$ . Call  $p$  the **decider** process.

What if  $p$  crashes in state  $T$ ? No consensus is reached!

# Conclusion

- In a purely asynchronous system, there is no solution to the consensus problem if a single process crashes..
- Note that this is true for **deterministic algorithms only. Solutions do exist** for the consensus problem using **randomized algorithm**, or using the **synchronous model**.

# Consensus in Synchronous Systems: Byzantine Generals Problem

Describes and solves the consensus problem on the **synchronous model of communication**. Processor speeds have lower bounds and communication delays have upper bounds.

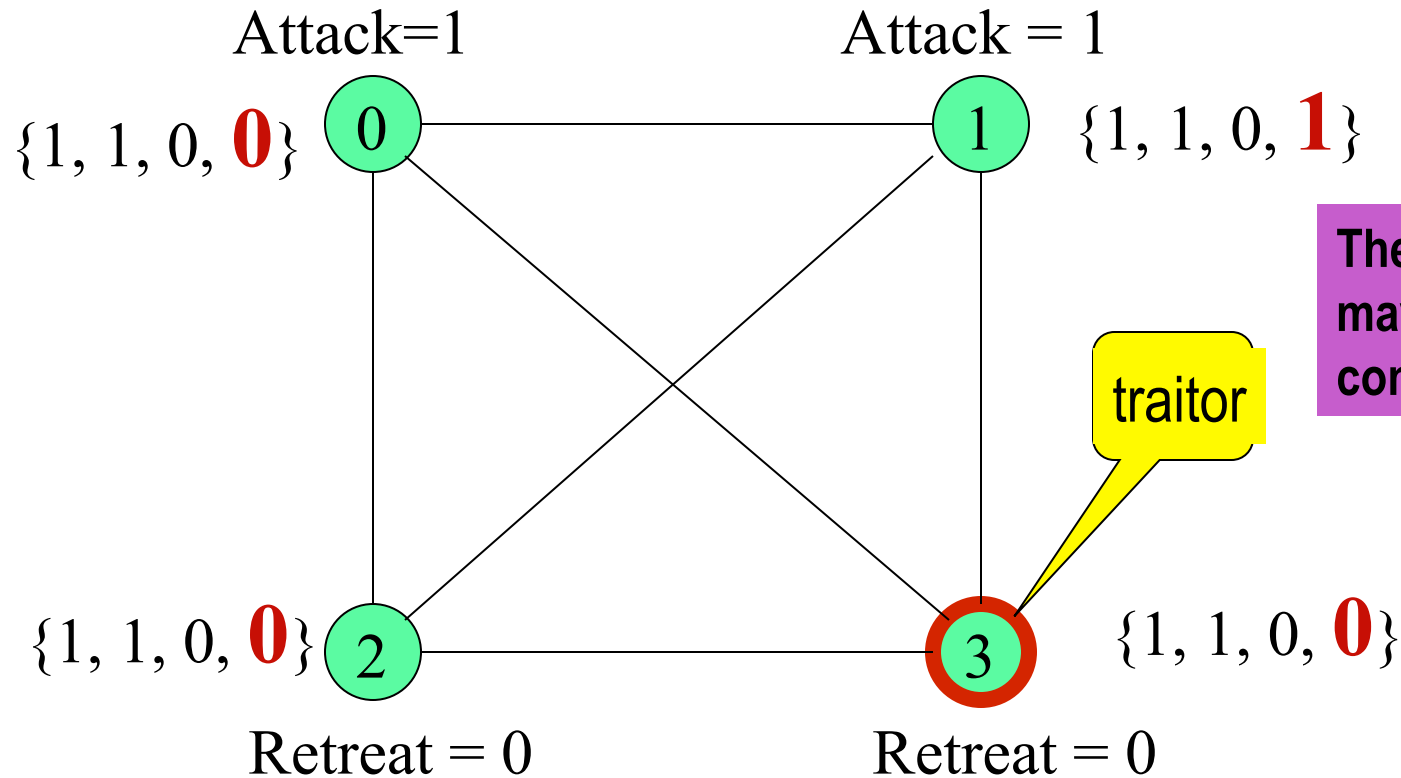
- The network is *completely connected*
- Processes undergo **byzantine failures**, the worst possible kind of failure



# Byzantine Generals Problem

- $n$  generals  $\{0, 1, 2, \dots, n-1\}$  decide about whether to "attack" or to "retreat" during a particular phase of a war. The goal is to **agree upon the same plan of action.**
- Some generals may be "traitors" and therefore send either no input, or send conflicting inputs to prevent the "loyal" **generals from reaching an agreement.**
- Devise a strategy, by which every loyal general eventually agrees upon the same plan, regardless of the action of the traitors.

# Byzantine Generals



Every general will broadcast his judgment to everyone else. These are inputs to the consensus protocol.

# Byzantine Generals

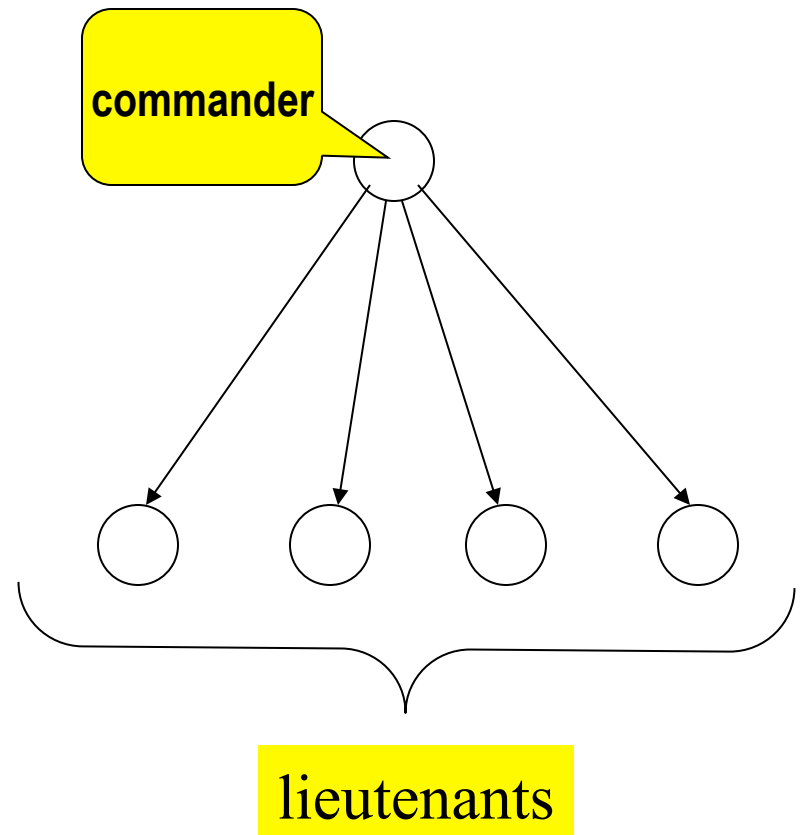
We need to devise a protocol so that every peer (call it a **lieutenant**) *receives the same value* from any given general (call it a **commander**). Clearly, the lieutenants will have to use **secondary information**.

Note that the roles of the **commander** and the **lieutenants** will rotate among the generals.

# Interactive consistency specifications

**IC1.** Every loyal lieutenant receives the **same order** from the commander.

**IC2.** If the commander is loyal, then every loyal lieutenant receives the order that the commander sends.



# The Communication Model

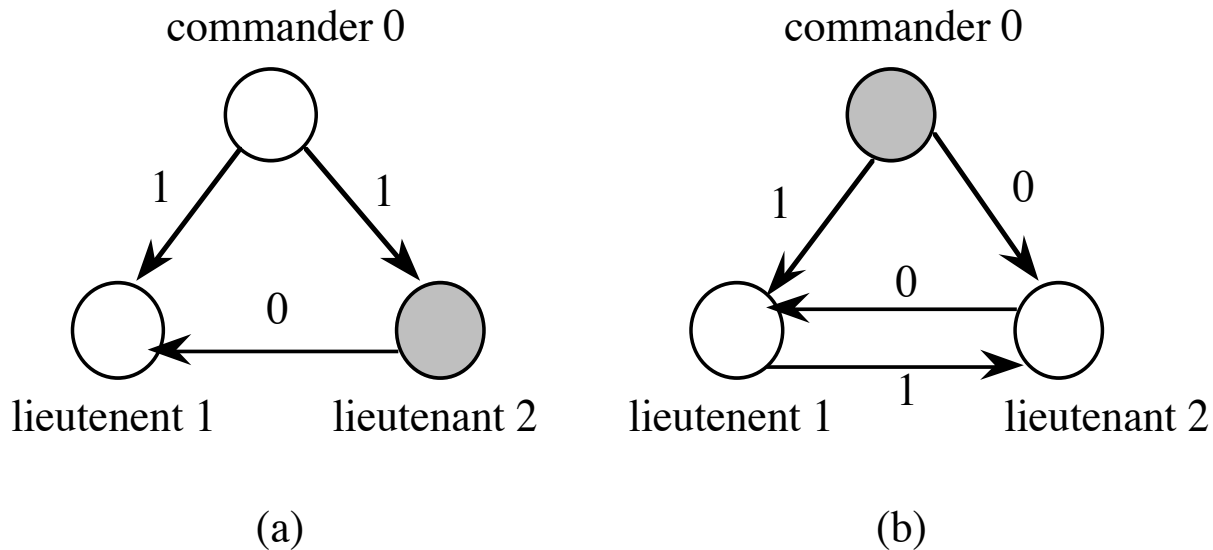
## *Oral Messages*

1. Messages are not corrupted in transit.
2. Messages can be lost, but the absence of message can be detected.
3. When a message is received (or its absence is detected), the receiver knows the identity of the sender (or the defaulter).

**OM(m)** represents an *interactive consistency protocol* in presence of at most **m** traitors.

# An Impossibility Result

Using **oral messages**, **no solution** to the Byzantine Generals problem exists with **three or fewer generals** and **one traitor**. Consider the two cases:



In (a), to satisfy IC2, lieutenant 1 must trust the commander, but in IC2, the same idea leads to the violation of IC1.

# Impossibility result

Using oral messages, **no solution to the Byzantine Generals problem exists** with  **$3m$**  or fewer generals and  **$m$**  traitors ( $m > 0$ ).

*The proof is by contradiction.* Assume that such a solution exists. Now, divide the  $3m$  generals into three groups of  $m$  generals each, such that all the traitors belong to one group. Let one general simulate each of these three groups. This scenario is equivalent to the case of **three generals and one traitor**. We already know that such a solution does not exist.

**Note.** In the original paper, Lamport asks readers to be always suspicious about such an informal reasoning.

# The OM(m) algorithm

## Recursive algorithm

OM(m)



OM(m-1)

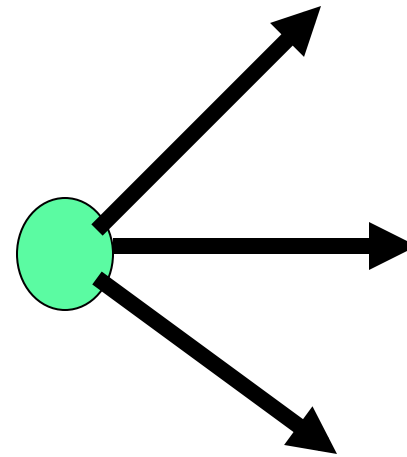


OM(m-2)



OM(0)

OM(0)

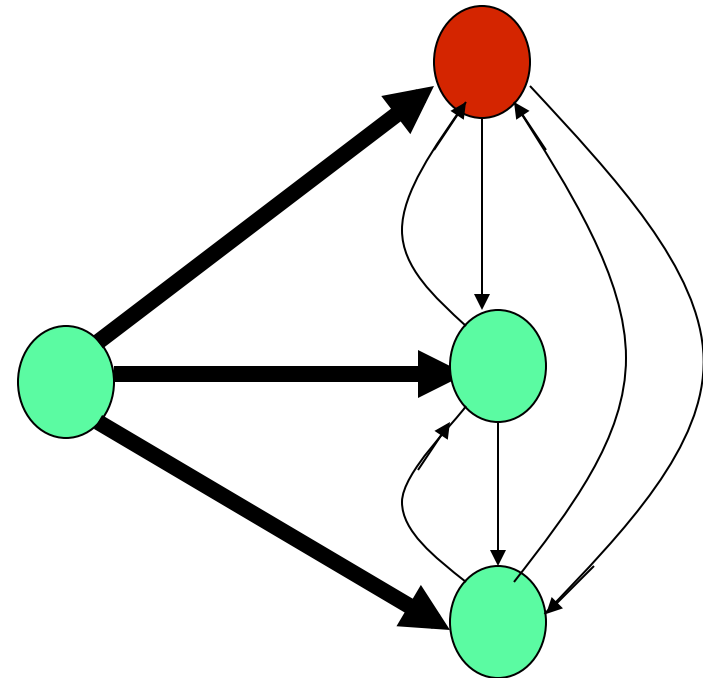


**OM(0) = Direct broadcast**

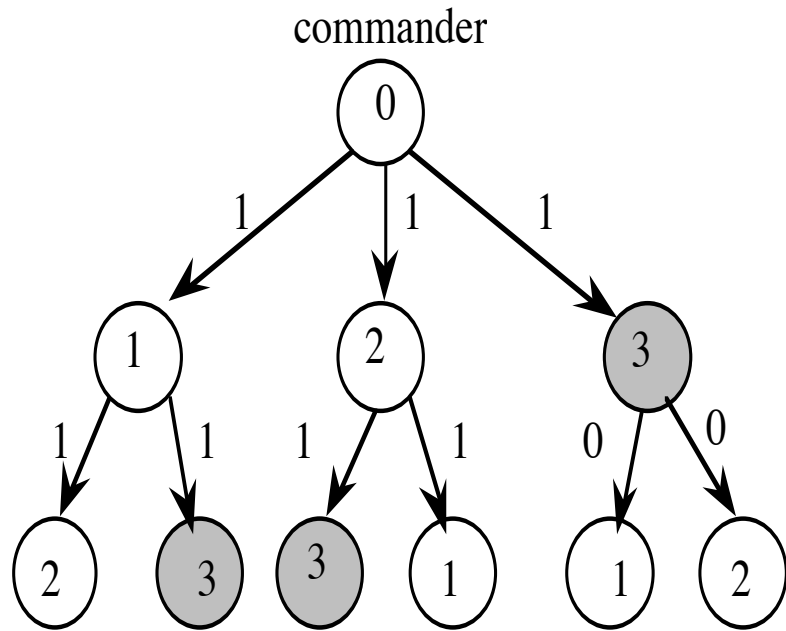


# The OM(m) algorithm

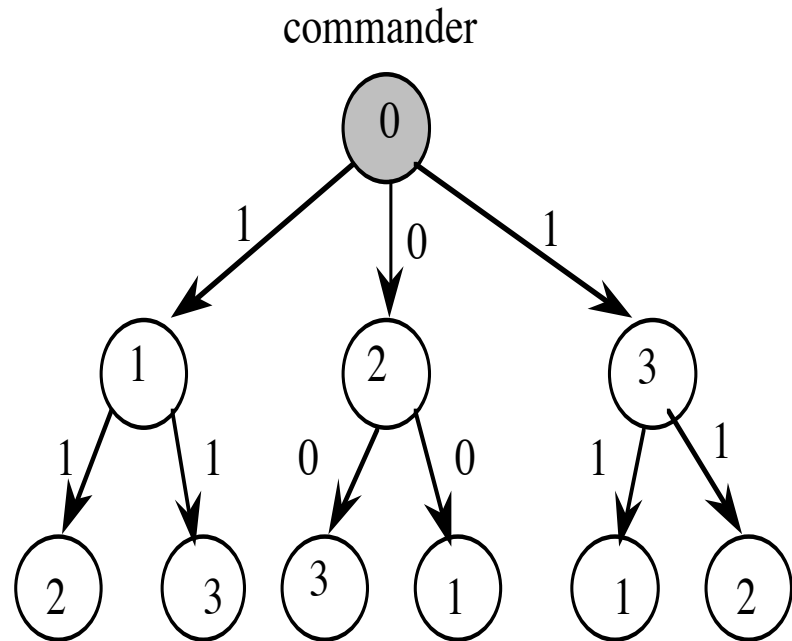
1. **Commander i** sends out a value  $v$  (0 or 1)
2. If  $m > 0$ , then **every lieutenant  $j \neq i$** , after receiving  $v$ , acts as a commander and initiates **OM(m-1)** with everyone except  $i$ .
3. Every lieutenant, collects **(n-1)** values: (n-2) values received from the lieutenants using **OM(m-1)**, and one direct value from the commander. Then he picks **the majority of** these values as the **order** from  $i$



# Example of OM(1)

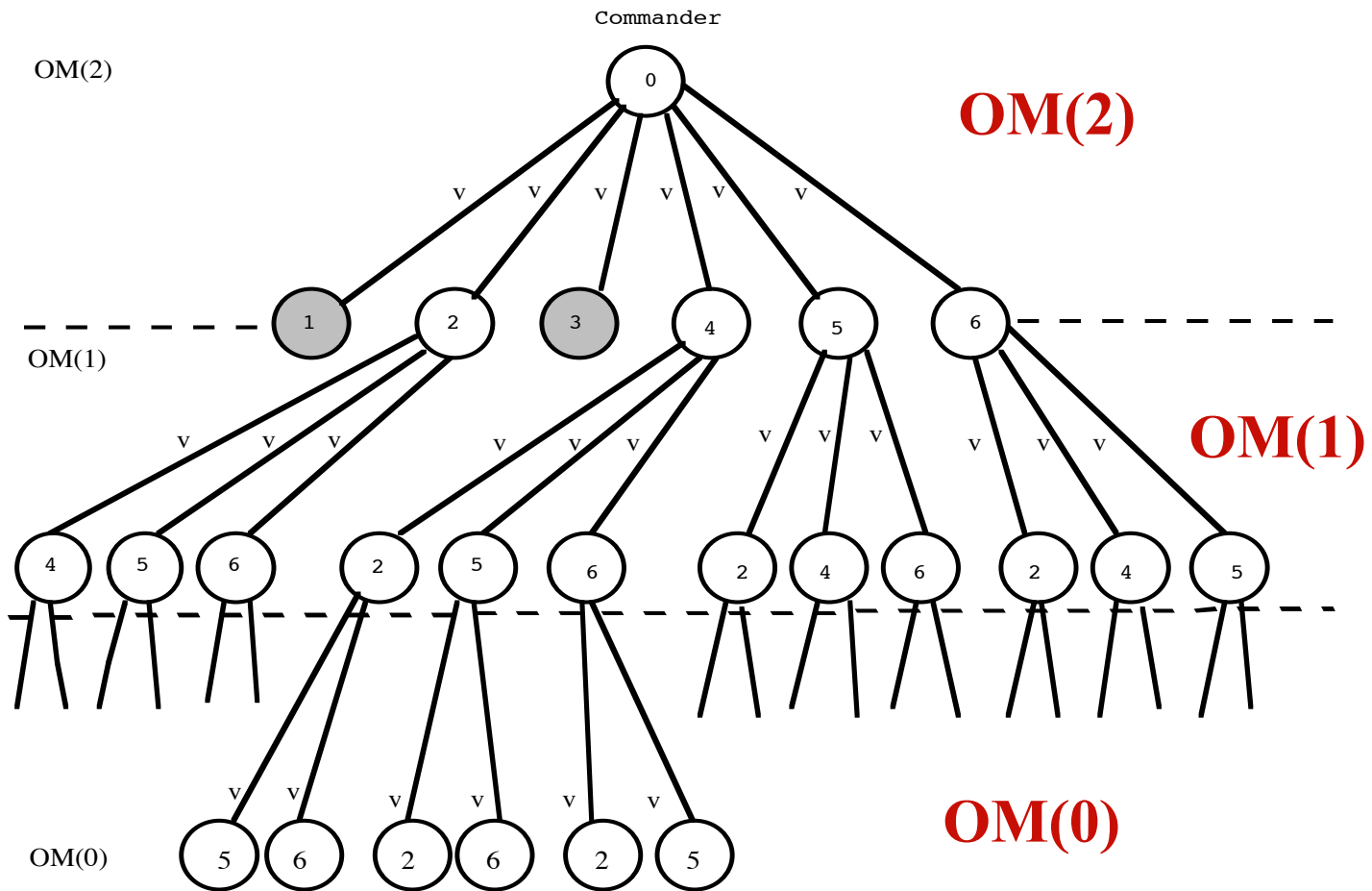


(a)



(b)

# Example of OM(2)

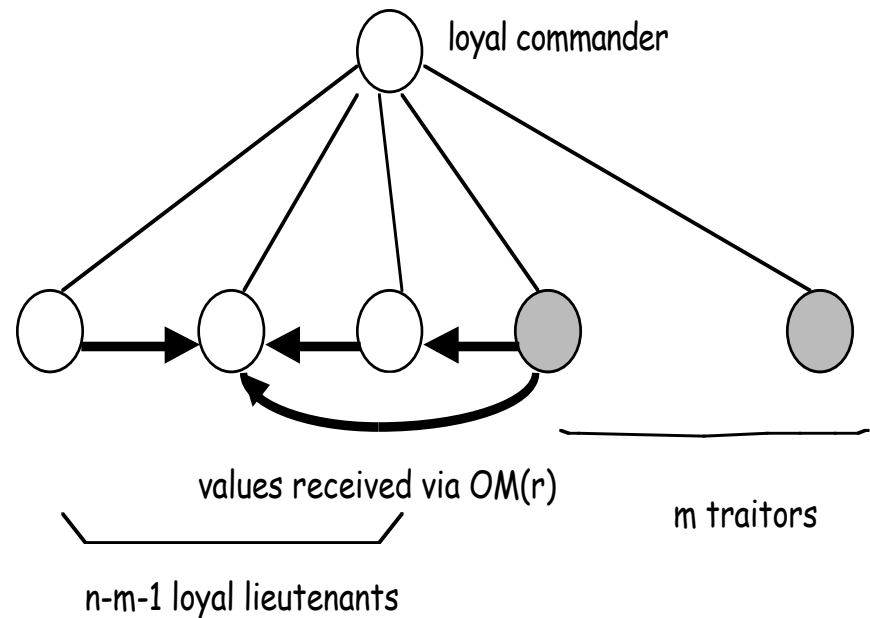


# Proof of OM(m)

## Lemma.

Let the **commander** be **loyal**, and  $n > 2m + k$ , where  $m =$  maximum number of traitors.

Then **OM(k)** satisfies **IC2**



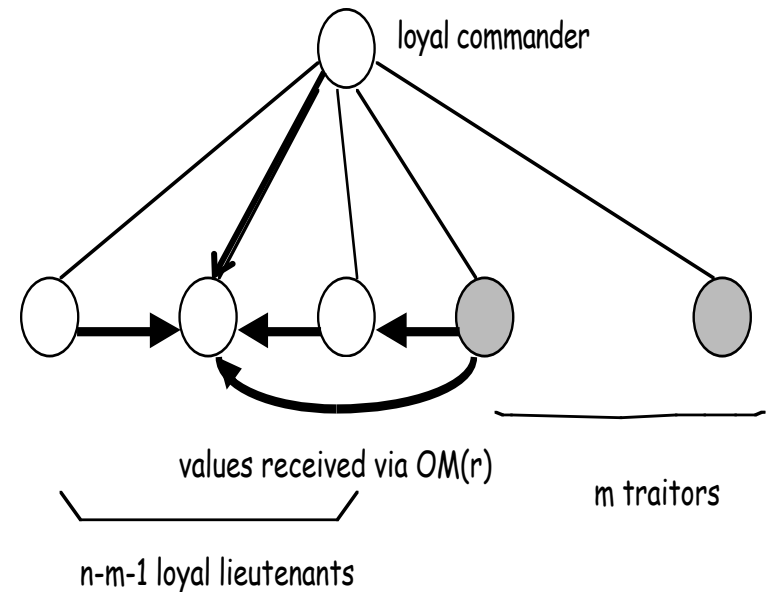
# Proof of OM(m)

## Proof

If  $k=0$ , then the result trivially holds.

Let it hold for  $k = r$  ( $r > 0$ ) **i.e. OM(r) satisfies IC2**. We have to show that it holds for  $k = r + 1$  too.

By definition  $n > 2m + r + 1$ , so  $n - 1 > 2m + r$   
**So OM(r) holds for the lieutenants in the bottom row.** Each loyal lieutenant collects  $n - m - 1$  identical good values and  $m$  bad values. So bad values are voted out ( $n - m - 1 > m + r$  implies  $n - m - 1 > m$ )



“OM(r) holds” means each loyal lieutenant receives identical values from every loyal commander

# The final theorem

**Theorem.** If  $n > 3m$  where  $m$  is the maximum number of traitors, then **OM(m)** satisfies both **IC1** and **IC2**.

**Proof.** Consider two cases:

**Case 1.** Commander is loyal. The theorem follows from the previous lemma (substitute  $k = m$ ).

**Case 2.** Commander is a traitor. We prove it by induction.

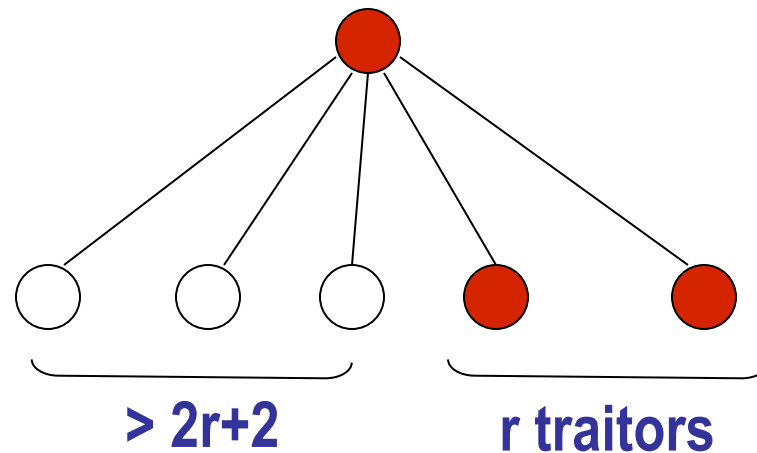
*Base case.*  $m=0$  trivial.

*(Induction hypothesis)* Let the theorem hold for  $m = r$ .

We have to show that it holds for  $m = r+1$  too.

# Proof (continued)

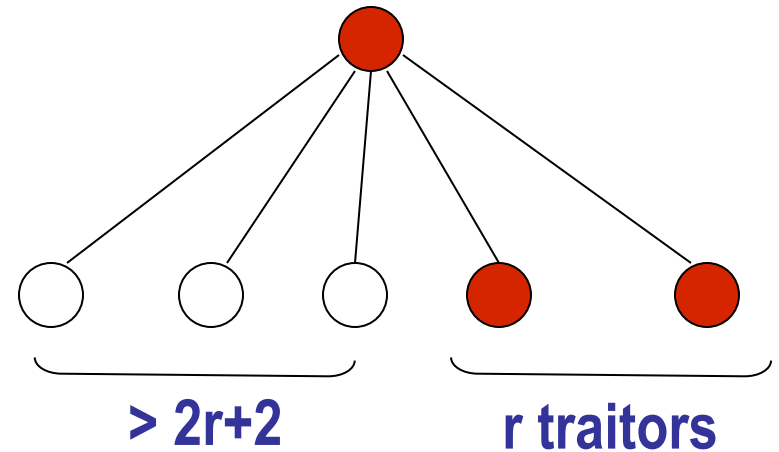
There are  $n > 3(r + 1)$  generals and  $r + 1$  traitors. Excluding the commander, there are  $> 3r+2$  generals of which there are  $r$  traitors. So  $> 2r+2$  lieutenants are loyal. Since  $3r+ 2 > 3.r$ , OM( $r$ ) satisfies IC1 and IC2



# Proof (continued)

In  $OM(r+1)$ , a loyal lieutenant chooses the majority from

- (1)  $> 2r+1$  values obtained from the loyal lieutenants via  $OM(r)$ ,
- (2) the  $r$  values from the traitors, and
- (3) the value directly from the commander.



The set of values collected in part (1) & (3) are the same for all loyal lieutenants – it is the same set of values that these lieutenants received from the commander.

Also, by the induction hypothesis, in part (2) each loyal lieutenant receives identical values from each traitor. So every loyal lieutenant eventually collects the same set of values.